



# ET-6000 series

**User's Manual** 

Version: 1.1, 2007, Sep

### Warranty

All products manufactured by ICPDAS are under warranty regarding defective materials for a period of one year, starting from the date of delivery to the original purchaser.

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# **Manual Revisions**

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1.0	2007-02-27	All	Original Issue
1.1	2007-09-01	Page 54~63 Page 148~157	Update the description of MiniOS7 utility
		Page 118	I/O Pair connection

# **Table of Contents**

1. INTRODUCTION	7
1.1 Features	9
1.2 Specifications	12
1.3 MODULE SELECTION	13
1.4 VIEW OF THE ET-6000	24
1.4.1 Front Panel Description	24
1.4.2 SMMI	30
1.4.3 Left Panel Description	34
1.4.4 Right Panel Description	35
1.5 ET-6000 INSTALLATION	36
1.5.1 Mounting the ET-6000	36
1.5.2 Connecting the Hardware	39
Ethernet cable wiring	41
1.6 I/O WIRING CONNECTION	43
1.7 PORTABLE CONFIGURATION	46
1.8 SOFTWARE & DOCUMENT INFORMATION	48
1.9 UPDATE INFORMATION	49
2. CONFIGURING THE ET-6000	50
	50
·	51
	57
	60
2.2.1 Accessing the SMMI menu for Network Co	
	onfiguration60
2.2.2 The SMMI menu tree	60
<ul><li>2.2.2 The SMMI menu tree</li><li>2.2.3 Set the address values</li></ul>	
2.2.2 The SMMI menu tree	

	3.2	2.4 Module I/O settings	89
	3.3	AUTHENTICATION	93
	3	3.1 Account management	93
	3	3.2 IP filter Settings	94
	3.4	Web HMI	96
	3.4	4.1 Web Editing	96
	3.4	4.2 Web HMI	101
	3.5	I/O PAIR CONNECTION	115
	3.6	More Information	117
4.	Н	OW TO ACCESS ET-6000?	118
	4.1	Via an Ethernet Network	118
	4.2	USING THE MODBUS PROTOCOL	119
	4.2	2.1 Introduction	119
	4.	2.2 Function Codes Supported	120
	4.2	2.3 Modbus Register address table	120
5.	I/0	O PAIR CONNECTION	121
6.	St	OFTWARE DEVELOPMENT APPLICATION	122
٠.			
	6.1	LOCATION OF DOCUMENTS AND SOFTWARE	
	6.2	LabVIEW	124
7.	0	PC SERVER	125
	7.1	Introduction	125
	7.2	PROCEDURE FOR USING THE OPC SERVER	126
	7.3	OPC SERVER EXAMPLE USING MODBUS PROTOCOL	126
8.	SO	CADA	131
	8.1	Indusoft	132
	8.2	CITECT	133
	8.3	ıFıx	134
9.	C	ONSOLE MODE	135
1(	).	TROUBLESHOOTING AND TECHNICAL SUPPORT	140
		IDIX A: DIMENSIONS	
<b>A</b> ]	PPEN	DIX B: MINIOS7 UTILITY	146
Al	PPEN	DIX C: MODBUS PROTOCOL	156

APPENDIX D: MODBUS REGISTER TABLES	160
APPENDIX E: MODBUS APPLICATION NOTES	173
APPENDIX F: JAVA INSTALLATION	180
APPENDIX G: FRAME GROUND	185
APPENDIX H: TECHNICAL SUPPORT	186

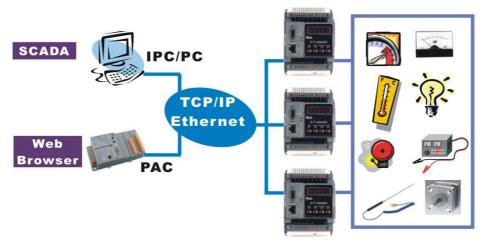
# **TABLES**

Table 1-1	ET-6000 classification	13
Table 1-2	RJ45 LED.	26
Table 1-3	J2 Connector	26
Table 1-4	J3 Connector	29
Table 1-5	Four LED Indicators	33
Table 1-6	RJ-45 Wiring Standards	42
Table 3-1	TCP/IP network settings	75
Table 3-2	Serial Port Settings	78
Table 3-3	Basic Settings	86
Table 3-4	Load All Setup Default Table	88
Table 3-5	Input or Holding Data Types	99
Table 3-6	Main Web HMI Page - Table1	102
Table 4-1	ET-6000 Modbus Function Code	120
Table 10-1	Troubleshooting	140

## 1. Introduction

The ET-6000 is a web-based Ethernet I/O module. It has a built-in web server that used for all configuration and I/O data monitoring and controlling using a regular web browser dynamically. No extra programming tools or HTML editor are needed. Thus users can easily and safely access the ET-6000 from anywhere at and any time all over the world.

In addition, the ET-6000 also supports various Modbus functions. For example, Modbus/TCP slave, Modbus/TCP to Modbus/RTU gateway, Modbus/RTU master, Modbus/RTU slave, and etc, meaning the ET-6000 can easily be integrated into any SCADA software environment using the Modbus protocol.



The ET-6000 module is designed to be used in industrial monitoring and measurement applications, so the hardware has been manufactured to survive in harsh and noisy environment. As a result, the module contains 3-way isolation against noise and surge signals, has a wild range power input (10~30VDC) and can operating at temperature ranging from -25~+75 C.

## **Package Checklist**

In addition to this manual, the package includes the following items:

- One ET-6000 hardware module
- One Quick Start Manual
- One software utility CD
- One CA0910F download cable
- One screw driver

#### Note:

If any of these items are missing or damaged, contact the local distributors for more information. Save the shipping materials and cartons in case you need to ship the module/product in the future.

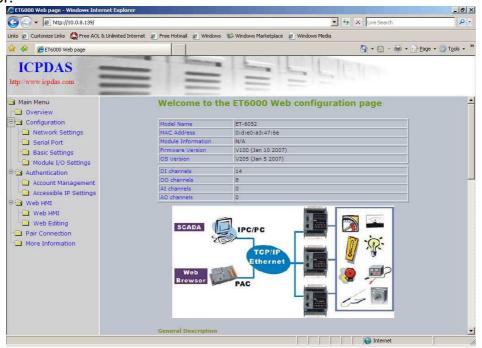
### Release Notes:

It is recommended that the **release notes and README.TXT** file are read before using the controller. The release notes are included in the shipping package and the README.TXT file can be found in the root directory of the enclosed CD. Some important information is provided in the release note and README.TXT file.

### 1.1 Features

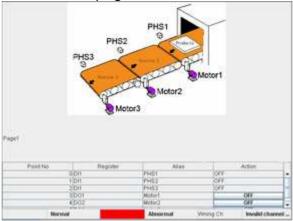
#### **Built-in web server**

Each ET-6000 module has a built-in web server that allows the user to easily configure, monitor and control the module from a remote location using a regular web browser.



### **Web HMI**

The Web HMI function allows the user to create dynamic and attractive web pages to monitor and control the I/O points. The user can upload specific I/O layout pictures (bmp, jpg, gif format) and define a description for each I/O point. No HTML or Java skills are needed to create the web pages.



### **Communication Security**

An Account and password is needed when logging into the ET-6000 web server. An IP address filter is also included, which can be used to allow or deny connections from specific IP addresses.

### **Modbus protocol**

- The Modbus/TCP slave function on the Ethernet port can be used to provide data to remote SCADA software.
- The Modbus/RTU slave function on the RS-232 port can be used to connect to a local HMI.
- The Modbus /TCP to Modbus/RTU gateway function through the Ethernet port to the RS-232 port can be used to upgrade a serial device with Ethernet communication ability.

### **Built-in Multi-function I/O**

All Digital Output modules provide:

- Power on value (On boot up, the DO status is set to the Power-on value)
- Safe value (If Modbus/TCP communication is lost for a specified period, the DO status is set to the safe value)

All Digital Input modules provide:

- High/Low latched status
- DI channels can also be used as DI status and 16-bit low speed (100Hz) counters.

An LED indicator is used for each DI or DO channel.

#### All-in-one module

The various I/O components are mixed with multiple channels in a single module, which provides the most cost effective I/O usage and enhances performance of the I/O operations.

### 3-way isolated noise/surge protection

To protect the hardware from damage caused by noise and surge, the ET-6000 module is designed with isolation circuits for Ethernet, I/O and Power.

### **Portable Configuration**

All configuration settings can be saved to the EEPROM on the ET-6000, which is mounted on a daughter board (called the "portable" board), meaning that the settings can stored and easily backed up and moved.

### **Built-in Dual Watchdog**

The Dual Watchdog consists of the/a Module Watchdog and the/a Host Watchdog.

- The <u>Module Watchdog</u> is a built-in hardware circuit that can be used to monitor the operation of the module and will reset the CPU module if a failure occurs in either the hardware or the software.
- The <u>Host Watchdog</u> is a software function that can be used to monitor the operating status of the host, and is used to prevent network communication problems or host failures.

### **Automatic MDI / MDI-X crossover for plug-and-play**

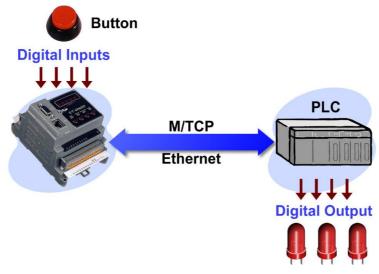
The RJ-45 port support automatic MDI/MDI-x that can automatically detect the type of connection to the Ethernet device without requiring special straight or crossover cables.

### Ventilated housing designed to operate between -25°C ~+75℃

The ET-6000 is housed in a plastic-based shell/case with a column-like ventilator that helps to cool the working environment inside the shell/case and allows the ET-6000 to operate at temperatures ranging from -25℃ and +75° C.

### I/O Pair Connection

This function is used to create a DI to DO pair through the Ethernet. Once the configuration is complete, the ET-6000 module can poll the status of local DI channels and then use the Modbus/TCP protocol to continuously write to a remote DO device in the background.



# 1.2 Specifications

### **System**

• CPU: 80186-80 or compatible

EEPROM: 16KB
 SRAM: 512KB
 FLASH ROM: 512KB

#### Communication

Ethernet Port:

10/100MBaseT, RJ-45 Port

COM Port

COM1: RS232 (RXD, TXD, GND)

**Built-in WatchDog Timer (0.8 seconds)** 

### SMMI (Small Man Machine Interface) (for ET-6000D series only)

• 7-segment LED: 5-digit

4 system LED indicators

• 4 push buttons

#### **LED** indicators

Indication for Digital Output

Indication for Digital Input

Ethernet (Link/Active)

#### Isolation

I/O Isolation: 3000V DC
Power Isolation: 1000V DC
Ethernet Isolation: 1500V DC

#### Power

Power requirements: +10 to +30 V DC (non-regulated)

Power consumption: 3.0W

#### **General environment**

Operating temperature: -25℃ to +75℃
 Storage temperature: -30℃ to +75℃

• Relative humidity: 10%~95% RH, non-condensing

#### Mechanical

- Dimensions (W x H x D): Dependent on the type of ET-6000 module. Please refer to "Appendix A Dimensions" for more detailed information
- Installation: DIN-Rail Mounting

### **I/O Components**

 Dependent on the type of ET-6000 module, please refer to the next chapter for more detailed I/O specifications.

# 1.3 Module Selection

### ET-6000 classification



ET: Ethernet communication interface

U: Number of units

U: '2' denotes 2 units

U: '3' denotes 3 units

U: Blank means 1 unit

X: Number of the variance

Y: Function code

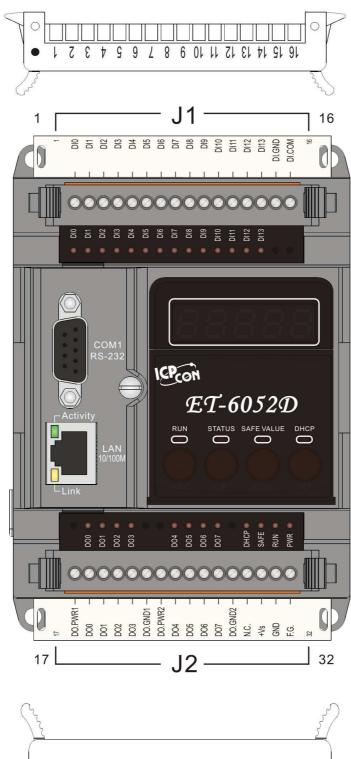
**Z:** Extension function code

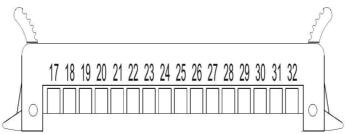
Table 1-1 ET-6000 classification

	Table 1-1 L1-0000 Clas	Silication
X	Y	Z
		<ul><li>3. RTD</li><li>4. Transmitter</li><li>5. Thermistor</li><li>6. Strain Gauge</li><li>7. Analog Input</li><li>8. Thermocouple</li></ul>
Number of variance	2. AO module	Voltage output     Current Output
Number of variance	3. Reserved	
	4. DIO module	Number of variance
	5. DIO module	Number of variance
	6. DIO module with relay	Number of variance
	7. Multi-function	1. General purpose
	8. Counter / Frequency	Number of variance
	9. Motion	N: Number of axes

# ET-6052D

### Layout





## ET-6052 Pin Assignment:

J1	Pin Assignment Name	ent J2 Pin A:	
G = 1 01	D10	[ n 17	DO.PWR1
T =   02	DI1	T = 18	D00
[ D 03	D12	[ n   19	DO1
[ n   04	DI3	20	DO2
_ o 05	DI4	[ n 21	DO3
[ = 06	D15	22	DO.GND1
C = 1 07	D16	23	DO.PWR2
08 m	DI7	[ = 24	DO4
T = 09	D18	[ = 25	DO5
T = 10	D19	26	DO6
C - 11	DI10	[ n 27	D07
T - 12	DI11	28	DO.GND2
[ o 13	DI12	29	N.C.
[ 0   14	DI13	Д н 30	+Vs
[ n 15	DI.GND	□ □ 31	GND
C - 16	DI.COM	32	F.G.

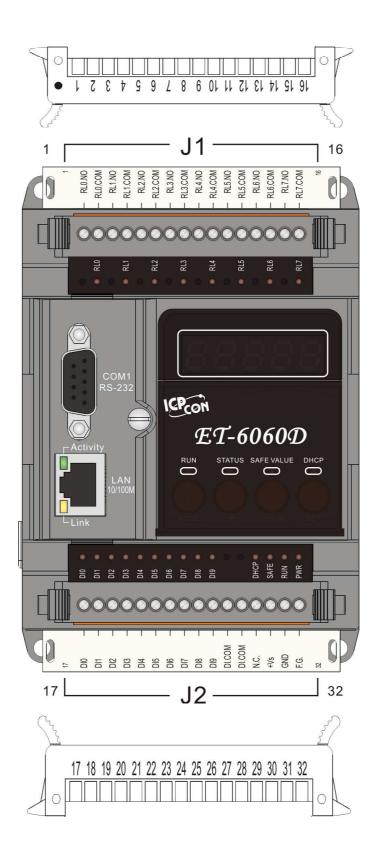
# **Chapter 1** Introduction

# ET6052 (D) I/O Specifications:

Digital Output		
Output Channels	8 (Source)	
LED Indicator	Yes	
Output Type	Isolated (N-MOSFET, Open Source)	
Max Load Current	1.4A/ channel	
Load Operating Voltage	10Vdc to 40Vdc	
External Power Voltage Range	12Vdc to 45Vdc	
Over-Voltage Protection	+48 VDC	
Direct Drive Power Relay Module	Yes	
Short Circuit Protection and Current Limitation	Yes	
Switching Inductive Loads	Yes	
Intra-module Isolation, Field to Logic	3750V rms	
Digital Input		
Input Channels	14 (Sink/Source)	
LED Indicator	Yes	
Input Type	Isolation, One Common/Ground for All Digital Inputs	
Input Impedance	10K Ohms, 0.5W (For Wet Contact)	
Dry Contact (Source)	On Voltage Level: Close to GND	
	Off Voltage Level: Open	
Wet Contact (Sink/Source)	On Voltage Level: +10 to 50Vdc	
	Off Voltage Level: +3V (Max.)	
Each Channel Can Be To Dry Contact or Wet Contact	Yes	
	Channels: 14	
Counters	Max. Input Frequency: 100Hz	
	Min. Pulse Width: 5ms	
Intra-module Isolation, Field to Logic	3750V rms	

## ET-6060D

## Layout



# ET-6060 Pin Assignment:

J1		Pin Assignment Name	t J2 Pin Assig Nam	
7 0 (	01	RL0.NO	C 0 1	7 DI0
C =	02	RL0.COM	G - 1	8 DI1
20	03	RL1.NO	[ o 1	9 DI2
201	04	RL1.COM	[ 0 2	0 DI3
7 0	05	RL2.NO	[ a 2	1 DI4
7 0	06	RL2.COM	[ = 1 2	2 DI5
7 0	07	RL3.NO	2	3 DI6
La a	08	RL3.COM	[ D 2	4 DI7
[n = (	09	RL4.NO	C = 2	5 DI8
C o	10	RL4.COM	2 0 2	6 DI9
[ n	11	RL5.NO	[ D 2	7 DI.COM
20	12	RL5.COM	[ 0 2	8 DI.COM
2 0	13	RL6.NO	[ D 2	9 N.C.
	14	RL6.COM	J = 3	0 +Vs
C a	15	RL7.NO	G = 3	1 GND
	16	RL7.COM	3	2 F.G.

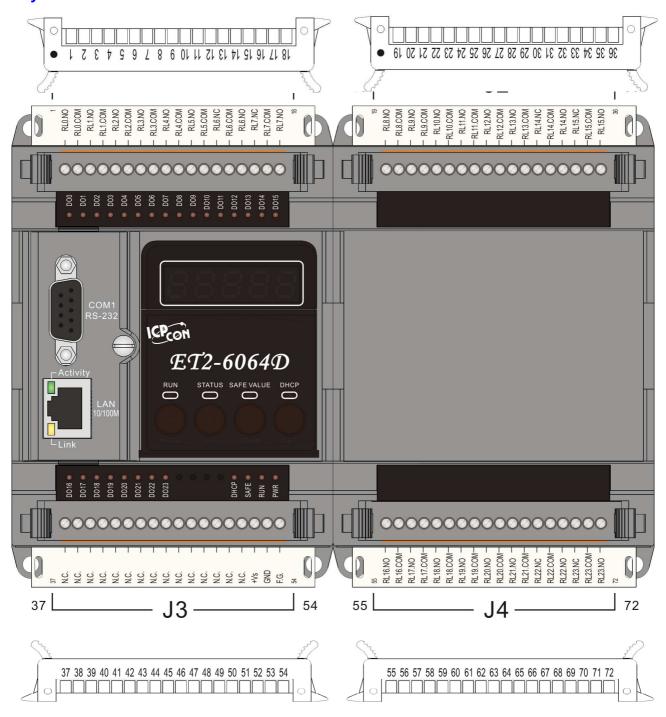
# **Chapter 1** Introduction

# ET6060 (D) I/O Specifications:

Digital Output	
Output Channels	8
LED Indicator	Yes
Output Type	Power Relay, Form A (Normal Open)
On anating Walter as Dange	5 ~ 240VAC (47~63Hz)
Operating Voltage Range	5 ~ 24VDC
Balay Cantagt Valtage Bange	0~ 250VAC (47~63Hz)
Relay Contact Voltage Range	0~ 28VDC
Max. Load Current	3.0 A/Channel
Max. Operate Time	15 milliseconds Max.
Max. Release Time	3 milliseconds Max.
Insulation Resistance	Min. 1,000 MOhms, at 500VDC
	Between Open Contacts: 750VAC 50/60Hz (at 1 Minute)
Dielectric Strength	Between Coil and Contacts: 4,000VAC 50/60Hz (at 1
	Minute)
Surge Strength	10,000V (at 1.2*50us)
Polov Life	Mechanical: 10 million operations at no Load Condition
Relay Life	Electrical: 100, 000, 28VDC@5A min., Resistive
Digital Input	
Input Channels	10 (Sink/ source)
LED Indicator	Yes
Input Type	Isolation, Two Common for All Digital Inputs
On Voltage Level	+10V ~ 50V
Off Voltage Level	+3V max
Input Impedance	10K Ohms, 0.66W
	Channels: 10
Counters	Max. Input Frequency: 100Hz
	Min. Pulse Width: 5ms
Intra-module Isolation, Field to	3750V rms
Logic	

### ET2-6064 (D)

### Layout



# ET2-6064(D) Pin Assignment:

J1		Pin Assignment Name	J2		Pin Assignment Name
	01	RL0.NO	5	19	RL8.NO
	02	RL0.COM	7	20	RL8.COM
[1]	03	RL1.NO	7	21	RL9.NO
	04	RL1.COM	7	22	RL9.COM
[J	05	RL2.NO	7 0 (	23	RL10.NO
	06	RL2.COM	7	24	RL10.COM
7	07	RL3.NO	7	25	RL11.NO
	80	RL3.COM	7	26	RL11.COM
	09	RL4.NO	7	27	RL12.NO
	10	RL4.COM	70	28	RL12.COM
	11	RL5.NO	7	29	RL13.NO
	12	RL5.COM	7 0	30	RL13.COM
	13	RL6.NC	7	31	RL14.NC.
	14	RL6.COM	7	32	RL14.COM
	15	RL6.NO		33	RL14.NO
	16	RL7.NC		34	RL15.NC
	17	RL7.COM		35	RL15.COM
	18	RL7.NO		36	RL15.NO

# **Chapter 1** Introduction

J3	Pin Assignment Name	J4		Pin Assignment Name
37	N.C.		55	RL16.NO
38	N.C.	\[ \frac{1}{2} \]	56	RL16.COM
39	N.C.	\[ \frac{1}{2} \]	57	RL17.NO
40	N.C.		58	RL17.COM
<u>_</u> 41	N.C.		59	RL18.NO
42	N.C.	\[ \frac{1}{2} \]	60	RL18.COM
43	N.C.	\[ \]	61	RL19.NO
<b>L</b> - 44	N.C.		62	RL19.COM
45	N.C.		63	RL20.NO
46	N.C.		64	RL20.COM
<u>_</u> 47	N.C.		65	RL21.NO
<u></u>	N.C.	\[ \frac{1}{2} \]	66	RL21.COM
49	N.C.	\[ \frac{1}{2} \]	67	RL22.NC
50	N.C.		68	RL22.COM
51	N.C.		69	RL22.NO
52	+Vs		70	RL23.NC
53	GND		71	RL23.COM
54	F.G.		72	RL23.NO

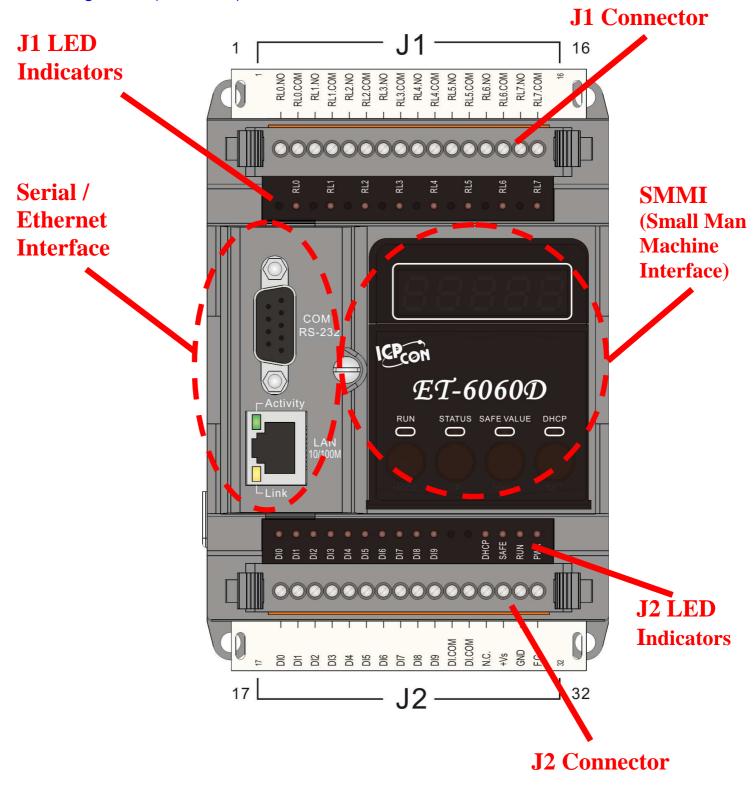
# ET2-6064 (D) I/O Specifications:

Digital Output			
Output Channels	18		
LED Indicator	Yes		
Output Type	Power Relay, Form A (Normal Open)		
On anoting Weller as Decree	5 ~ 240VAC (47~63Hz)		
Operating Voltage Range	5 ~ 24VDC		
Dalas Cantact Valtara Danas	0~ 250VAC (47~63Hz)		
Relay Contact Voltage Range	0~ 28VDC		
Max. Load Current	3.0 A/Channel		
Max. Operate Time	15 milliseconds Max.		
Max. Release Time	3 milliseconds Max.		
Insulation Resistance	Min. 1,000 MOhms, at 500VDC		
	Between Open Contacts: 750VAC 50/60Hz (at 1 Minute)		
Dielectric Strength	Between Coil and Contacts: 4,000VAC 50/60Hz (at 1		
	Minute)		
Surge Strength	10,000V (at 1.2*50us)		
Dalam I Ka	Mechanical: 10 million operations at no Load Condition		
Relay Life	Electrical: 100, 000, 28VDC@5A min. , Resistive		
Output Channels	6		
LED Indicator	Yes		
Output Type Power Relay, Form C (Normal Open and Close)			
On anotic a Valla na Danas	5 ~ 240VAC (47~63Hz)		
Operating Voltage Range	5 ~ 24VDC		
	0~ 250VAC (47~63Hz)		
Relay Contact Voltage Range	0~ 30VDC		
Max. Load Current	2.0 A/Channel		
Max. Operate Time	5 milliseconds Max.		
Max. Release Time	5 milliseconds Max.		
Insulation Resistance	Min. 1,000 MOhms, at 500VDC		
Diala atria Otrono	Between Open Contacts: 1,000Vrms (at 1 Minute)		
Dielectric Strength	Between Coil and Contacts: 1,500Vrms (at 1 Minute)		
Surge Strength	2,500V (at 1.2*50us)		
Dolov Life	Mechanical: 100 million operations at no Load Condition		
Relay Life	Electrical: 100, 000, 30VDC@2A min. Resistive		

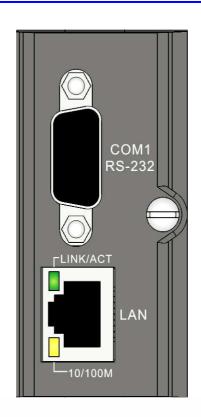
### 1.4 View of the ET-6000

# 1.4.1 Front Panel Description

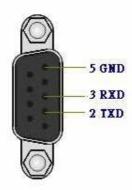
Single Unit (ET-6XXX)



### **Serial/Ethernet Interface**



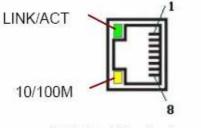
### RS-232 Port



Female 9-Pin D-Sub (DTE)

Pin	Description	
1	N/A	
2	TX (Transmit Data)	
3	RX (Receive Data)	
4	N/A	
5	GND (Signal Ground)	
6	N/A	
7	N/A	
8	N/A	
9	N/A	

### Ethernet Port



- 11				
D 1/1	h Da	+ Din	Accia	nmanta
C.14			A >>101	nments
1.40	0 , 0,		10010	111101110

Pin	Description	
1	TX+	
2	TX-	
3	RX+	
4	<no connection=""></no>	
5	<no connection=""></no>	
6	RX-	
7	<no connection=""></no>	
8	<no connection=""></no>	

<b>Tab</b>	le 1	1-2	R.	45	LED
IUN		-	110	TU	

Name	LED Action	Function
LINK/ACT	ON	Ethernet link detected
	OFF	No Ethernet link detected
	Flashing Green	Ethernet packet received
10/100M	OFF	Speed 10 Mbps
	Orange	Speed 100 Mbps

#### J1 Connector

Refer to **Sec.1.3 Module Selection** for more details regarding the pin assignment of the J1 Connector for all types of single unit ET-6000 series modules.

### J1 LED Indicators

Refer to **Sec.1.3 Module Selection** for more details regarding the J1 LED Indicators for all types of single unit ET-6000 series modules.

#### J2 Connector

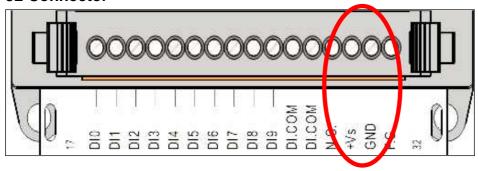


Table 1-3 J2 Connector

14510 1 0 02 00111100101				
Pin number	Name	Function		
30	+VS	The ET-6000 series can be powered using a 10-30V DC supply		
31	GND	Ground connection		
32	F.G.	Frame Ground		

The definition of the 3 pins above is applicable to all types of the single unit ET-6000 series modules (Single unit). The definition of the other pins is dependent on the different type of ET-6000 series module.



**Appendix G** describes how to connect the Frame Ground to the ET-6000 series module.

### **J2 LED Indicators**

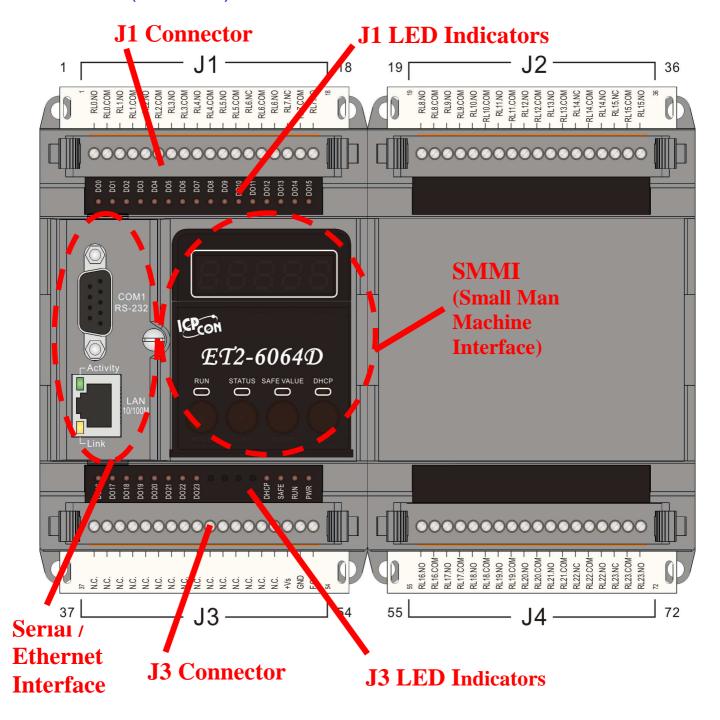


The 4 LED Indicators at the far right is applicable for all types of single unit ET-6000 series modules.

Name	LED Action	Function
PWR	ON/OFF	Power ON/ Power OFF
RUN	Flashing	Firmware is running
SAFE	ON/OFF	Safe value triggered/Un-triggered
DHCP	ON/OFF	DHCP enabled/ DHCP disabled

All other LED indicators are dependent on the different type of single unit ET-6000 series module.

### Two Units (ET2-6XXX)



#### Serial/Ethernet Interface

The definition of the two interfaces is same as for a single unit ET-6000 series module.

#### J1 Connector

Refer to **Sec.1.3 Module Selection** for more details regarding the pin assignment of the J1 Connector for all types of two- unit ET-6000 series modules.

#### J1 LED Indicators

Refer to **Sec.1.3 Module Selection** for more details regarding the J1 LED Indicators for all types of two-unit ET-6000 series modules.

### J3 Connector (Two Units)

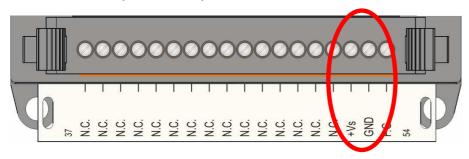


Table 1-4 J3 Connector

Pin number	Name	Function
52	+VS	The ET-6000 series can be powered using a 10-30V DC supply
53	GND	Ground connection
54	F.G.	Frame Ground

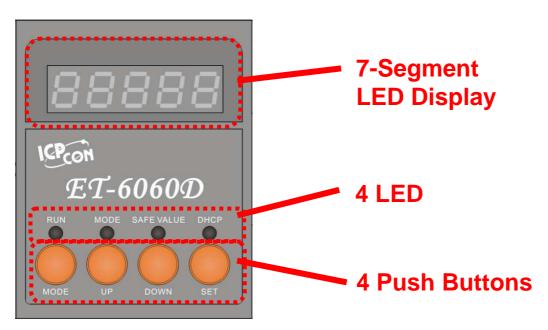
The definition of the 3 pins above is applicable to all types of the two units ET-6000 series modules (Two units). The definition of the other pins is dependent on the different types of the two units ET-6000 series module.

J3 LED Indicators



The definition of 4 LED Indicators at the far right is same as for a single unit ET-6000 series module. All other LED indicators are dependent on the different type of two-unit ET-6000 series modules.

### 1.4.2 SMMI



All types of ET-6000D series module have the same SMMI format (7-Segment LED Display, 4 LED Indicators and 4 Push Buttons).

### 7-Segment LED Display

This display is consists of five 7-Segment LEDs. The most important information related to the ET-6000D series can be classified as follows:

Group-ID 11111: Indicates the IP information and DHCP status of the ET-6000D module.

Group-IP 22222: Indicates the Baud Rate of the ET-6000D module COM port.

Group-IP **33333**: Indicates the Data format and operation mode of the ET-6000D module COM port

Group-IP 44444: Indicates the number of clients connected to the ET-6000D module.

1. The format of the IP-information is as follows:

5-digit LED Group-ID:111111

LED-1: Indicator, which can be either 1,2,3,4, or 5

LED-2~LED-5: the IP address, which can be 0~9.

A "1." shown on LED-1 denotes the first number of the IP address.

A "2." shown on LED-1 denotes the second number of the IP address.

A "3." shown on LED-1 denotes the third number of the IP address.

A "4." shown on LED-1 denotes the fourth number of the IP address.

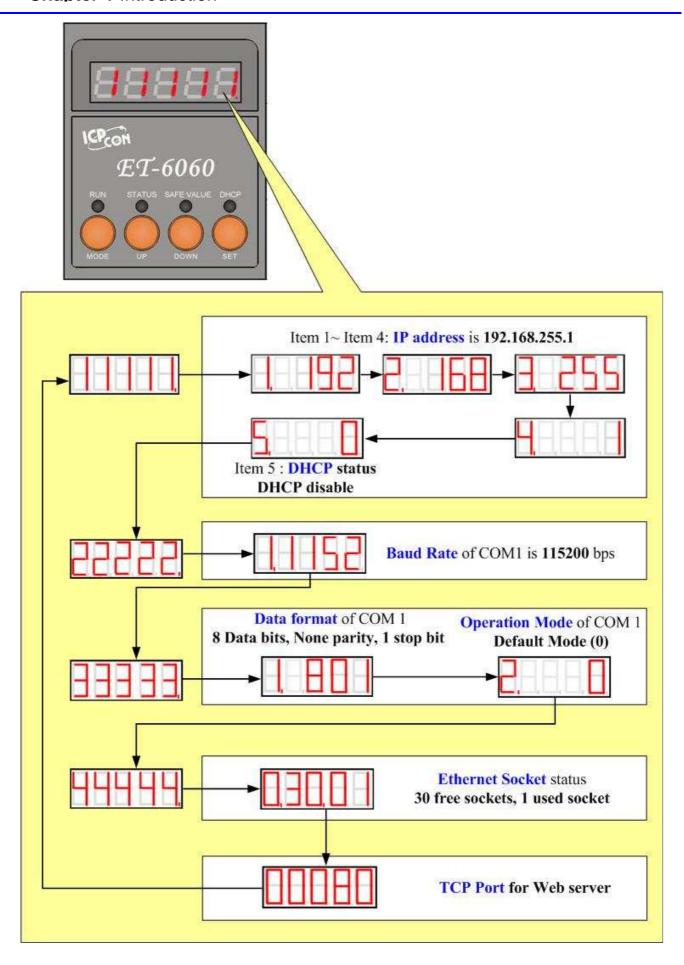
A "5." shown on LED-1 denotes the DHCP status.

Eg. "5.\_\_\_0", 0 (Disabled) and "5.\_\_\_\_1", 1(Enabled)

The LED will initially show the Group-ID, and then show the IP address as indicated in the diagram below. If the IP address is changed, the value displayed will change immediately.

The default shipping IP = 192.168.255.1.

The LED-display sequence is shown in the diagram below.





#### Note:

Only the display version modules (**ET-6000D** series) include a 5-digit 7-segment LED. The **ET-6000** series is the non-display version.

2. The format of COM Port Baud Rate is as follows:

5-digit LED Group-ID:22222

LED-1: COM Port number

**LED-2~LED-5**: Displays the Baud Rate and is determined as (Baud Rate/100) Therefore, a displayed value of 1.1152 means that the Baud Rate of COM1= 115200 bps.

3. The format of the COM port is Data as follows:

5-digit LED Group-ID:33333

**LED-1**: COM port number

**LED-3**: Data bit: 5, 6, 7 or 8

**LED-4**: Parity bit, 0=No parity, 1=Odd parity, 2=Even parity

**LED-5**: Stop bit, 1 or 2

The default operation mode of the COM port is 5 (Console mode)

Refer to **Appendix C** for more details regarding the operation modes of the COM port.

4. The format of the Ethernet socket information is as follows:

5-digit LED Group-ID:44444

**LED-1**: Indicator, which is 0.

**LED-2~LED-3**: The number of free sockets available. (Default is 30 for the ET-6000)

**LED-4~LED-5**: The number of sockets currently being used by clients. (Default is 0) If a client connects to the ET-6000, the number of free-sockets will be decreased and the number of used-sockets will be increased. If the number of free-sockets is reduced to 0, then no extra clients can connect to the ET-6000. The default number of free-socket for the ET-6000 is 30. Therefore, the server allows up to 30 clients to connect to a single ET-6000.

The TCP port for the Web server is a well-known port used for TCP/IP communication, and the default is 80.



#### Note:

If the 5-digit LED does not display the information as above, the following steps should be taken:

- Switch the Power off
- Check that the Init/Normal switch is in the Normal position. (Refer to **Sec 1.4.3** Left Panel Description)
- Switch the Power on and double check the displayed data.

### **Four LED Indicators**

### Table 1-5 Four LED Indicators

Name	LED Action	Function
RUN	Flashing	Firmware is running
MODE	ON/OFF	SMMI mode/Normal mode
SAFE VALUE	ON/OFF	Safe value triggered / Un-triggered
DHCP	ON/OFF	DHCP enabled/ DHCP disabled

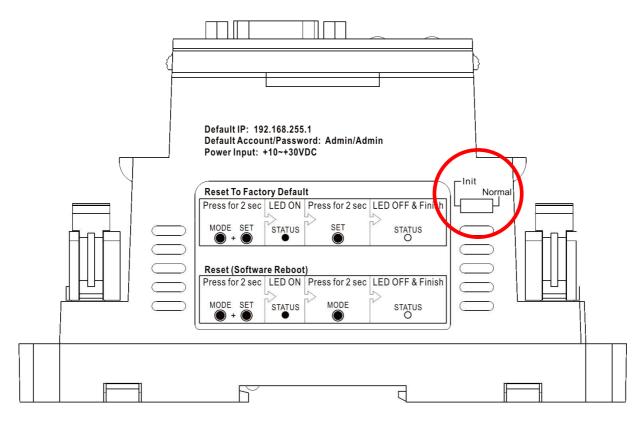
### **Four Push Buttons**



Refer to **Section 2.2** for more details regarding how use four SMMI Menu buttons to set Network configuration. Refer to **Section 2.3.2** for more information about setting the factory defaults for the ET-6000.

You must left the acrylic cover of the ET-6000 before pressing the 4 push buttons.

# 1.4.3 Left Panel Description



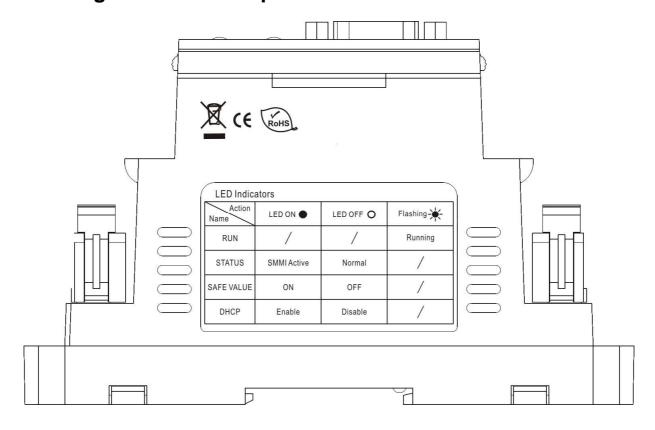
### Init/Normal switch

**Init** mode: MiniOS7 configuration mode **Normal** mode: Firmware running mode

In the ET-6000 series, the Switch is ALWAYS in the Normal position. Only when updating the ET-6000 firmware or OS, the switch can be moved from the Normal position to the Init position.

Move the Switch to the Normal position after the update is complete.

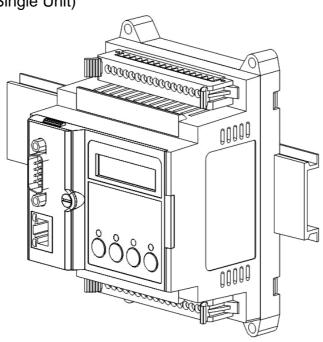
# 1.4.4 Right Panel Description



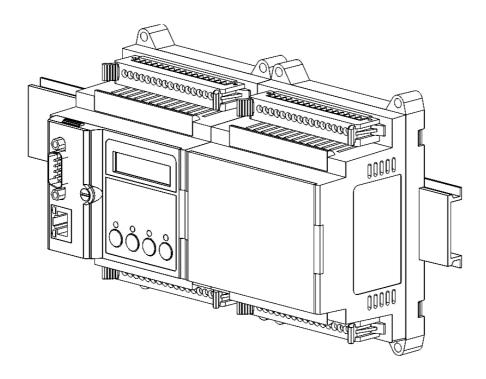
# 1.5 ET-6000 installation

# **1.5.1** Mounting the ET-6000

Din-Rail Mounting (Single Unit)

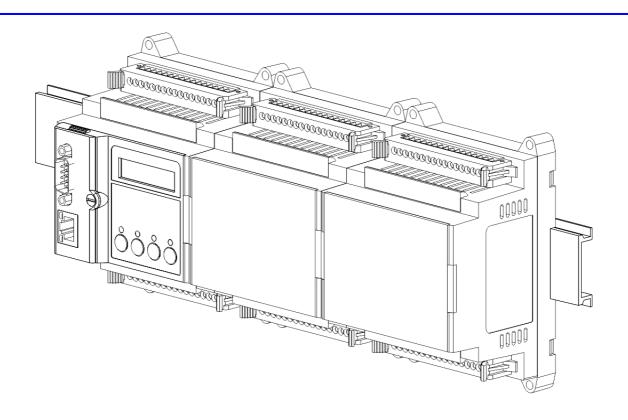


Din-Rail Mounting (Two Units)



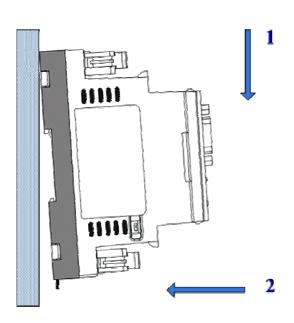
Din-Rail Mounting (Three Units)

# Chapter 1 Introduction

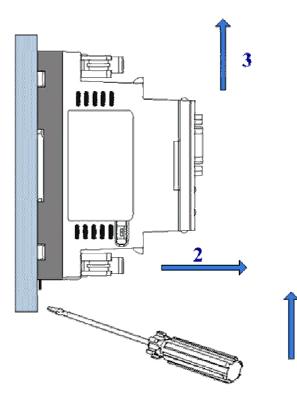


- Snap the ET-6000 onto the DIN-rail (refer to the Snap On picture below)
  - Snap the ET-6000 off from the DIN-rail (refer to the Snap Off picture below)

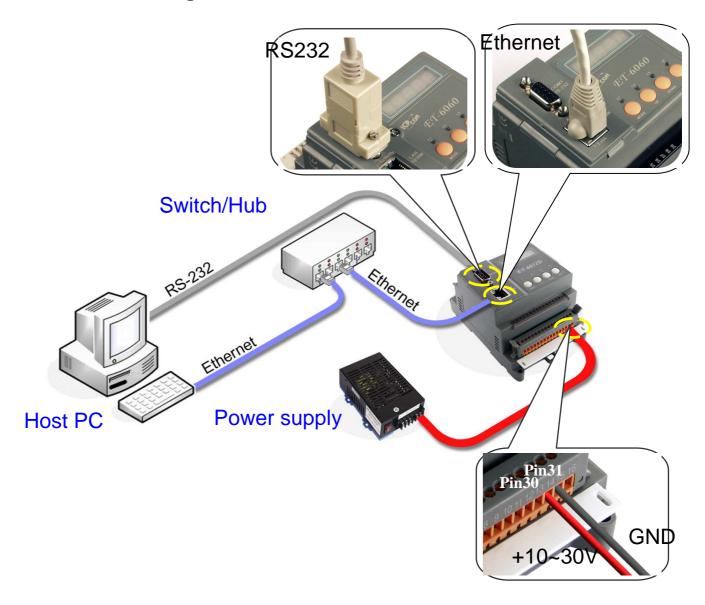
## **Snap On**



## **Snap Off**



## 1.5.2 Connecting the Hardware



Step 1: Connect the RS-232 download-cable (CA0910F) between the ET-6000 and COM Port the Host PC, as shown in the diagram above

Step 2: Apply the power (+Vs, GND) to the ET-6000. +Vs can be in a range from +10 to +30V DC.



#### **Notes:**

- In single unit ET-6000 series modules, V+ is connected to **Pin 30** of the J2 connector, and GND is connected to **Pin 31** of the J2 connector.
- In a two-unit, V+ is connected to **Pin 52** of the J3 connector, and GND is connected to **Pin 53** of the J3 connector.
- Refer to **Sec. 1.4.1 Front Panel Description** for more details regarding pin assignments.

## **Chapter 1** Introduction

- Step 3: Check that the 5-digit 7-SEG LED continuously shows the group ID information from 11111 to 44444. (If the Module is an ET-6000 series module without a 7-SEG LED Display, ignore this step)
- Step 4: Check that the "RUN" LED on the ET-6000 is periodically ON for 0.5 seconds and then OFF for 0.5 seconds.

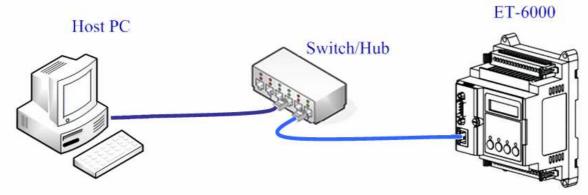


#### Note:

Only display versions of the module will include a 5-digit 7-SEG LED Display. A detailed description of the 7-SEG LED Display can be found in **Sec. 1.4.2**.

## **Ethernet cable wiring**

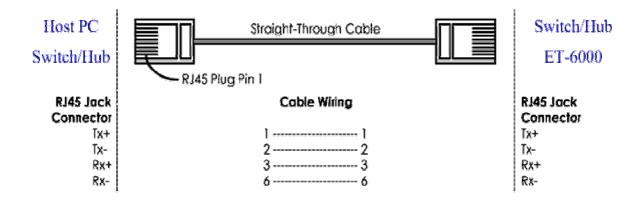
### Connecting the ET-6000 to Switch or Hub



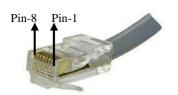
### Connecting the ET-6000 to a Host PC



As a result of the automatic MDI / MDI-X crossover for plug-and-play on the ET-6000 RJ45 port, there is no need to a crossover cable to connect the ET-6000 to the Host PC, and only a general straight-through cable is needed to make the connection. The straight-through cable is shown as follows:



## **RJ-45 Cables Wiring Standard**

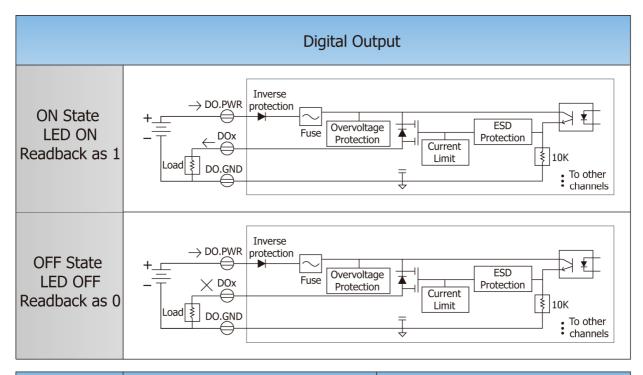


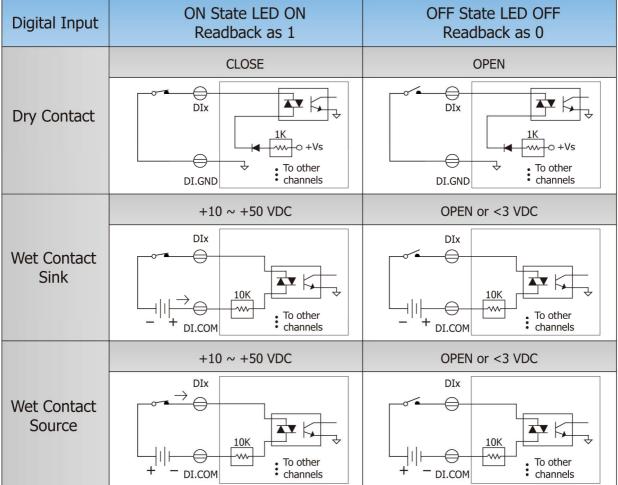
**Table 1-6 RJ-45 Wiring Standards** 

Pin Number	Signal	Function
1	Tx+	Transmit Data +
2	Tx-	Transmit Data -
3	Rx+	Receive Data +
4	N/A	Not Used
5	N/A	Not Used
6	Rx-	Receive Data -
7	N/A	Not Used
8	N/A	Not Used

# 1.6 I/O wiring connection

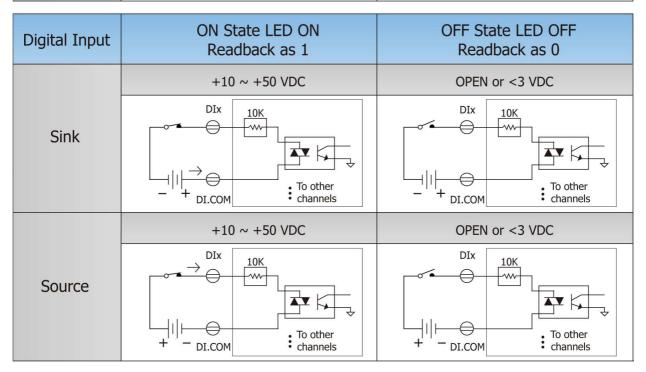
ET-6052(D)



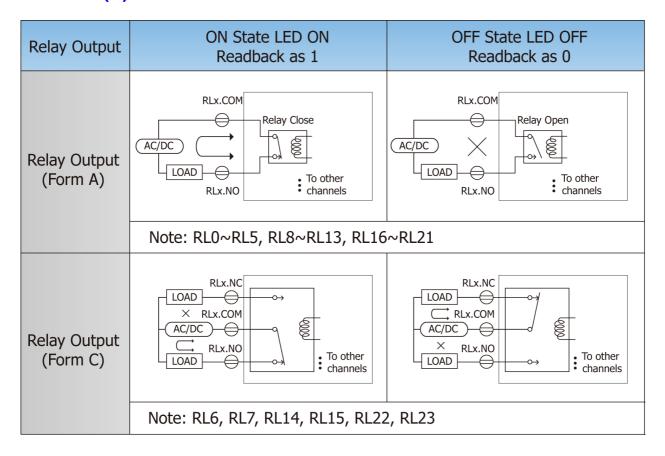


## ET-6060(D)

Digital Output	ON State LED ON Readback as 1	OFF State LED OFF Readback as 0	
	Relay ON	Relay Off	
Relay Output	RLx.COM Relay Close  To other channels	RLx.COM Relay Open  AC/DC  LOAD  To other channels	



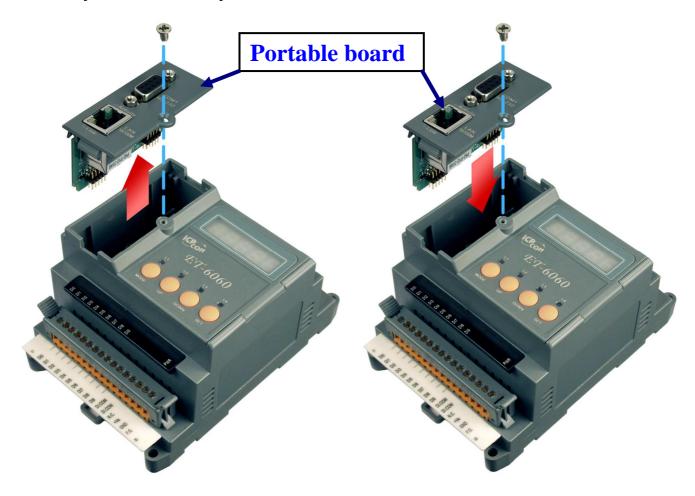
## ET2-6064(D)



## 1.7 Portable Configuration

All configuration settings can be saved to the EEPROM of the ET-6000, which is mounted on a board (known as the "portable" board shown below). The Ethernet and Serial ports are also included on the portable board and can be plugged into the main board of the ET-6000, meaning that the stored settings can be easily backed up and moved.

### **Assembly and Disassembly**





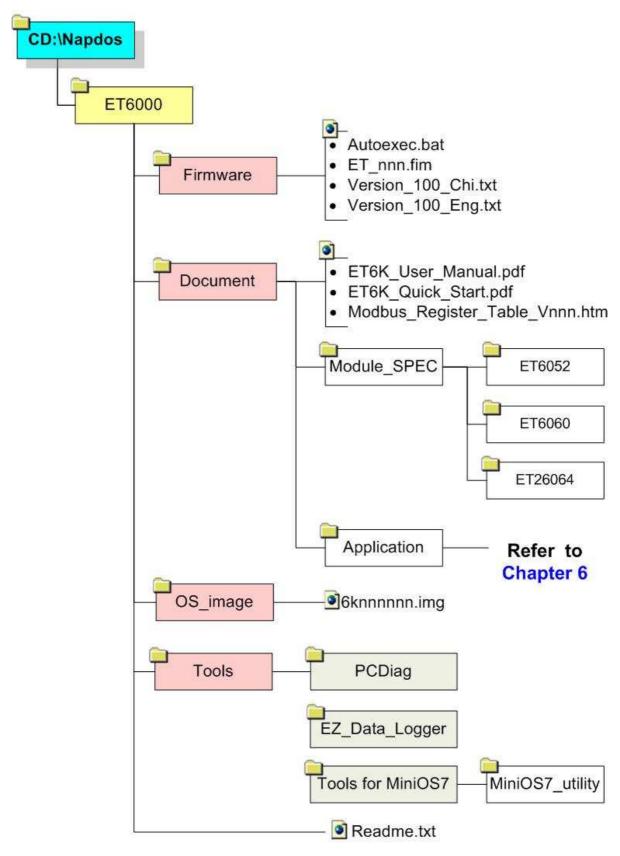


## Note:

- Before inserting or removing the portable board to /from the ET-6000, the power supply
  must be switched off. It's recommend that the power cord can be completely
  disconnected from the module.)
- The ET-6000 series module will not work normally without the portable board.

## 1.8 Software & Document information

The location of all documents and software related to the ET-6000 module is shown in the following directory structure diagram. The relevant file can quickly be located by referring to the diagram.



ET-6000 User's Manual, 2007, Sep., V1.1, 6PH-002-11------48<sup>1</sup>

## Chapter 1 Introduction

For details of the 6knnnnnn.exe revision information, please refer to CD:\NAPDOS\ET6000\Firmware\Version\_nnn\_Eng.txt or Version\_nnn\_Chi.txt

# 1.9 Update Information

Refer to http://www.icpdas.com/products/Remote\_IO/et-6000/et6k\_manual\_software.htm

# 2. Configuring the ET-6000

Before using the ET-6000, the following settings must be configured: The factory default settings are as follows:

Networking settings: IP, Mask, and Gateway of ET-6000.

Item	Default
IP Address	192.168.255.1
Subnet Mask	255.255.0.0
Gateway	192.168.0.1

Web page Configuration

Item	Default
Username	Admin (Case sensitive)
Password	Admin (Case sensitive)

The most important procedure to be completed prior to using the controller is to correctly configure the network settings.

## 2.1 Configuring the network settings

Network settings can only be configured via the Ethernet port (UDP search) or RS-232 COM Port.

MiniOS7 utility can be used to make the Ethernet address and COM port settings through Serial interface, and also can be used to make the Ethernet address settings via the Ethernet and the other Diagnostic tools used for testing the Ethernet module.

The two tools below are included in the PC Diagnostic tool and can be used to configure the ET-6000 network settings.

- 1. MiniOS7 utility (Ethernet/RS232 interface)
- 2. Configuration Wizard (RS232 interface)

# 2.1.1 Using the "MiniOS7 utility"

The MiniOS7 Utility is used to download files to the ET-6000 module and update the OS image. It can also be used to configure the network and COM port settings. In contrast to the "Configuration Wizard", valid IP, Mask and Gateway information must be available and must be manually entered into the text box provided.

Refer to **Sec. 1.4.2** for details regarding wiring connections for ET-6000 series modules, before downloading firmware.



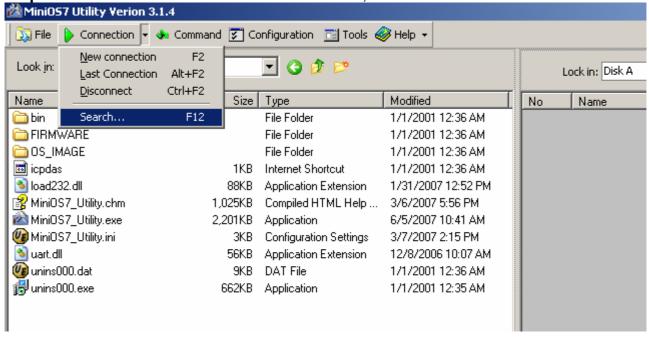
#### Note:

• The Init/Normal switch is always placed in the Normal position.

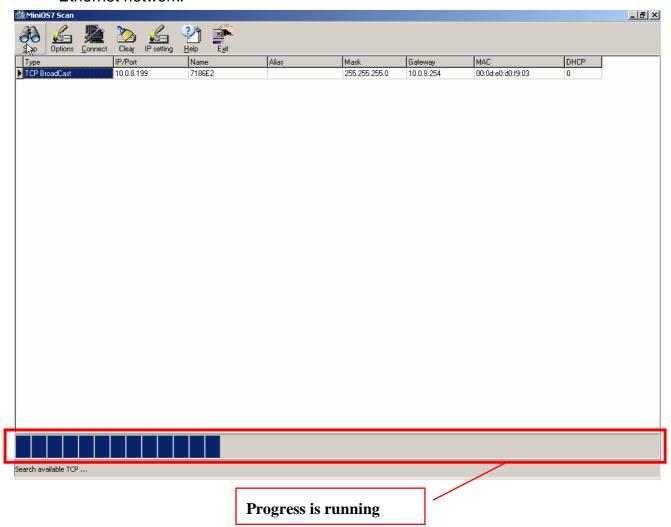
**Step 2**: Install the MiniOS7 Utility on the host PC by executing CD:\NAPDOS\ET7000\Tools\Tools for MiniOS7\MiniOS7\_utility\MiniOS7\_Utility.exe and follow the on-screen instructions

**Step 3:** Run the MinioS7 utility as per the following diagram. Mini057 Utility Verion 3.1.4 \_ B × 📆 File 🖒 Connection 🕶 🔥 Command 🗾 Configuration 🛅 Tools 🐠 Help 🕶 Look in: Carrie MiniOS7\_Utility · (3 / 1) Lock in: Disk A -Size Type Modified No Name Size Modified 🛅 bin File Folder 1/1/2001 12:36 AM FIRMWARE File Folder 1/1/2001 12:36 AM OS IMAGE File Folder 1/1/2001 12:36 AM dicpdas 1KB Internet Shortcut 1/1/2001 12:36 AM load232.dll
MiniOS7\_Utility.chm 88KB Application Extension 1/31/2007 12:52 PM 1,025KB Compiled HTML Help ... 3/6/2007 5:56 PM MiniOS7\_Utility.exe 2,201KB Application 6/5/2007 10:41 AM MiniOS7\_Utility.ini 4KB Configuration Settings 1/7/2001 11:03 PM 👏 uart.dll 56KB Application Extension 12/8/2006 10:07 AM unins000.dat 9KB DAT File 1/1/2001 12:36 AM 👸 unins000.exe 662KB Application 1/1/2001 12:35 AM ▶ Connection(F2) 🗐 Upload(F5) 😽 DiskTool(F6) 🛅 Info(F7) 🔕 Delete(F8) 🥰 Refresh(F9) 🚰 Console(F10) 🖾 DOS(F11) 👫 Search(F12)

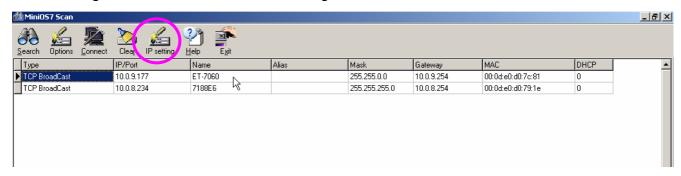
Step 4: Select the Connection item of main menu, and then click the "Search".



**Step 5:** The "MiniOS7 Scan" window appear, and start to search the modules in this Ethernet network.



**Step 6:** When the search is finished, click the ET-6000 module which you want to configure and then click the "IP setting" button.



Step 6: IP Setting window appears.



- **Step 6.1:** Check that valid IP, Mask, Gateway, Alias, DHCP values have been inserted into the "Recommend Settings" fields.
- **Step 6.2:** If these values are modified, the "Set" button must be clicked in order to create the new values.
- **Step 7**: Exit the MiniOS7 Utility and restart the ET-6000 to enable the new settings to take effect.



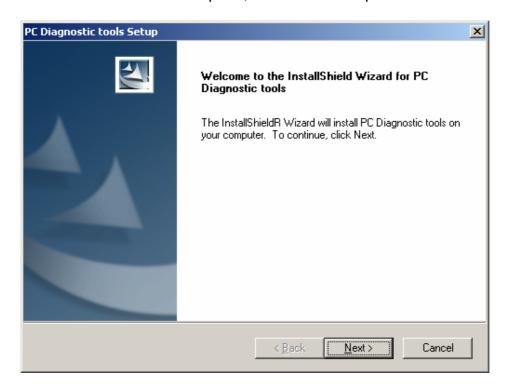
#### Note:

Please refer to **Appendix C** for more details regarding the MiniOS7 Utility installation procedure.

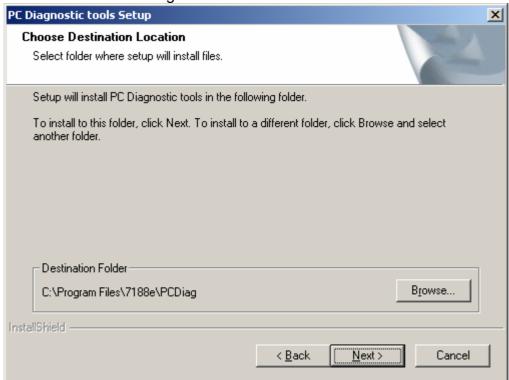
## 2.1.2 Installation

Installation Procedure

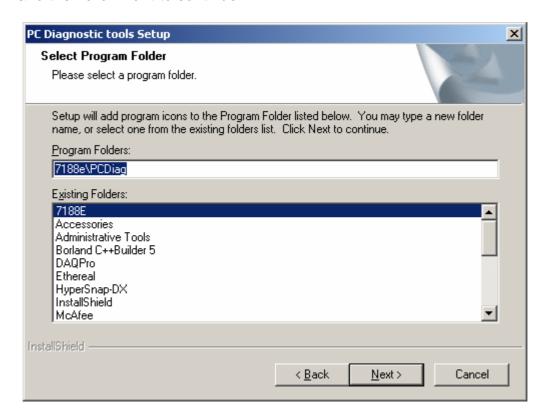
- 1. The PC Diagnostic tool is located on the shipment CD or is available via FTP. The paths are as follows
  - CD:\NAPDOS\ET6000\Tools\PCDiag\Setup\_2.0.5
  - ftp://ftp.icpdas.com/pub/cd/6000cd/napdos/et6000/tools/pcdiag/setup\_2.0.5/
  - 1. Double click the Setup.exe file to begin installation.
  - 2. When the Welcome window opens, click on Next to proceed with the installation.



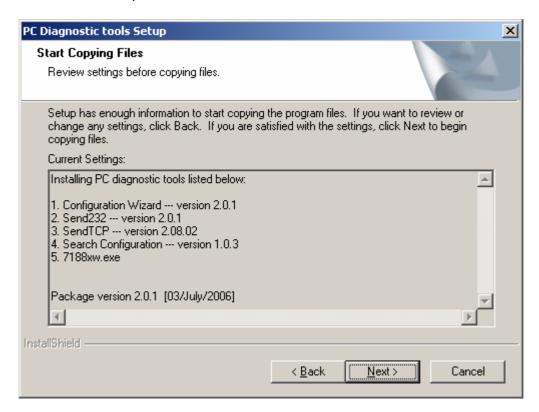
3. Click **Next** to install the program files in the default directory, or select an alternative location using the browse button.



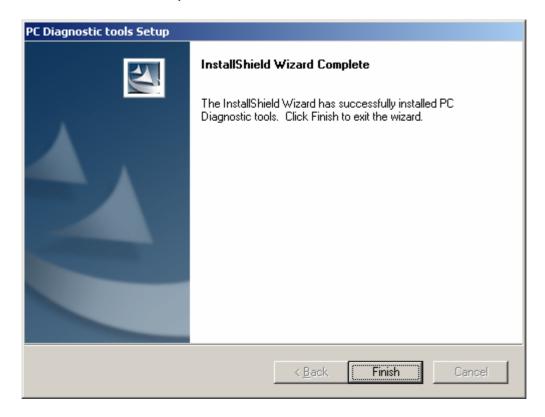
4. Select the program folder using the default folder or enter an alternative name, and then click **Next** to continue



5. Click on **Next** to proceed with the installation.



6. Click on Finish to complete the installation.



# 2.1.3 Using the "Configuration Wizard"

The "Configuration Wizard" provides step-by-step instructions for configuring the network settings. The wizard is most useful for detecting the network settings of the host PC, and for searching the local network to locate a valid IP, Mask and Gateway address. Using the "Configuration Wizard" allows automatic detection of important settings and reduces the need to contact system administrators for support.

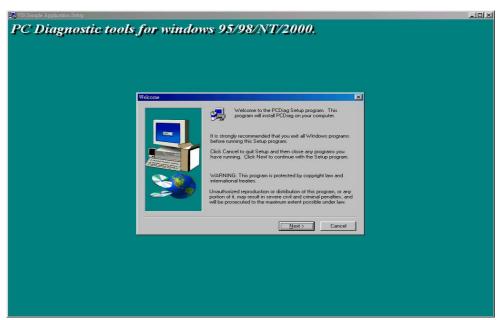
**Step 1**: Refer to **Sec.1.4.2** for details regarding the wiring connections for ET-6000 series modules.



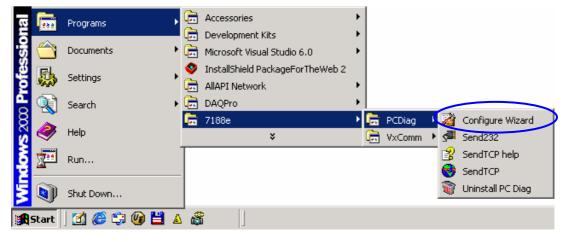
#### Note:

- During configuration, the Init/Normal switch is placed in the Init position.
- Return the Switch to the Normal position after updating the configuration.

**Step 2**: Install the PCDiag application on the host PC by executing CD:\NAPDOS\ET6000\Tools\PCDiag\Setup\_2.0.5 \PCDiag.exe and follow the onscreen instructions.



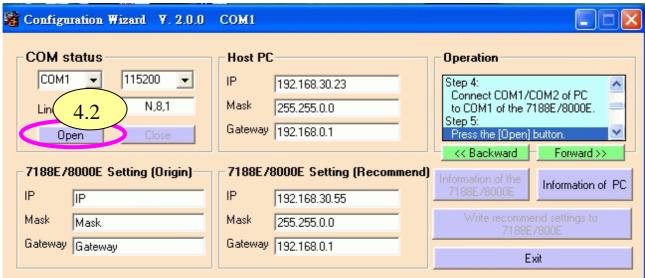
**Step 3**: Run the Configuration Wizard as follows:



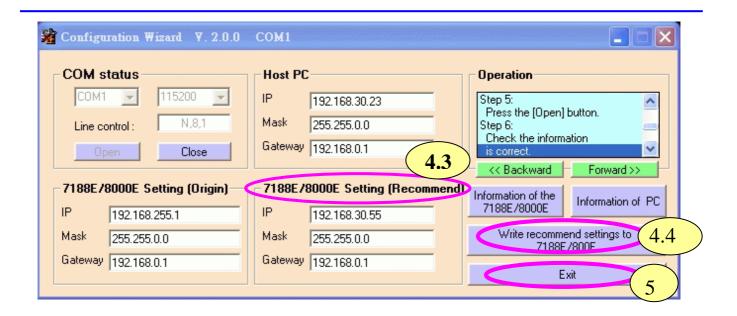
- **Step 4**: Follow each step of the instructions provided in the "Configuration Wizard" dialog box until the following window appears.
- **Step 4.1**: Click the "Custom" button to enter initial operation.



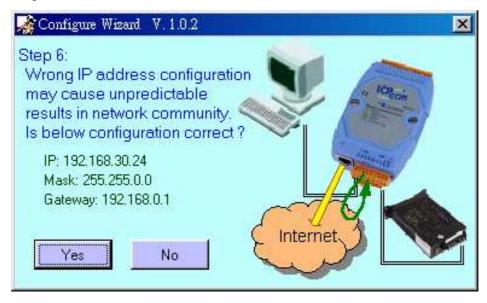
**Step 4.2**: Click the "Open" button in the COM status section to establish a connection to the PC.



- **Step 4.3**: Check that a valid IP, Mask and Gateway value has been inserted into the "7188E/8000E Settings (Recommended)" fields.
- **Step 4.4**: Click the "Write recommend settings to 7188E/800E" button to confirm the new settings. Click "YES" in the following dialog



**Step 5**: Exit the "Configuration Wizard" and then restart the ET-6000 to allow the new settings to take effect.



# 2.2 Configuration using the SMMI Menu



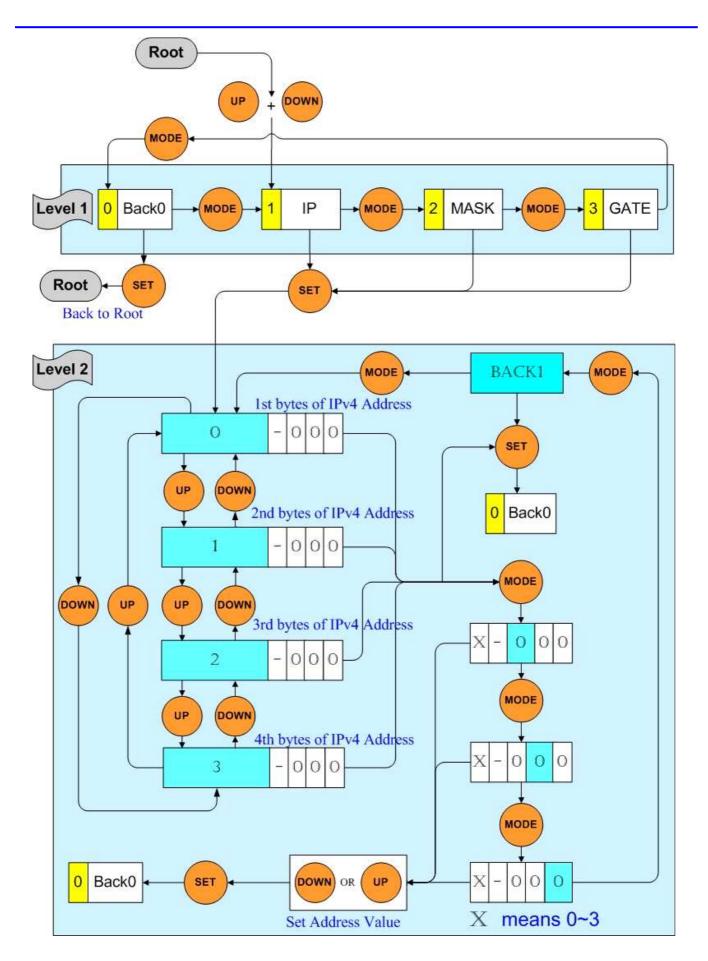
## 2.2.1 Accessing the SMMI menu for Network Configuration

The LEDs normally show system information. To access the SMMI menu, simultaneously press the "UP" and "DOWN" buttons for at least two seconds. The LED menu has 2 levels. By following the menu tree map shown in Sec. 2.2.2., the cursor position in the SMMI menu can be changed.

## 2.2.2 The SMMI menu tree

The SMMI menu is designed to allow users to set the network settings (IP, Mask, Gateway) without requiring a host PC.

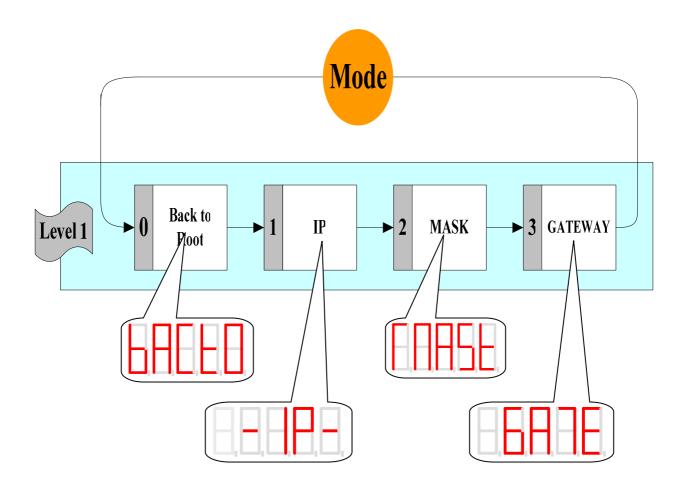
The Following diagram illustrates the SMMI menu tree.



Menu items that can be changed

There are four items in the menu, and three of which (IP, MASK and GATEWAY) can be changed. When first enter the LED menu, the initial status will be at level 1 and the cursor position will be at position 1 (IP).

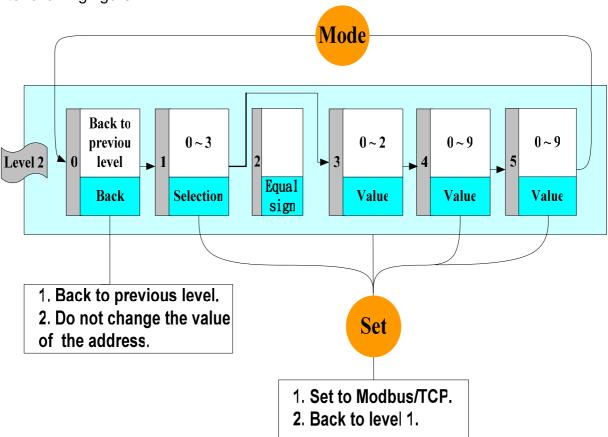
Only the "MODE" and "SET" buttons are available in this situation. By pressing the "MODE" button, the cursor can be moved with in the same level. By pressing the "SET" button, the position will be changed to another level in order to execute the selected action.



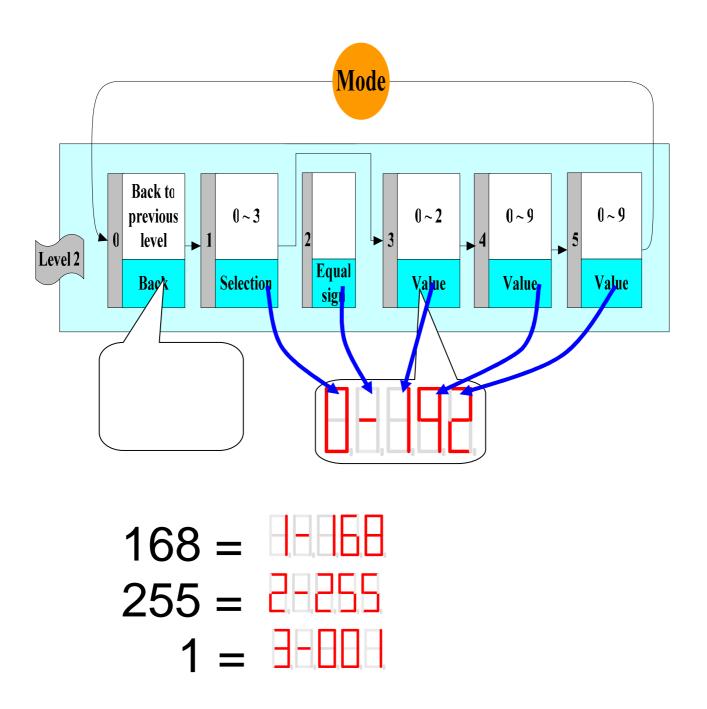
## 2.2.3 Set the address values

When enter the "**Sets the address values**" sub routine, the first LED is used for choosing which IPv4 values to change, and the last three LEDs display the current IPv4 values. Use the "**MODE**" button to select the cursor position. The "**UP**" and "**DOWN**" buttons are used to input the addresses, and the "**SET**" button establishes the addresses.

Refer to following figure:



When entering the "**Set values procedure**", the LED shows the current value. The following example shows that the IP address is192.168.255.1.



## 2.3 Load Factory Default

# 2.3.1 Web page configuration

Refer to "Load All Setup Default" in **Sec 3.2.3 Basic Setting** for more details regarding loading the factory default using the Web configuration.

## 2.3.2 SMMI

### Accessing the SMMI menu to configure the Factory Default

The LEDs normally show system information. To access the SMMI menu, simultaneously press the "MODE" and "SET" buttons for at least two seconds. The LED menu has 2 levels. By following the menu tree map shown in Sec. 2.2.2, the cursor position in the SMMI menu can be changed.



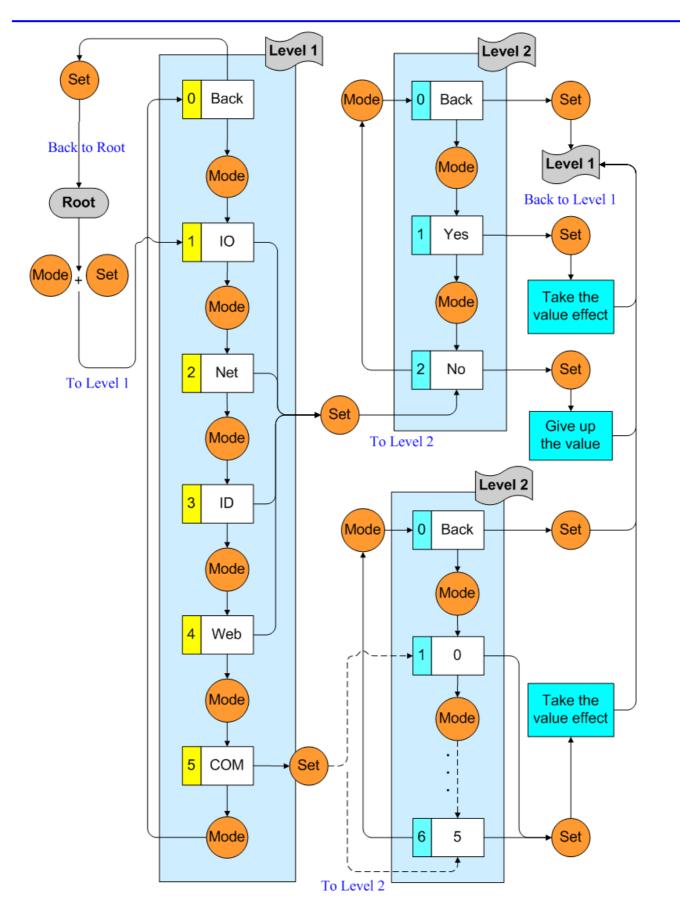
#### The SMMI menu tree

The SMMI menu is designed to allow users to load the factory default settings, including I/O, Web Server, and ID settings without requiring a host PC.

The following diagram illustrates the SMMI menu tree.

#### Menu items that can be changed

There are Six items in the menu, four of which (IO, Net, ID, Web and COM) that can be changed. When first entering the LED menu, the initial status will be at level 1 and the cursor position will be at position 1 (IO)



Only the "Mode" and "Set" buttons are available in this situation. By pressing the "Mode" button, the cursor can be moved within the same level. By pressing the "Set" button, the position will be changed to another level in order to execute the selected action.

### 7-Segment LED Display version

Reset to Factory Defaults

Step 1	Step 2	Step 3	Step 4
100: ST 12 0 10 10 10 10 10 10 10 10 10 10 10 10 1	STATUS	SET	CTATUC
			SIATUS
Press two tulions in/2 sec Press SET on x	STATUS		STATUS
Press two buttons	Led ON	Press SET for 2	Led OFF
For 2 seconds		seconds	

Reset (Software Reboot)

Step 1	Step 2	Step 3	Step 4
MODE SET		MODE	
Press two buttons	STATUS Led ON	Press MODE for 2	STATUS STATUS Led OFF
For 2 seconds		seconds	

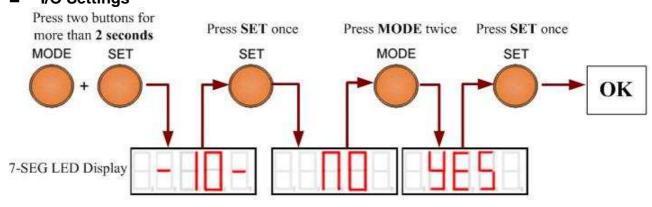


#### Note:

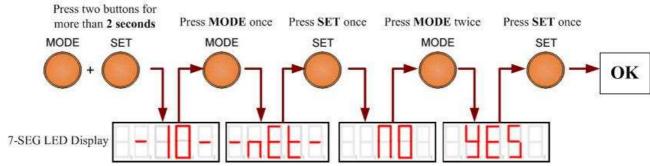
The reset function is a software reboot of the ET-6000 and doesn't reset or change the configuration of the ET-6000.

Load the Factory Defaults for each item

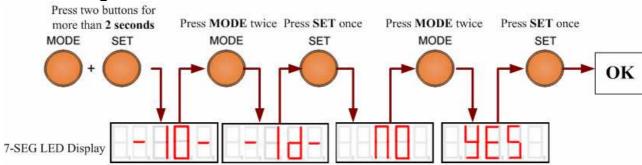
### ■ I/O Settings



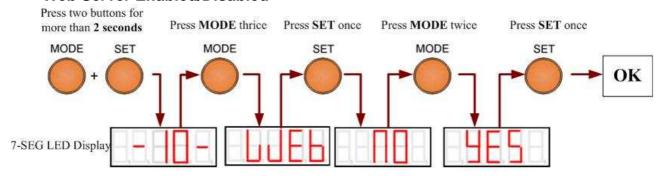
### NET settings

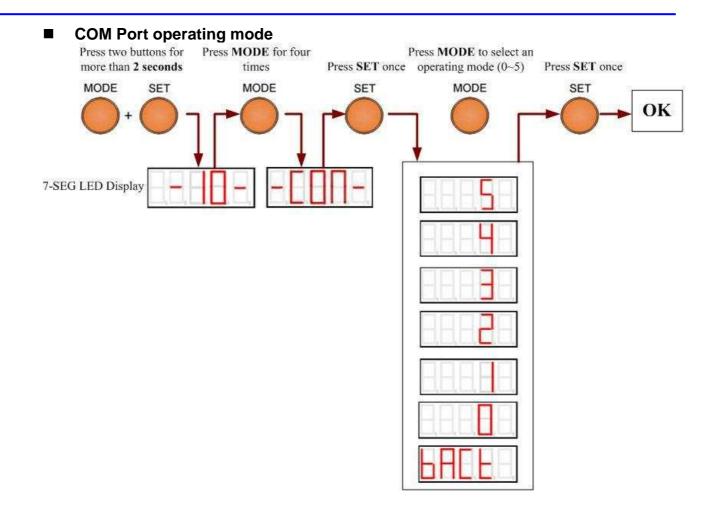


### ■ ID settings



#### Web Server Enabled/Disabled





### **Non-LED Display version**

The ET-6000 series with non-display version only has two functions Reset to Factory Defaults and Reset). The methods of Reset to Factory Defaults and Reset (Software Reboot) are same as the **7-Segment LED Display version**.

# 3. Web Configuration Page

ET-6000 series modules have a built-in Web configuration page with a friendly user interface making it simple to configure using the standard web browser.

The web configuration page is optimized for Microsoft Internet Explorer 6.0 and Mozilla Firefox, and the other browsers can work well, but the Web might appear differently.

The all configuration of ET-60000 is constructed on web page and you can only click the web to do everything through the onboard web pages using a standard web browser via Ethernet. Don't need extra tools or utilities on Windows to configure and control the ET-6000.

#### Opening the browser to connect the ET-6000

- 1 Start up the Internet Explorer or Mozilla Firefox, and click the URL block at the top of the screen.
- 2 Input the URL address of the ET-6000 (Such as http://192.168.255.1) into the URL block and press the "Enter" button to enter the login page.



#### Note:

- The Factory default IP address is **192.168.255.1**
- The default user name and password is Admin and Admin (Case sensitive)
- If you forget the user name or password, the ONLY way to start configuring ET-6000 is to load factory default by using the Reset button on SMMI menu (Refer to chapter xxx)
- 3 Input the User Name and password on the dialog, and then click the "OK" button. (See the dialog box below)



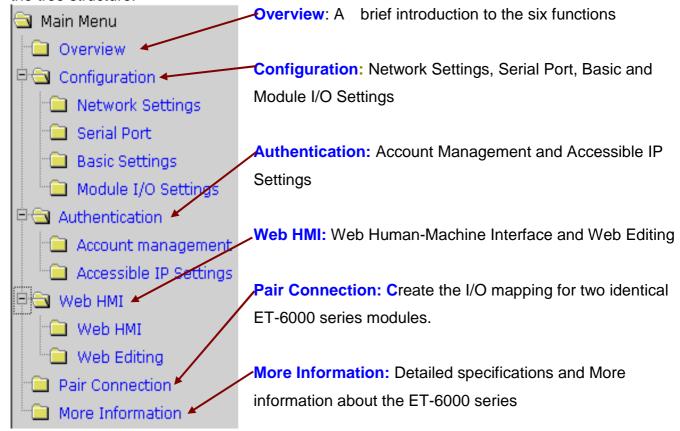
After the user name and password is accepted by the ET-6000, The ET-6000 home page will be displayed.





If either the user name or the password is incorrect or is left blank, the main home page and the other pages will not be accessible, so ensure that the input data is correct and rectify it if and as necessary.

The brief description of the Web page configuration function is listed on six main functions of the tree structure.



### 3.1 Overview

The Welcome page for the ET-6000 contains information related to the currently accessed ET-6000 series module, as shown below:

**Model Name:** ET-6000 series module name (The default is the ET-6000 series name. The maximum length is **8** characters)

MAC address: The MAC address of the currently accessed ET-6000 series module

Module Information: The alias name of the ET-6000 series module Firmware Version: The version number and date of the default firmware

OS Version: The version number and date of the operating system

**DI/DO/AI/AO channel:** The number of DI/DO/AI/AO channels depends on the specifications of the ET-6000 module.

Model Name	ET-6060
MAC Address	0:d:e0:a3:dd:af
Module Information	N/A
Firmware Version	V100 (Dec 29 2006)
OS Version	V202 (Aug 8 2005)
DI channels	10
DO channels	8
AI channels	0
AO channels	0

#### **General Description**

The ET-6000 series is a selection of cost effective, high performance 10/100 Mbps I/O modules designed for remote data collection and remote Ethernet application control. Each ET-6000 module includes its own internal Ethernet configuration, Modbus TCP/IP port and web port, with a build-in simple HMI that makes configuration and access easy, together with an I/O LED display to indicate the current transmission status.

The ET-6000 supports Modbus/TCP forout any extra programming. Us connecting to most SCADA software such as Indusoft, iFix and Labview. The built-in RS-232 serial port supports the Modbus RTU protocol making it easy to connect an HMI panel. ET-6000 also supports Web server access allowing the making user to monitor and access the remote I/O from a Web browser withers can also download their own custom defined pages into the ET-6000 via our Windows Utility. ICPDAS also provides a Java Applet application in ET-6000 as a reference for designing your own Web interface.

#### Configuration

### Network Settings

IP address, Net mask, default gateway, DHCP, static IP or dynamic IP , Firmware and OS version information...

#### Serial Port

Baud rate, start bits, data bits, stop bits, operation mode.

#### Basic Settings

Module name, Module information, real time clock, time server IP address, Web HMI and Telnet console Enable, Disable function. Load the factory default settings

### Module I/O Settings

Module I/O configuration including DI latch, digital counter Enable, Disable function...

Settings for Watchdog Timer, DO Power on value and Safe value, AI High/Low

# 3.2 Configuration

# 3.2.1 Ethernet Settings



The Ethernet settings page can be used to view and change the TCP/IP network settings for the ET-6000 module.

Table 3-1 TCP/IP network settings

Settings	Description	Range	Factory default
IΡ	4-byte IP address. Each ET-6000 module needs an IP address so that if can be identified on the network	X.X.X.1 To X.X.X.254	192.168.255.1
Gateway	4-byte Gateway. A gateway is a network address that acts as an entrance to another network. Usually, computers that control the traffic within the network or at the local Internet Service Provider (ISP) are gateway nodes.	1()	192.168.0.1
Mask	4-byte subnet Mask. A subnet mask represents all the network hosts at one geographic location on the same local area network. When an Ethernet packet is sent across the network, the ET-6000 will use the subnet Mask to check whether the TCP/IP host specified in the packet is on local network segment.	10	255.255.0.0

DHCP	Select this option If there is a DHCP server on the network, the IP address can be assigned automatically by the server.		0 (Disable)
Firmware Ver.	Firmware Version and Date	N/A	Varies depending on the Module
MiniOS7 Ver.	MiniOS7 Version and Date	N/A	Varies depending on the Module

### **DHCP function**

DHCP (Dynamic Host Configuration Protocol) is a method used to dynamically assign temporary numeric IP addresses as required.

When the DHCP function is enabled, the ET-6000 module will automatically load the IP/Mask/Gateway address saved in the EEPROM if the ET-6000 cannot get a dynamic IP address from the DHCP server on boot up. This may occur if the DHCP server is unavailable or if the Ethernet cable/device between the module and the Host PC is damaged. In this situation, the ET-6000 will not continue to make requests to the DHCP server until the next reboot, even if the DHCP function is enable.



#### Notes:

- For correct IP/Mask/Gateway address information, please consult the network administrator.
- If you don't have a DHCP server available on the network, it is recommended that the DHCP function is disabled.
- No matter whether a static IP or a dynamic IP address is used, the IP address will be displayed on the 7-segment of SMMI LED (ET-6000D module only). Refer to Sec 1.4.1 "Front Panel Description" for more details.

## 3.2.2 Serial port settings

Item	Parameters	Current setting
Com Port	COM1 ♥	1
Baudrate	115200 V bps	115200
Data Bits	C 5 bits C 6 bits C 7 bits € 8 bits	8
Parity	None CEven COdd CMark CSpace	None
Stop Bits	• 1 bits ○ 2 bits	1
Check Sum	C True False	1
Operation Mode	2 V 0 (VxComm),1 (ModbusRTU),2 (Programming),3 (UpLink),4 (Debug), 5 (Console)	2
Net ID	1 Modbus Station Number	1
Time Out	200 ms (5~32767)	200
Station per COM Port	10 Stations	10

The right hand column shows the current serial port settings.

The left hand column shows the serial port settings parameters that can be modified. The serial port settings page allows you to view and change the Serial port settings of the ET-6000 module.

**COM port:** The ET-6000 series only has one COM port (COM1)

Baud Rate: The Baud Rate can be set to either 300, 600, 1200, 2400, 4800, 9600, 19200,

38400, 57600 or 115200 bps

Data bit: The Data Bit can be set to either 7 or 8 bit.

Parity: The Parity can be set to None, Even Odd, Mark or Space.

**Stop bit:** The Stop Bit can be set to 1 or 2 bit.

Checksum: This value can be set to either enabled or disabled.

**Operation Mode:** 

Mode 0: VxComm (Virtual COM)

Enable VxComm. The Remote application program can use a Virtual COM port (the VxComm Driver sould be installed) or can connect to TCP/IP Port 10001 to access the COM port via the Ethernet. In VxComm mode, the COM port can connect to any serial device. (Unavailable)

Mode 1: Modbus/RTU

Enable the protocol converter function to convert Modbus/TCP to Modbus/RTU. In Modbus/RTU mode, the COM port can only connect to Modbus/RTU slave devices.

- Mode 2: System Reserved
- Mode 3: UpLink

Enable the COM port as a Modbus/RTU slave port.

Mode 4: Debug port

The Modbus kernel displays some messages while communicating with Modbus clients or masters.

Mode 5: Console

This is a serial console port that can be used to configure the module via an RS232.

#### **Net ID:**

If the Modbus station number in a Modbus/TCP request (from PC or HMI) matches the Net ID, the request is passed to the Modbus kernel. Then Modbus kernel program will then respond and send the internal registers to the Modbus/TCP client (PC or HMI). The content of all other registers is zero.

### Time out:

It's used for Modbus protocol communication via a RS232 interface. After completing data transmission, the system begins to count time, if timeout expires, the system stop receiving responses.

### **Stations per COM port:**

This value is used to decide how many Modbus/RTU stations can add on one ET-6000 COM port for control.

Table 3-2 Serial Port Settings

Settings	Range	Factory default
Baud Rate	300, 600, 1200, 2400, 4800, 9600, 19200, 38400,57600,115200 bps	115200 bps
Data Bit	7, 8 bit	8
Parity	None, Even, Odd	None
Stop Bit	1, 2 bit	1
Checksum	True, False	False
Operation Mode	0~5	5 (Console mode)

Net ID	1~255	1
Time out	0~32767 milliseconds	200
Stations per COM port	1~255	10



#### Note:

When an ET-6000 module receives a Modbus/TCP request that is not directed to its internal registers, it first decides which COM port to use to send the request. Modbus/RTU must be enabled for this COM port otherwise the request will be discarded.

# 3.2.3 Basic Settings

Module Name	ET-6060 (Maximum 8 characters)	
Module Information	N/A (Maximum 16 characters) (The content cannot include " or " character)	
Top page Information (First line)	ICPDAS (Maximum 20 characters)  Color Red ▼ Font 0	
Top page Information (Second line)	http://www.icpdas.com (Maximum 50 characters)  Color Red Font 0	
More Information URL	http://www.icpdas.com/products/Remote_IO/et-6(Maximum 100 characters)	
Web Server TCP Port	80	
Time		
Time Zone	(GMT0:00)Greenwich Mean Time: Dublin, Edinburgh, Lisbon, London ▼	
Current Module time	2000 / 5 / 31 10 t 31 t 51 Check Set Now	
Time server		
Console		
Web Configuration	C Disable Enable	
Telnet console	© Disable C Enable	

### **Module Name:**

The initial value will be the default module name. The name can be modified by the user using a maximum of 8 characters. (**Unavailable**)

#### **Module Information:**

Indicates the alias name given to the module and can be modified by the user. The name can be a maximum of 16 characters, but cannot include single or double quotes (' or "character).

After the new values are submitted, the **Module Name** and **Module Information** will be updated. The new details can be verified by viewing the main.htm (Overview of tree), while you submit the new value.

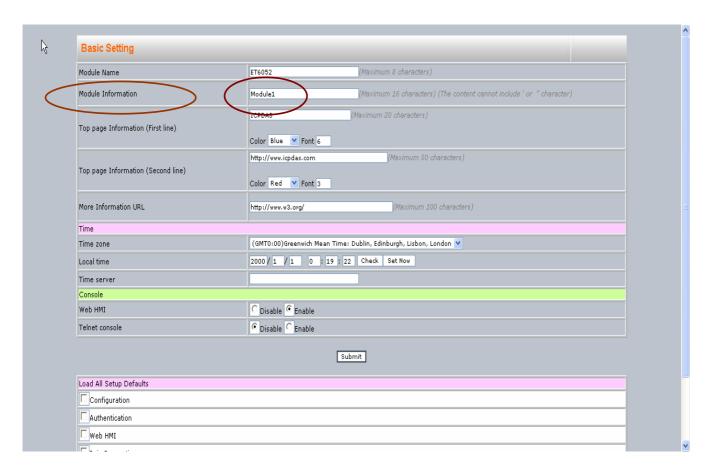
### **Example:**

Click the Basic Setting in the Configuration section of the Main Menu tree.

Enter a string into the Module Information text field, for example, Module1.

Click Submit to enable the settings to take effect.

Click the "Overview" in the Main Menu tree to verify that the changes have been applied.





### Top page Information (First line) and Top page Information (second line):

The top page information is displayed at the top of the web page, as shown below, and can be modified to enable custom information to be displayed.



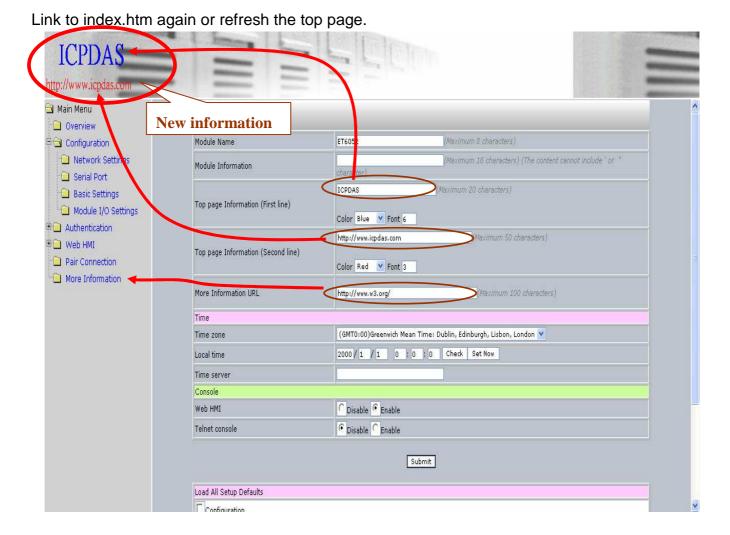
After submitting the new details, the **Top page Information** will be updated and will be displayed at the top of the web configuration page.

### **Example:**

Click "Basic Settings" in the Configuration Section of the Main Menu tree.

Enter a string in the Top page Information (First line) and Top page Information (second line) text fields, for example "ICPDAS" and "http://www.icpdas.com". The font size and color can be modified by selecting an option from the color drop down box and entering a value in the font text field.

Click Submit button to enable the settings to take effect.



### **More Information URL:**

It may often be helpful to provide users with additional information while browsing the Web Configuration page.

After submitting the new details, the **More Information** link in the Main menu tree will be updated.

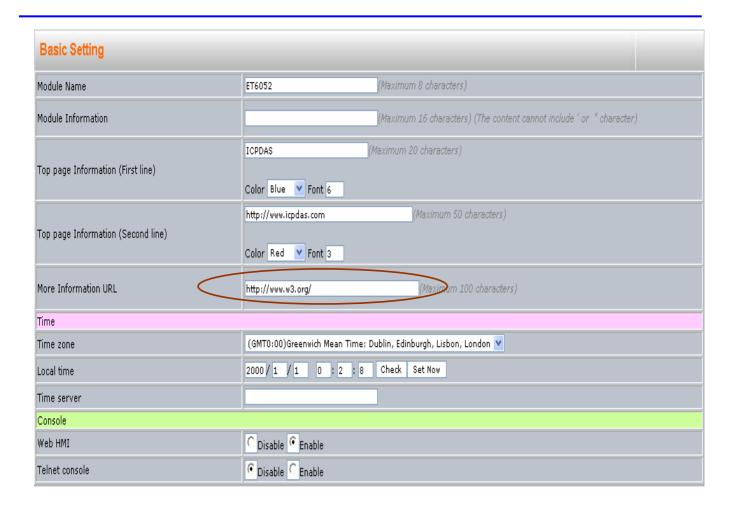
### **Example:**

Click the "Basic Settings" if the Configuration Section of the Main Menu tree

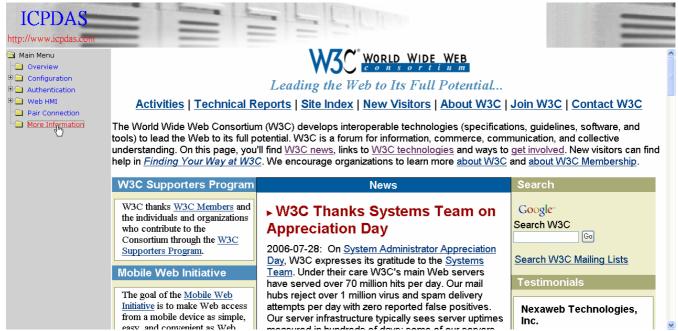
Enter a URL in the "More Information URL" text field, for example "http://www.w3.org". (The

URL may be either an external site or a link to a page on your intranet)

Click Submit to enable the settings to take effect.



Clicking the "More Information" in the Main Menu tree will automatically open the web page defined in the More Information URL.



The default URL for "More information" is "http://www.icpdas.com/products/Remote\_IO/et-6000/et-6000\_introduction.htm"

### **Web Server TCP Port:**

The default well known port which is used in TCP to name the ends of logical connections for Web server of ET-6000 is 80.

It allows the user to change the port to the other,  $(0\sim65535)$ .



### **Time**

The ET-6000 module includes a built-in Real-time Clock that is used to perform time calibration functions.

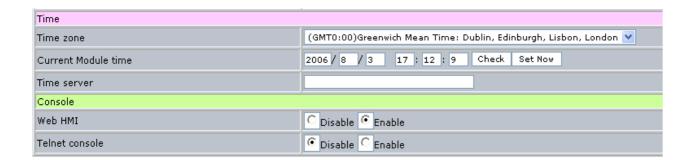
### Check:

**Set Now**: Synchronizes the current local time of the host computer to the ET-6000



### **Notes:**

- 1. If the IP address of the "Timer Server" is valid, the ET-6000 will request time information from the "Time server" at one hour intervals.
- 2. If the IP address of the Time server is not present or incorrect, the synchronization with the SNTP server function will be disabled.



**Table 3-3 Basic Settings** 

Function Name	Description	Range	Factory default
Module Name	The name of the ET-	Not available for	Depends on the
	6000 series module	modification	type of ET-6000
			Module
Module Information	Alias or nickname	Maximum of 16	None
	assigned to the Module	characters	
Top page	User-defined	Maximum of 20	None
Information	Information	characters	
(First line)			
Top page	User-defined	Maximum of 50	None
Information	Information	characters	
(Second line)			
More Information	The URL can be linked	Maximum of 100	None
URL	to a user specified Web	characters	
	page.		
Time Zone	User selectable time	24 Time Zones	GMT (Greenwich
	zone		Mean Time)
Current module time	The current time stored	Year/Month/Day,	Module time

	on the ET-6000 module	Hour:Minute:Second	
Time server	The IP address of the	IP address or Domain	None
	SNTP server (Time	name	
	Server)		
Web Configuration	Web configuration via a	Enable/Disable	Enable
	Web browser		
Telnet console	Console mode via an	Enable/Disable	Enable
	Ethernet (Telnet).		



### **Notes:**

- 1. If both "Web Configuration" and "Telnet Console" are disabled, the Serial console can still be used to configure ET-6000 locally.
- 2. The setting value of "Top page Information (First line)", "Top page Information (Second line)" and "More Information URL" function will retain in factory default while the settings have not be changed. If the settings have be modified by user, the setting value will be the user's defined information even loading the factory default again.

Load All Setup Default
Load All Setup Defaults
☐ Configuration
☐ Authentication
web HMI
Pair Connection

Table 3-4 Load All Setup Default Table

Function Name	Details	Factory default
Configuration	All of the Ethernet settings	Refer to Table 3-1
	All of the Serial port settings	Refer to Table 3-2
	All of the Basic settings	Refer to Table 3-3
	All of the Module I/O settings	Refer to Sec. 3.2.4
Authentication	Account management	The default account is
		"Admin" and the
		password is "Admin"
	IP filter settings	Allow all of the IP
		connections
Web HMI	Web Page editing function	0 pages
Pair Connection	I/O Pair connection	Disabled
All	Set the factory default value for the 4	Refer to the function
	main functions above. (Configuration,	details above.
	Authentication, Web HMI, Pair	
	Connection)	

Submit: Press this button to allow the settings to take effect.



□ All

## Note:

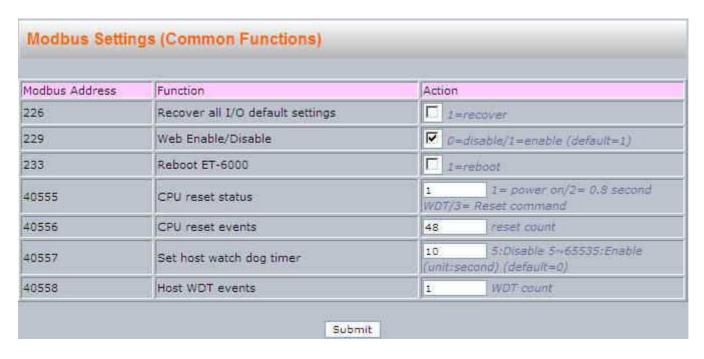
Be aware that affer modifying the settings and submitting the new information, all previous settings for the module will be lost.

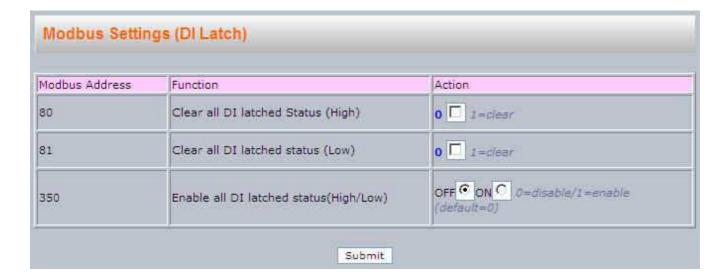
# 3.2.4 Module I/O settings

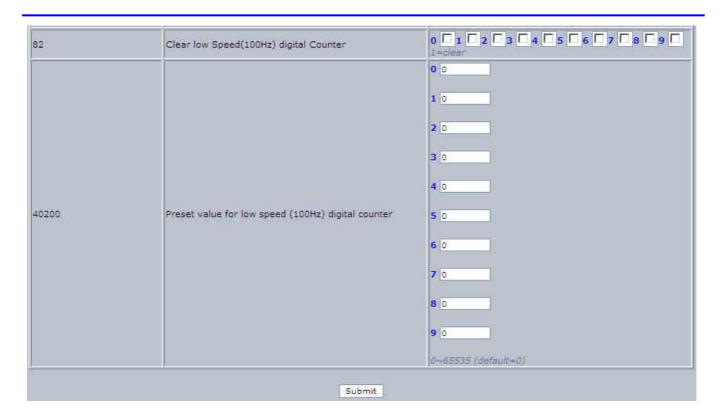
Different Modbus setting functions will be displayed on this page depending on the type of ET-6000 module. All settings can be divided into either common, DI, DO, AI and AO settings. Please refer to **Appendix D** for more details regarding ET-6000 Modbus register table.

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The illustration below shows the Modbus settings for the ET-6060 module







Modbus Address	Function	Action
40200	Preset value for low speed (100Hz) digital counter	0 0 1 0 2 0 3 0 4 0 5 0 6 0 7 0 8 0 9 0 0~65535 (default=0)
40555	CPU reset status	1
40556	CPU reset events	6 reset count
40557	Set host watch dog timer	0 5:Disable 5~65535:Enable (unit:second) (default=0)
40558	Host WDT events	0 WDT count

## **Modbus Registers and Factory Defaults**

## **Common Functions**

Modbus Address	Points	Description	Range	Factory default
40557	1	Set host watch dog timer	5~65535 (Enable)	0 (Disable)
		(Second)	(<5: Disable)	

### **DI Module Functions**

Modbus Address	Points (Max.)	Description	Range	Factory default
00350	1	Enable all DI latched	0 (Disable)	0 (Disable)
		status (high/low)	1(Enable)	
00351~	80	Enable low speed	0 (Disable)	0 (Disable)
00431		(100Hz) digital counter	1(Enable)	
40200~	32	Preset value for low	0~65535	0
40231		speed (100Hz) digital		
		counter		

### **DO Module Functions**

Modbus Address	Points (Max.)	Description	Range	Factory default
00435~	80	Power on value for DO	0=off	0
00514			1=on	
00515~	80	Safe value for DO	0=off	0
00594			1=on	

### **Al Module Functions**

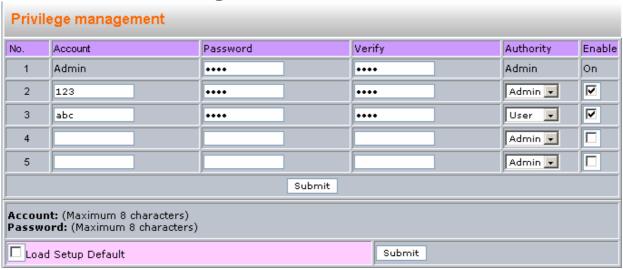
Modbus Address	Points (Max.)	Description	Range	Factory default
00595~ 00626	32	Enable/Disable Al channel	0=disabled 1=enabled	1
00627	1	Enable/Disable CJC	0=disabled 1=enabled	1
00628	1	Normal/Fast mode for AI	0=normal (16 bit) 1=fast (12 bit)	0
00629	1	50/60 Hz rejection for AI	0= 50 Hz 1=60 Hz	1
40296~ 40327	32	High alarm value for Al	-32768 ~ +32767	32767
40328~ 40359	32	Low alarm value for Al	-32768 ~ +32767	-32768
40360	1	Alarm mode for all Al	0= disabled 1= moment 2= latched	0
40427~ 40458	32	Range code for Al	Refer to range code table	Depends on the type of Module
40491~ 40522	32	CJC value for Al	-256~+255, unit = 0.1 °C	0

## **AO Module Functions**

Modbus Address	Points (Max.)	Description	Range	Factory default
40361~ 40392	32	Power on value for AO	-32768 ~ +32767	0
40393~ 40424	32	Safe value for AO	-32768 ~ +32767	0
40459~ 40490	32	Range code for AO	-32768 ~ +32767	Depends on the type of Module
40523~ 40554	32	Slew Rate of AO	-32768 ~ +32767	Depends on the type of Module

## 3.3 Authentication

# 3.3.1 Account management



Each ET-6000 series module provides access privilege for up to five user accounts including a default **Admin** account and four general user-defined accounts. Each of the user-defined accounts can be assigned either Admin or general user privilege. Assigning Admin privilege allows the account to read and write configuration settings but the general user account is restricted to read only access. The maximum number of characters that can be used for an account name is 8.

Each of the account requires password authentication. The maximum number of characters allowed for the password is 8.

Load Setup Defaults: Load the factory default Account management settings. All current accounts will be deleted, except the Admin account, and the password of Admin account will revert to "Admin".

Submit: Press this button to enable the settings to take effect.



#### Notes:

- The default account is called "Admin" and the password is also "Admin". The password and the Admin account can be changed, but the account name cannot be changed or deleted.
- If you forget the password for the Admin account, the ONLY way to configure the ET-6000 is by using the "Reset to Factory default" option. (Please refer to Load All Setup Default on Sec. 3.2.3 for more information)

## 3.3.2 IP filter Settings

IP	IP filter Settings				
ПЕ	Enable the IP filter table. ("Disable" will allow connection requests from all IPs.)				
IP ad	dress at the browser PC	: 10.0.8.12			
No.	Active the rule	From (IP Address)	To (IP Address)		
1					
2					
3					
4					
5					
6					
7					
8					
9					
10					
	Submit				

Each ET-6000 series module contains an IP filter that can be used to control access to the module, thereby preventing unauthorized access from unknown IP addresses. The IP filter can be granted across a range of IPv4 addresses, such as from 10.0.8.1 to 10.0.9.22 or to a single IP address, with a maximum of ten permission rules. Once the IP addresses that have been granted access permission have been entered, and the rule activated, the ET-6000 module IP filter will guard the TCP/IP connection by restricting access to any unauthorized IP addresses.

There are three methods of restricting or granting access permissions.

### Allow Only a specific IP address

Enter the same IP address in both the From and TO IP address text fields

Active the rule	From IP Address	To IP Address
	192.168.255.1	192.168.255.1

### Allow Hosts within a specific IP address range

Enter the first IP address in the From IP address text field, and enter the last IP address in the permitted range in the To IP address text field.

Active the rule	From IP Address	To IP Address
<u>~</u>	10.0.8.1	10.0.9.22

### Allow access from any IP address

Disable IP filter function to allow access to the ET-6000 module from any address.

Enable the IP filter table. ("Disable" will allow connection requests from all IPs.)

The "Enable the IP filter table" checkbox must be checked when granting permissions to either a single IP address or a range of IP address.

Epable the IP filter table. ("Disable" will allow connection requests from all IPs.)

Submit: Press this button to enable the settings to take effect.



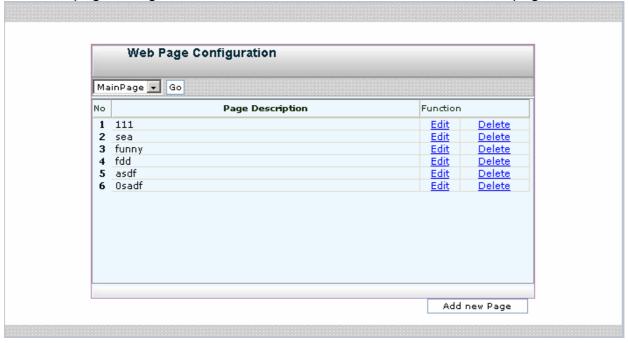
### Note:

The IP filter is set to "disabled" by default, meaning that access to the ET-6000 module is allowed from any IP address.

### 3.4 Web HMI

# 3.4.1 Web Editing

The Web page configuration can be used to create a user-defined Web page.



Click "Web Editing" in the "Web HMI" section of the Main menu tree and the window above will be displayed.

Click the "Add new Page" button to create a new page.

Click the "Edit" link to edit the selected page.

Click the "Delete" link to remove the selected page.

The list box on the left hand side of the "Web Page Configuration" window lists all existing pages including the main page, pair connection page.

A maximum of 10 pages can be created.

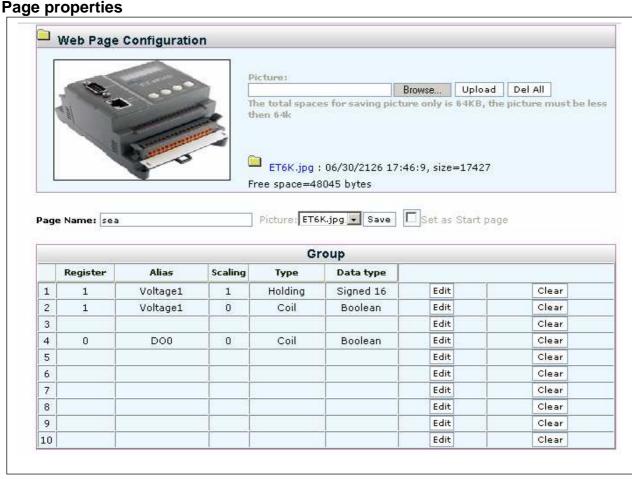


Browses the Web HMI with the name listed on the list box.

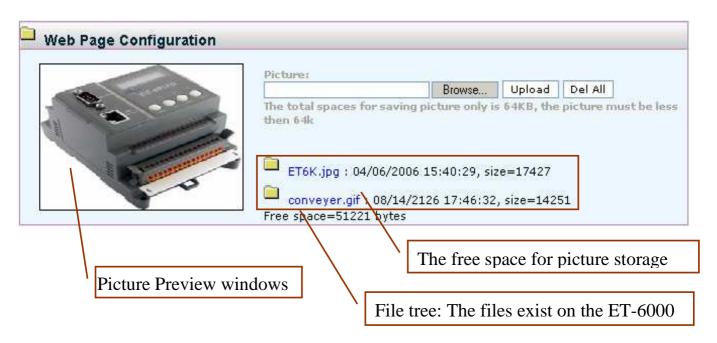


### Notes:

- By default, no existing pages will be listed in the Web Page Configuration window.
- The "Main page" shown in the HMI list box located on the left hand side of the "Web Page Configuration" window is a standard default Web HMI page and cannot be deleted.
- The Pair Connection Page can be enabled by enabling the I/O pair connection function in the "Pair connection" section of the Main menu tree. Please refer to Sec 3.5 for more details.



All properties can be configured on this page.



A maximum of 10 items in each group can be configured.

: The image file name selected by clicking the "Browse" button.

The image file type can be either of .jpg, .gif or .bmp. The recommended resolution for the

ET-6000 User's Manual, 2007, Sep., V1.1, 6PH-002-11-----97<sup>1</sup>

image to be displayed on the Editing Web page is 340 \* 250 pixels.

Each ET-6000 series module has a maximum storage space of 64KB.

: Browse a directory on the local disk to select an image file to be uploaded to the ET-6000 module.

: Upload the selected image file to the ET-6000 module.

Del All: Delete all files that are currently stored on the ET-6000 module.

Click the Del All button to delete all files that currently exist on the ET-6000 module.





### Notes

- The "Del All" action will delete all files currently stored on the ET-6000 module, and it cannot be used to delete individual files.
- The ET-6000 will reboot after deleting the files.

Page Name: Conveyer Picture: conveyer.gif ▼ Save ☐ Set as Start page

**Page Name**: This field can be used to give the page a more descriptive name. The maximum number of characters that can be used for a page name is **10**.

**Image**: Use the list box to choose the image to be displayed in the preview window.

Save: The information displayed on this page will be saved after clicking this button.

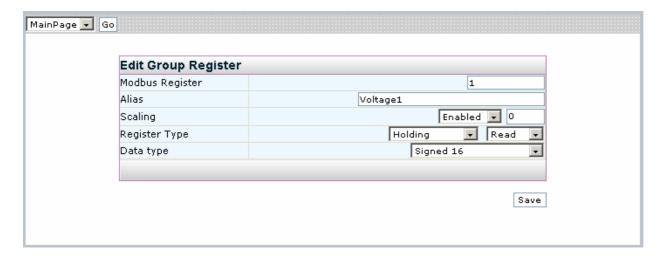
**Set as the Start Page**: Clicking the checkbox to make the current page to be displayed when clicking the Web HMI link in the Web HMI section of the Main Menu tree.

Edit: Clicking this button will link to the "Edit Group Register" page to allow the point information to be edited.

: Click the "Clear" button to delete the point information.

Refer to next Section for more details regarding the definition of the field if the "Group" Table.

### **Editing the Group Register**



Modbus Register: The Modbus Register number for the ET-6000 module

**Alias**: A string that describes the Modbus register. It can be a reference to a tag in the image of the Web editing page which is selected from the "Page properties" section. (If the tag of the Modbus register has defined on the image)

**Scaling**: The Modbus register value will be divided by the scale value before being displayed on the web page, or multiplied before value is written to the ET-6000 module.

This function is only used for Input or Holding register types.

- Enable: Enable the Scaling function
- **Disable:** Disable the Scaling function.

### **Example:**

- 1. Modbus register value= 620, Scale value=10 → 62.0 will be shown on the Web page.
- Modbus register value=7325, Scale value=1000 → 7.325 will be shown on the Web page.
- 3. Web page input= 32.20, Scale value=100 → 3220 will be written to the Modbus register.

**Register Type**: Defines the Modbus register type.

Bit format: Coil (Digital Output), Discrete input (Digital Input).

Byte format: Input (Analog Input), Holding (Analog Output).

**Data Type**: Defines the data type of the Modbus register and must be either Input or Holding. The data type can be one of the following:

**Table 3-5 Input or Holding Data Types** 

Data Type	Definition
Unsigned 16	A 16-bit positive value
Signed 16	A16-bit value with a sign
Unsigned 32	A 32-bit positive value. The Most significant word (register) is on the low address.
Signed 32	A 32-bit value with sign. The Most significant word (register) is on the low address.

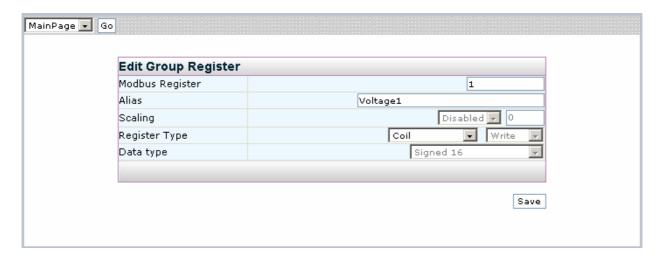
Unsigned 32 (swapped)	A 32-bit positive value. The Most significant word (register) is on the high address.
Signed 32 (Swapped)	A 32-bit value with sign. The Most significant word (register) is on the high address.
Float	A 32-bit floating point. (IEEE754). The Most significant word (register) is on low address.
Float (swapped)	A 32-bit floating point. (IEEE754). The Most significant word (register) is on high address.

: Click this button to save all settings.

The diagram below shows an example of how to select a Coil register type with a Modbus Register Address of 1 and Alias name of Voltage 1.

Other text fields that aren't related to the Coil register type will be disabled.

The Modbus Register and Alias text fields are only related to the Coil and Discrete Input register types, but the other fields aren't related.

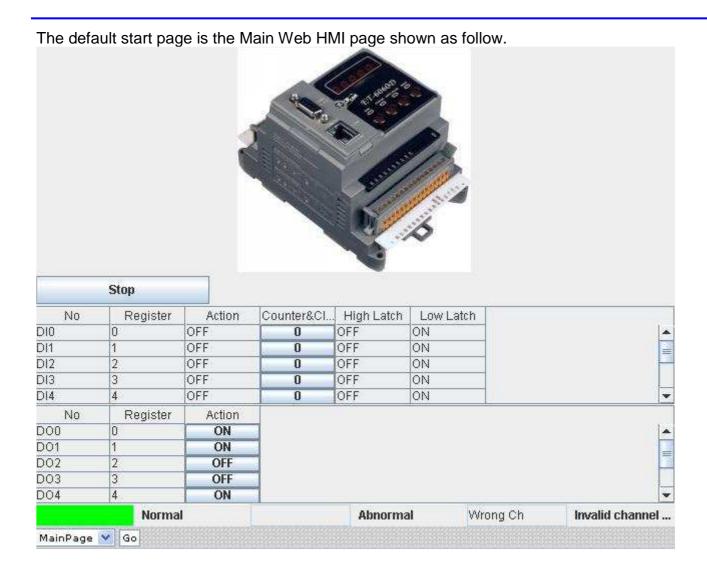


## **3.4.2** Web HMI

The first page displayed in the client Web browser will be the page that is defined by clicking the "Set as Start Page" checkbox on the "Page properties" area of the "Web page configuration" page in the "Web Editing" section of the Main Menu tree.

When the "Web HMI" link in the "Web HMI" section of the Main Menu tree is first clicked, a window will be displayed requesting you to input a valid user name and password, as shown below..





The Main Web HMI page shows all the components of the ET-6000. For example, the Main Web HMI page for an ET-6052 module will display the 8 DO and 14 DI components.

Table 3-6 Main Web HMI Page - Table 1

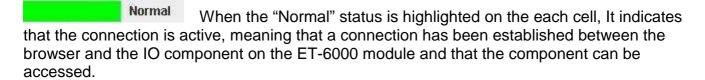
Title Name	Description	Notes
No.	The Component type and address	
Register	The Register address	
Action	DI: ON (1), OFF (0)	
Counter & Clear	DI Low Speed Counter, 0~65535	Press the button to clear the counter
High Latch	DI High Latch Status: Unlatched (0), latched(1)	
Low Latch	DI Low Latch Status: Unlatched (0), latched(1)	

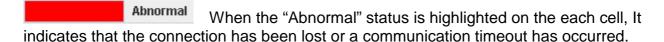
**Table 3-7** Main Web HMI Page – Table 2

Title Name	Description	Notes
No.	The Component type and address	
Register	The Register address	
Action	DO: ON (1), OFF (0)	
	AO: A numeral of Integer or float	

### **Connection Status:**

The status indicates the connection status of the IO component on ET-6000 module defined on the cell of IO channel and Modbus register mapping table.





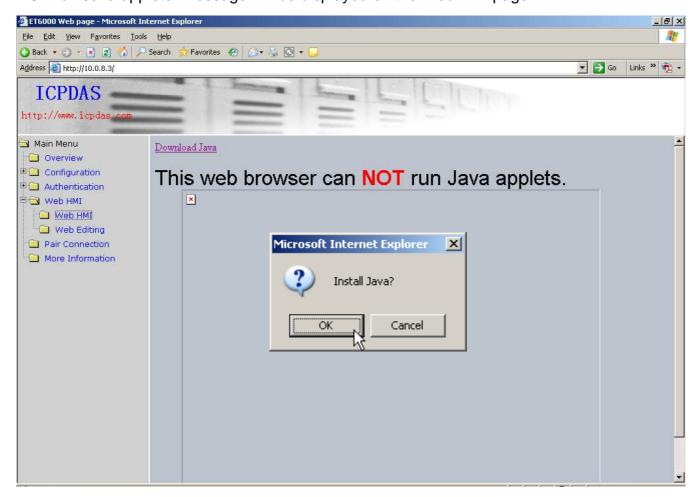
Wrong Ch Invalid channel ... Indicates that the defined channel is invalid, and is only applicable to the "Web Editing" or "Pair connection" pages.

The color of the cells in the table shown on the Web page below have turned red, indicating that the connection to the module has failed.



### Java Web page cannot be RUN

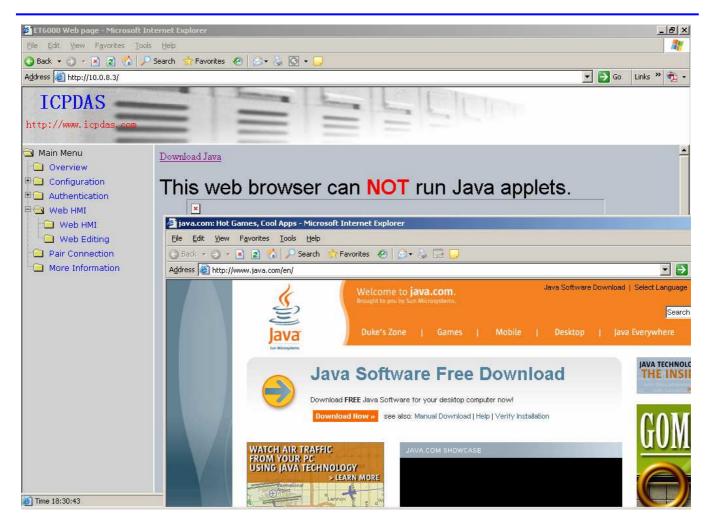
If your Web browser isn't JAVA enabled, a message notifying you that your Web browser can NOT run Java applets" message will be displayed on the Web HMI page.



Depending on the type of Web browser, a dialog box will appear asking whether you wish to install Java or not. (Refer to the figure below)



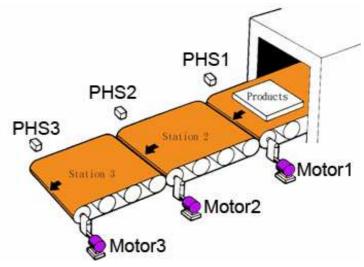
If you click "OK", a new browser window will be opened linking to the http://www.java.com web site to enable you to install Java.



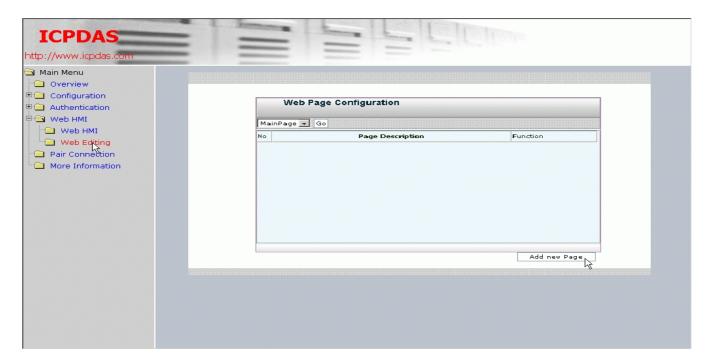
To test whether ava is installed or not, visit http://java.com/en/download/installed.jsp. Please refer to **Appendix F** for more details regarding JAVA installation.

#### An example of how to create a Web Editing Page

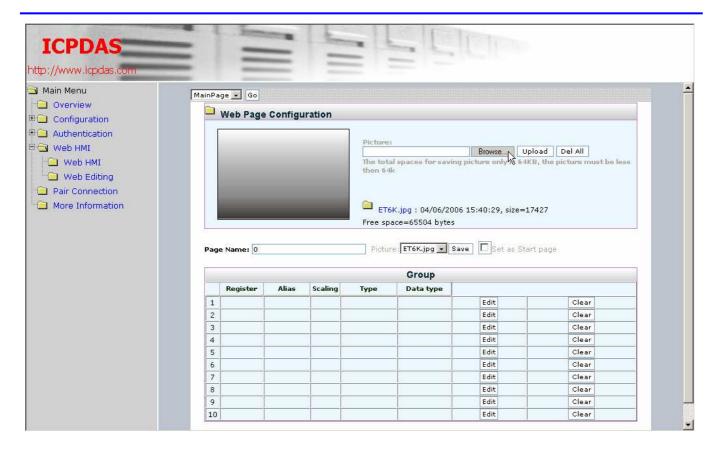
Create a Web page to monitor the I/O of the conveyer system shown below. The I/O system contains 3 photo sensors that are used to detect the products, and 3 switches that are used to turn the conveyer motor on and off.



Click the "Web Editing" link in the "Web HMI" section of the Main Menu tree and the "Web page Configuration" window will be displayed on the right hand of the browser windows. Click the "Add new Page" button to create a new editing page.

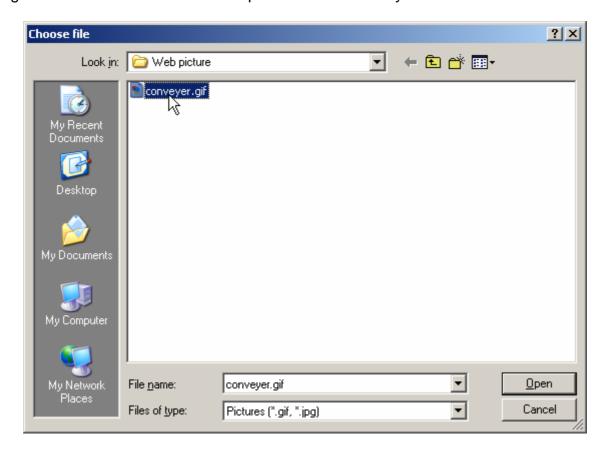


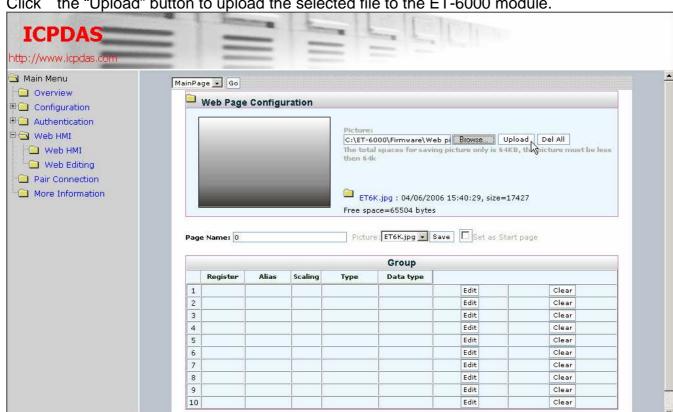
The first ghing to do is to upload an image file to the ET-6000 module.. Click the "Browse" button to locate the file (.jpg, .gif, .bmp) on your system.



Navigate to the required directory and select the appropriate image file. "conveyer.gif" is selected in this example.

Highlight the file name and Click the "Open" button to make your selection.

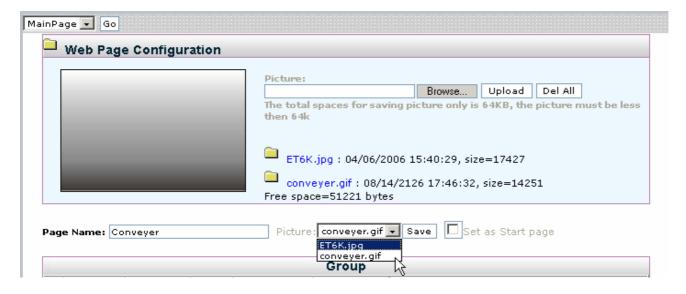


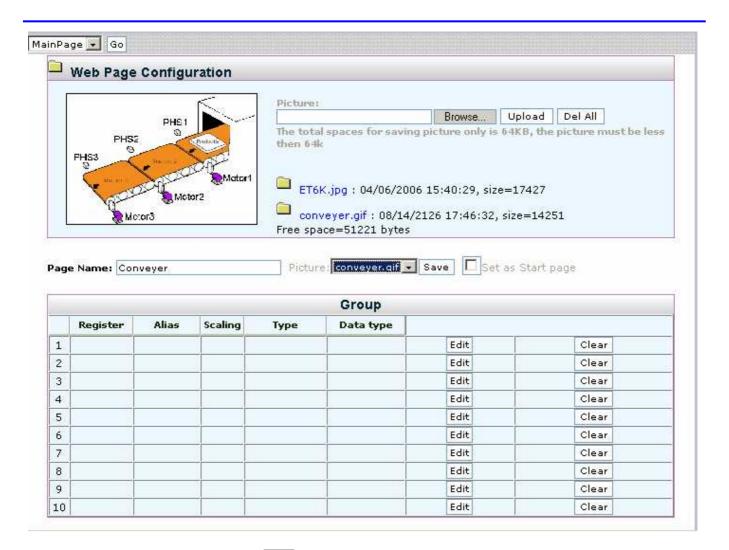


the "Upload" button to upload the selected file to the ET-6000 module.

After the upload is completed, the "conveyer.gif" file should now be listed in the file tree and also in the image list box.

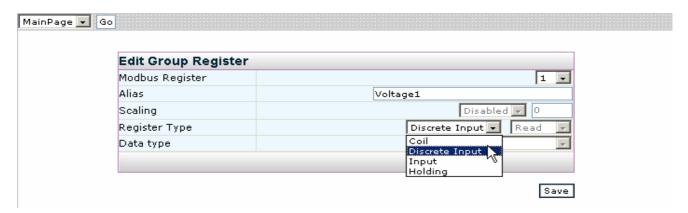
- 1. Enter the page name "Conveyer" to the "Page Name" text field.
- 2. Select the "conveyer.gif" file from the image list box (the image will be shown in the Preview window)

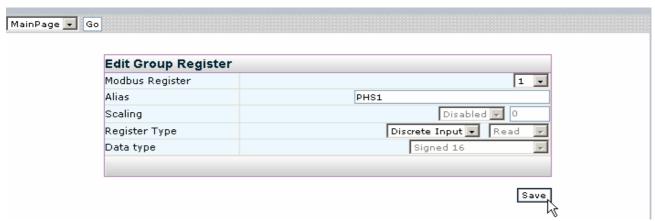




To add a register item, click the Edit button in the first row of the "Group" table and the "Edit Group Register" window will be displayed.

Add a new DI item using the Register Address 1, then select Discrete Input as the register type and enter "PHS1" as the alias. Refer to the following two diagrams as an example, then Press button to save the information on this page.

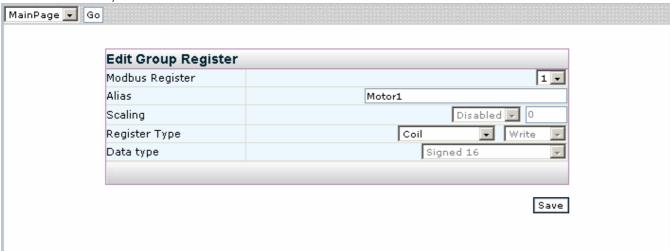




The new register item will now be displayed in the "Group" table.

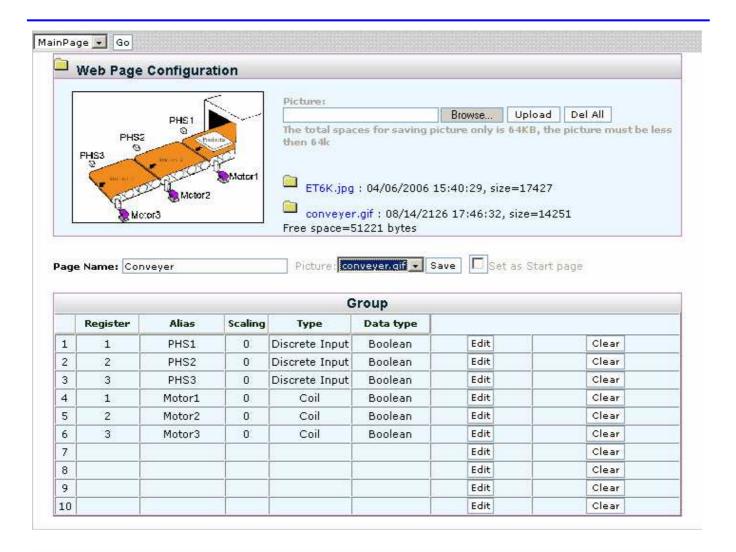
	Group						
	Register	Alias	Scaling	Туре	Data type		
1	1	PHS1	0	Discrete Input	Boolean	Edit	Clear
2						Edit	Clear
3						Edit	Clear
4						Edit	Clear
5						Edit	Clear
6						Edit	Clear
7						Edit	Clear
8						Edit	Clear
9						Edit	Clear
10						Edit	Clear

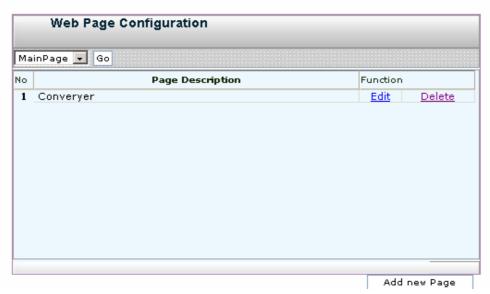
Add a DO register item by clicking on the Edit button on the second row of the "group" table then selecting the Register Address 1, select "Coil" as the Register type and enter the alias name "Motor 1", as shown below..



Repeat the steps above to add the other items, in this example, there are 3 DI items and 3 DO items.

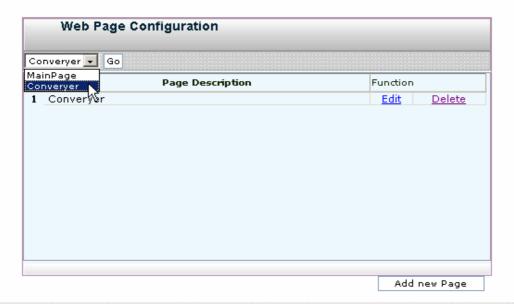
After all required register items have been added, Press save button to save this editing page.

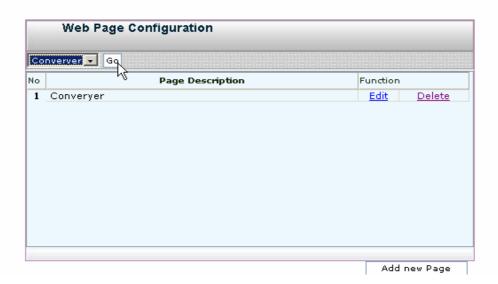




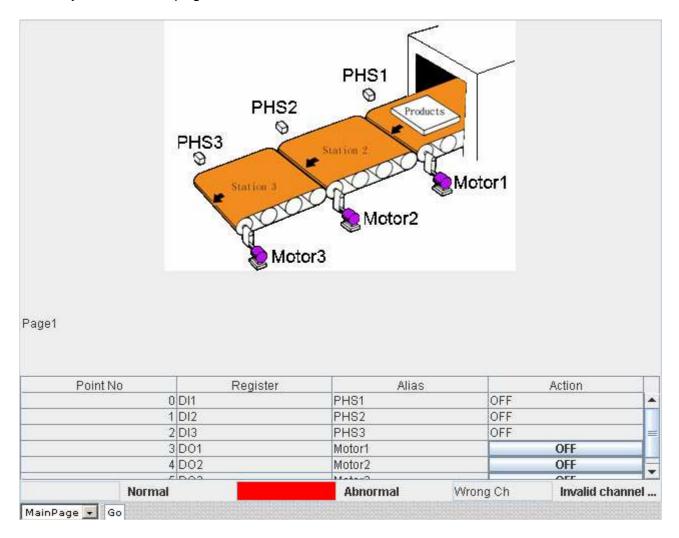
An editing page named as "Conveyer" has added to the list box on the top left-hand side of the "Web Page Configuration" window.

Select the "Conveyer" item and click Go button to browse to the "Conveyer" Web HMI page.





The "conveyer.gif" image file and all register items should now will be displayed on the "Conveyer" Web HMI page.





#### Note:

It is recommended that you check whether the browser is JAVA enabled before browsing the Web HMI. If Java is not installed, please refer to **Appendix F** for details of how to install JAVA.

## 3.5 I/O Pair Connection

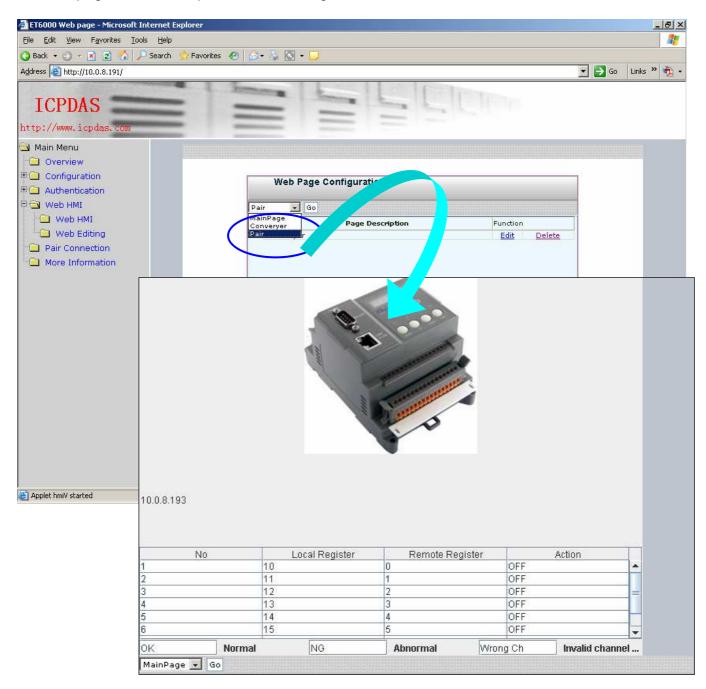
The function is used to make a DI to DO pair through the Ethernet. The communication is based on Modbus/TCP. Once the configuration is done, the ET-6000 can poll Remote DI status and then write to a local DO device constantly in the background.

Modbus Settings					
Modbus port	502				
✓ I/O Pair connection					
Remote IP Address	10.0.9.152		Remote TCP Port	502	
Connection Timeout	1000	ms	Reconnect Interval	5000	ms
Remote Net ID	1		Scan Time	1000	ms
Access Type	DO				
Local DO Base Address	0		Remote DI Base Address	0	
I/O Count	8		Communication Timeout	500	ms
Access Type	AO				
Local DO Base Address	0		Remote DI Base Address	0	
I/O Count	0		Communication Timeout	0	ms
Submit					

Table 3-8 I/O Pair Connection Settings

Settings	Description	Range	Default
I/O Pair	Enable/Disable I/O pair connection	Enable, Disable	Disable
connection			
Remote IP	IP address of remote device	0~ 42949672965 ms	0
Remote TCP port	TCP listen port of remote device	0~65535	502
Remote Net ID	Modbus Net ID of remote device	0~255	1
Connection	Timeout to build a connection.	0~ 42949672965 ms	5000 ms
timeout			
Reconnect	Continue to attempt to reconnect to the	0~ 42949672965 ms	10000 ms
interval	remote module once the connection is		
	lost until the reconnection time has		
	expired.		
Scan time	Time period to establish the	0~ 42949672965 ms	1000 ms
	communication		
Communication	Timeout for Modbus/TCP	0~ 42949672965 ms	500 ms
timeout	communication.		
Local DO base	DO base address of local DO register	Depend on the ET-	0
address	that will be mapped to remote DI device.	6000	
Remote DI base	DI base address of remote DI device	Depend on remote	0
address	that will be mapped to local DO register.	device	
I/O count	I/O count mapped from the base	1~255	0
	address		

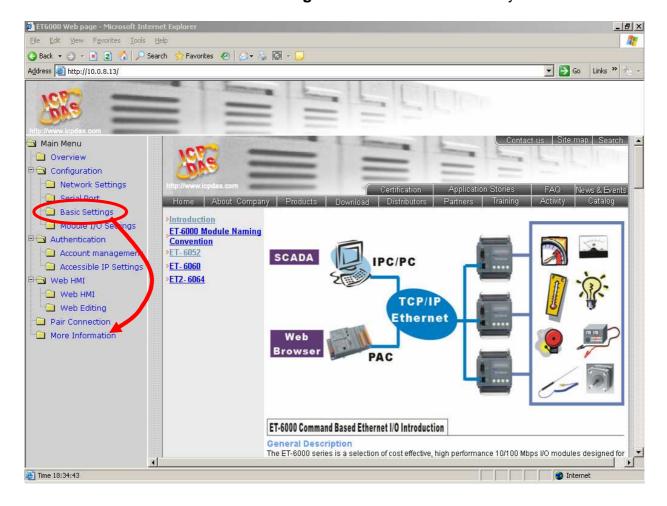
When the configuration is done, you can click "Pair" from "web page configuration" to open another page to view the pair connection again.



## 3.6 More Information

The More Information menu item is a Web page URL, and can be used to provide a link to a web site containing additional information about the product maker, detailed specs etc. The Default More Information URL is: http://www.icpdas.com/products/Remote\_IO/et-6000/et-6000\_introduction.htm

Please refer to Sec. 3.2.3 Basic Settings for details of how to modify the URL.



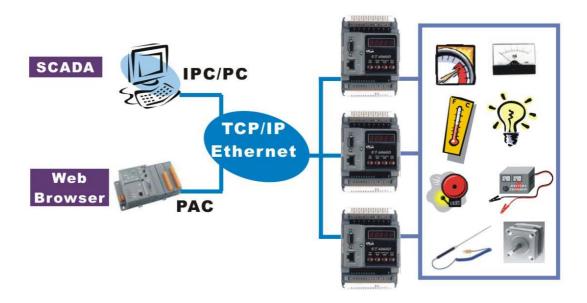
# 4. How to access ET-6000?

ET-6000 series is designed as remote I/O module that can be accessed via either an Ethernet or Serial interface.

### 4.1 Via an Ethernet Network

Ethernet is an extremely popular networking format that already exists for most applications, either for use with local networks or for connecting to the Internet. A host PC or other devices on the LAN or WAN can be connected to access the ET-6000 module or control the devices attaced on the COM1 of the ET-6000 module.

The Host PC is able to access the ET-6000 module using the Modbus/TCP.



#### Modbus/TCP Protocol:

The Modbus/TCP protocol is a variant of the standard Modbus protocol. It was developed in 1999 to allow access to Ethernet devices by Internet community.

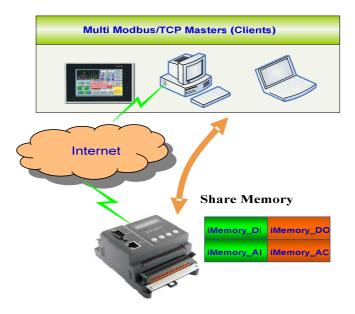
# 4.2 Using the Modbus protocol

### 4.2.1 Introduction

MODBUS is a master-slave bus system in which only one device (the master) actively starts a transaction (query). The passive device (the slave) then sends a response. Most SCADA Supervisor Control And Data Acuisition and HMI software can easily integrate serial devices via the Modbus protocol, such as Citect, ICONICS, iFIX, InduSoft, Intouch, Entivity Studio, Entivity Live, Entivity VLC, Trace Mode, Wizcon, Wonderware, etc.

**The ET-6000** controller includes the Modbus/TCP protocol, which is a variation of the Modbus protocol that was developed in 1999 to allow the Internet community to access Ethernet devices.

Modbus address for Modbus/TCP client access.



The ET-6000 series supports multi-operation modes related to the Modbus applications. Refer to Appendix C: Modbus Protocol to select the appropriate mode for your requirements.

# **4.2.2** Function Codes Supported

Modbus function codes are different both the analog and digital types.

**Table 4-1 ET-6000 Modbus Function Code** 

Modbus Command (Hex)	Protocol Description
01	Read multiple coils status for DO
02	Read multiple input discrete for DI
03	Read multiple registers for AO
04	Read multiple input registers for AI
05	Write single coil for DO
06	Write single register for AO
0F	Force multiple coils for DO
10	Write multiple registers for AO

# 4.2.3 Modbus Register address table

In addition to the Web Configuration Page, the custom's software that supports Modbus protocol can be used to issue Modbus command to the ET-6000 module.

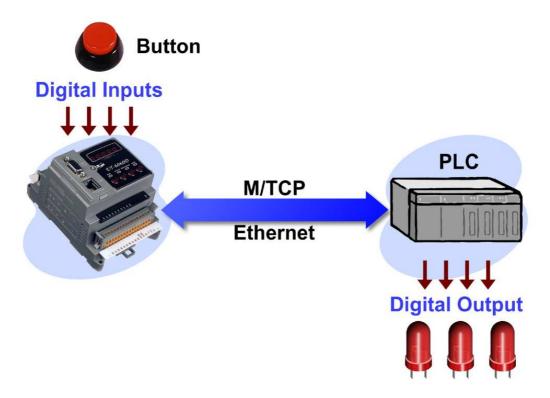
For more details regarding the Modbus address of the ET-6000 module, please refer to Appendix D: Modbus Register Table.



# 5.I/O Pair Connection

The function is used to make a DI to DO pair through the Ethernet. The communication is based on Modbus/TCP. Once the configuration is done, the ET-6000 can poll remote DI status and then write to a local DO device constantly in the background.

Using the function, remote DI status can be transmitted to local DO device over the Ethernet without any programming skill.



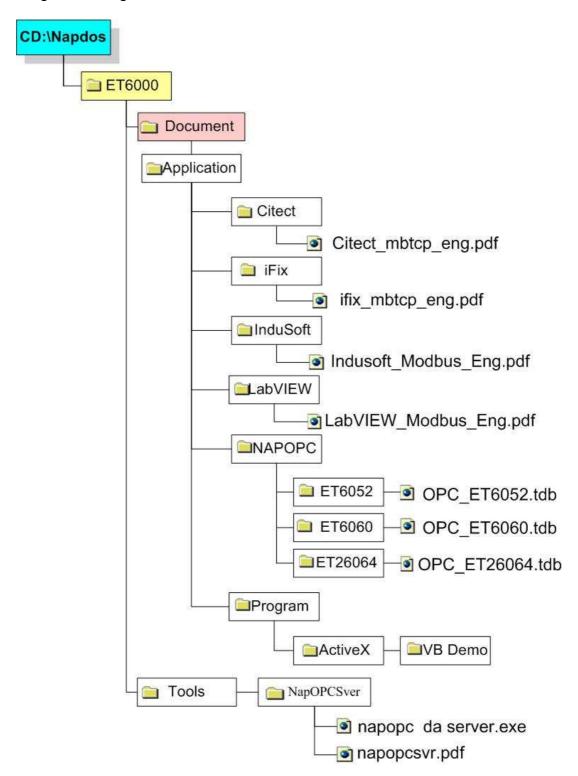
Please refer to **Sec. 3.5 Pair Connection** for more details regarding the configuration of the I/O pair connection.



# 6. Software Development Application

### 6.1 Location of documents and software

The following diagram illustrates the location of all documents and software related to Modbus applications for ET-6000 series modules. The relevant file can quickly be located by referring to the diagram.





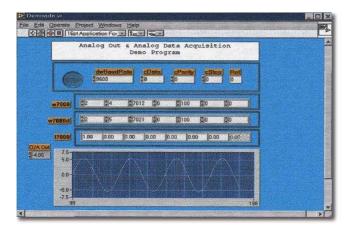
### **Chapter 6** Software Development Application

There are a variety of applications that conform to the the Modbus protocol, such as ActiveX, Labview, Indusoft, OPC Server, etc. are available for use on the/a Host PC. These applications can be used to access ET-6000 series module from the Host PC and contain a number of helpful free demo programs and documents, which can be found on the CD included in the shipping package, or can be downloaded from the ICP DAS web site or FTP site.

When planning the development of a system, appropriate software solutions should be chosen to suit different situations. The diagram (previous page) shows the relation between the software solutions. Refer to the diagram to determine a solution that meets your requirements.

### **Chapter 6** Software Development Application

### 6.2 LabVIEW



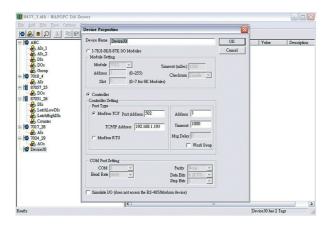
LabVIEW is the best way to acquire, analyze, and present data. LabVIEW delivers a graphical development environment that can be used to quickly build data acquisition quickly, instrumentation and control systems, boosting productivity and saving development time. With LabVIEW, it is possible to quickly create user interfaces that enable interactive control of software systems. To specify your system functionality, simply assemble block diagram – a natural design notation for scientists and engineers.

The document containing the detailed instructions for linking to the ET-6000 using the Modbus protocol is located on the shipped CD:

\NAPDOS\ET6000\Document\Application\LabVIEW or ftp://ftp.icpdas.com/pub/cd/6000cd/napdos/et6000/document/application/labview



# 7. OPC Server



### 7.1 Introduction

OPC (OLE for Process Control) is the first standard resulting from the collaboration of a number of leading worldwide automation suppliers working in cooperation with Microsoft. Originally based on Microsoft's OLE COM (Component Object Model) and DCOM (Distributed Component Object Model) technologies, the specification defines a standard set of objects, interfaces and methods for use in process control and manufacturing automation applications to facilitate interoperability.

There are many different mechanisms provided by various vendors that allow access to a variety of devices via specific applications. However, if an OPC server is provided for the device, other applications will be able to access the OPC Server via the OPC interface.

# 7.2 Procedure for using the OPC server

Step 1: Read the following documents

**Readme.txt:** contains the latest important information, including:

A list of files contained on the shipped CD

Reversion.txt: contains the revision history information, including

- Bugs
- New modules supported

Step 2: Install the OPC server by executing:

CD:\NAPDOS\ET6000\Tools\Napopcsvr\NapOPCServer.exe

Note: If there is an older version of the Nap OPC Server installed on the PC, and must be uninstalled before installing the new version.

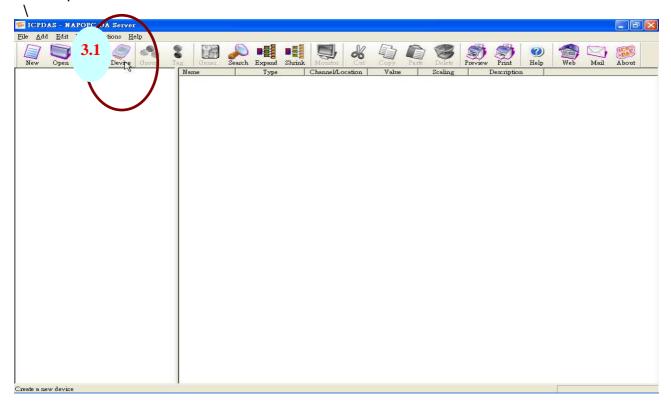
Step 3: Read the manuals describing how to begin.

The NapOPCSvr.pdf is the user's manual describing how to use the OPC server

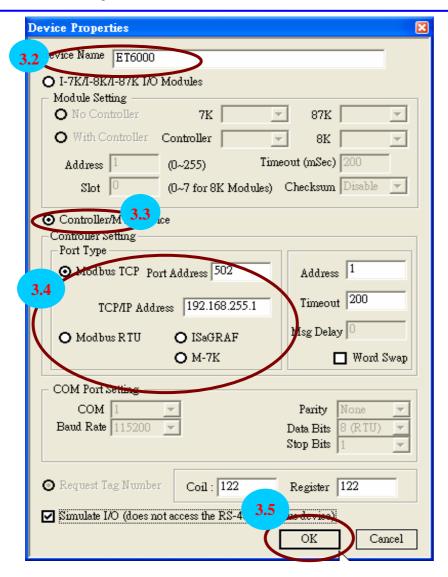
## 7.3 OPC Server Example using MODBUS protocol

The following is an example of accessing Digital input and output values from an ET-6000

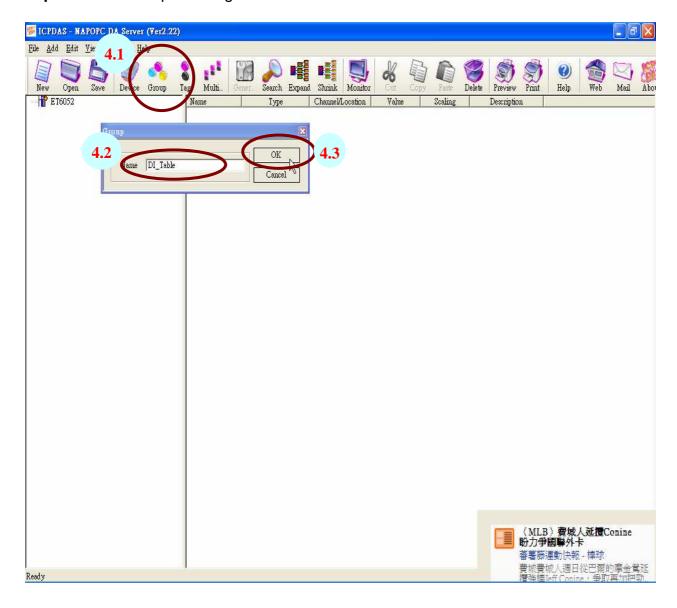
- **Step 1**: Connect the ET-6000 controller (refer to **Sec. 1.4.2**) and configure its network settings (IP, Mask and Gateway refer to **Sec. 2.1**)
- Step 2: Run the OPC server
- **Step 3**: Add/Create a new device and to search for I/O modules using Modbus /TCP protocol



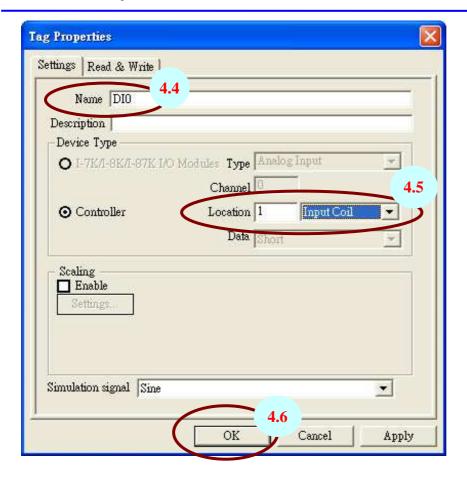


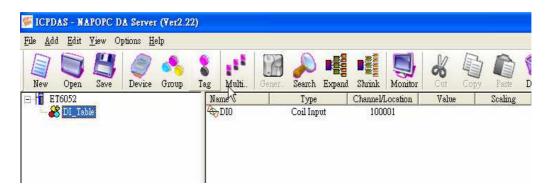


### Step 4: New a Group and Tag

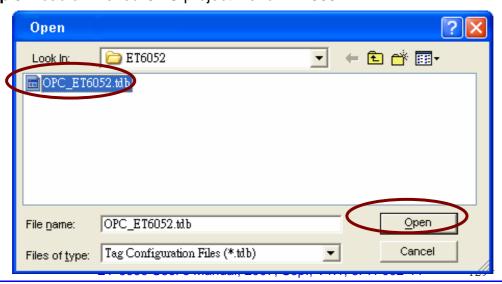




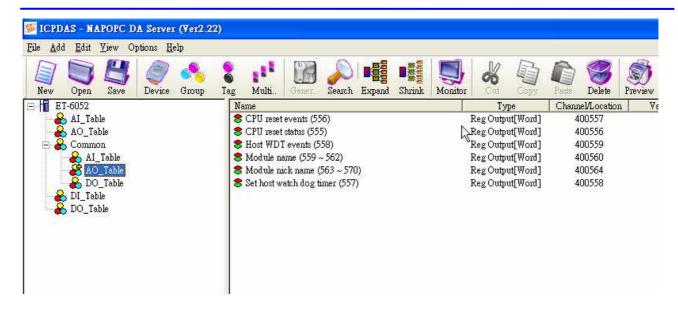




Step 5: Load a finished OPC project file for ET-6052







#### Note:

- 1. The OPC file for the ET-6052 is located at:
  - CD: NAPDOS\ET6000\Document\Application\NAPOPC\ET-6052
  - The OPC file for ET-6060 is located at:
  - CD: NAPDOS\ET6000\Document\Application\NAPOPC\ET-6060
- 2. The OPC file for ET2-6064 is located at:
  - CD: NAPDOS\ET6000\Document\Application\NAPOPC\ET2-6064



# 8.SCADA

**SCADA** stands for Supervisor Control And Data Acqusition. It is a production automation and control system based on PCs

SCADA is wildly used in many fields e.g. power generation, water systems, the oil industry, chemistry, the automobile industry. Different fields require different functions, but they all have the common features:

- · Graphic interface
- · Process mimicing
- Real time and historic trend data
- Alarm system
- Data acquisition and recording
- Data analysis
- Report generator

#### Accessing ET-6000 devices using SCADA software

SCADA software is able to access ET-6000 devices using Modbus communication protocols, and can communicate without the need for other software drivers.

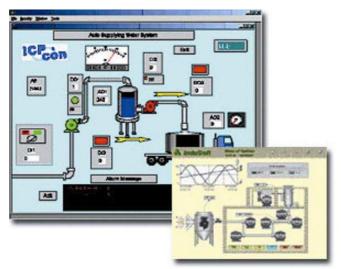
#### Famous SCADA software:

Citect, ICONICS, iFIX, InduSoft, Intouch, Entivity Studio, Entivity Live, Entivity VLC, Trace Mode, Wizcon, Wonderware ... etc

In the following sections 3 popular brands of SCADA software are introduced together with the detailed instructions in how use them to communicate with ET-6000 series module using the Modbus/TCP protocol.



### 8.1 Indusoft



InduSoft Web Studio is a powerful, integrated collection of automation tools that includes all the building blocks needed to develop modern Human Machine Interfaces (HMI), Supervisory Control and Data Acquisition (SCADA) systems, and embedded instrumentation and control applications. InduSoft Web Studio's application runs in native Windows NT, 2000, XP, CE and CE .NET environments and conforms to industry standards such as Microsoft .NET, OPC, DDE, ODBC, XML, and ActiveX.

The document containing detailed instructions for linking to the ET-6000 module using the Modbus protocol is located on the shipped CD:

\NAPDOS\ET6000\Document\Application\InduSoft or ftp://ftp.icpdas.com/pub/cd/6000cd/napdos/et6000/document/application/indusoft/



## 8.2 Citect



CitectSCADA is a fully integrated Human Machine Interface (HMI) / SCADA solution that enables users to increase return on assets by delivering a highly scalable, reliable control and monitoring system. Easy-to-use configuration tools and powerful features enable rapid development and deployment of solutions for any size application.

The document containing detailed instructions for linking to the ET-6000 module using the Modbus protocol is located on the shipped CD:

\NAPDOS\ET6000\Document\Application\Citect or ftp://ftp.icpdas.com/pub/cd/6000cd/napdos/et6000/document/application/citect/

# Chapter 8 SCADA

## 8.3 iFix



The document containing detailed instructions for linking to the ET-6000 module using the Modbus protocol is located on the shipped CD:

\NAPDOS\ET6000\Document\Application\iFix or

ftp://ftp.icpdas.com/pub/cd/6000cd/napdos/et6000/document/application/ifix/



# 9. Console Mode

Communication with the ET-6000 can be performed via either the Ethernet or COM1 using Hyper-terminal, Telnet or the 7188xw utility, etc.

#### Console Commands

Valid commands in console mode are as follows:

- 1. Help
- 2. Reset
- 3. Default
- 4. Setip/lp
- 5. setmask/mask
- 6. setgateway/gateway
- 7. seteid/mac
- 8. com1
- 9. commode
- 10. web

All commands are NOT case sensitive.

#### 1. Help

Use the Help command to access information related to the console commands. If you enter the 'help' command without any parameters, the console will display all valid commands on the screen. Such as:

```
ET-6K>help
?,help [command]: Help
reset
default
ip,setip
mask,setmask
gateway,setgateway
mac,seteid
com1 [baudrate][databit][parity][stopbit]
```

To access help for a specific command, enter help <command name>. Such as:

```
ET-6K>help ip ip(MyIP) ip1.ip2.ip3.ip4
```

#### 2. Reset



Use this command to reset the ET-6000.

#### 3. Default

Use this command to restore the settings to the factory default

Format: default [mode]

mode:

- 0: All settings. Set all settings to the factory default.
- 1: Configuration. It includes Ethernet, Serial Port, Basic and Module I/O Settings.
- 2: Authentication. It includes Account and IP filter settings.
- 3: Web HMI. Set the Web HMI settings to the factory default.
- 4: Pair Connection. Set the Pair Connection settings to the factory default

Refer to "Load All Setup Default" in Sec. 3.2.3 Basic Settings for more details.

#### 4. Setip/lp

This function is used to change the IP address of the ET-6000.

Format: setip ip1.ip2.ip3.ip4

ip1.ip2.ip3.ip4: This is a 32-bit address, such as 192.168.255.1

#### 5. setmask/mask

This function is used to change the Mask address of the ET-6000.

Format: mask m1.m2.m3.m4

m1.m2.m3.m4: This is a 32-bit address, such as 255.255.255.0

#### 6. setgateway/gateway

This function is used to change the gateway address of the ET-6000.

Format: gateway ip1.ip2.ip3.ip4

ip1.ip2.ip3.ip4: This is a 32-bit address, such as 192.168.0.1

#### 7. seteid/mac

This function is used to read the Mask address of the ET-6000, and isn't able to be changed.

Format: Seteid(mac)

Returns the MAC address, such as

MAC=00:0d:e0:a3:dd:af

#### 8. com1

This command is used to configure the Baud Rate and Data format of COM1.

#### Format:

com1 [baud] [databit] [parity] [stopbit]

baud: 300, 600, 1200, 2400, 4800, 9600, 19200, 38400, 57600, 115200 bps

databit: 7, 8

parity: 0 (None), 1 (Even), 2 (Odd)

stopbit: 1, 2

#### 9. commode

This function is used to change the operation mode of COM1.

ET-6000 User's Manual, 2007, Sep., V1.1, 6PH-002-11-----136<sup>1</sup>



Format: commode [mode]

mode:

0 (Vxcomm)

1 (ModbusRTU)

2 (Program)

3 (UPLink)

4 (Debug)

5 (Console)

Refer to **Sec. 3.2.2 Serial Port Settings** for details of how to change the settings, and refer to **Appendix C: Modbus Protocol** for more information.

#### 10. web

This function is used to enable/disable the Web Server on the ET-6000.

Format: web [mode]

mode:

0 (Disable), Disables the Web server.

1 (Enable), Enables the Web server.

If you enter the command above without any other parameters the console will show the current settings the on screen. Such as

ET-6K>ip

IP=10.0.8.149

ET-6K>mask

Mask=255.255.255.0

ET-6K>gateway

Gateway=10.0.8.254

ET-6K>mac

MAC=0:d:e0:a3:dd:af

ET-6K>

#### Communication Interface

1. RS232

Set the COM port operation mode to 5. Refer to **Sec 3.2.2 Serial port settings** for more details.



Item	Parameters	Current setting
COM Port	COM1 🕶	1
BaudRate	9600 v bps	9600
Data Bit	○ 5 bits ○ 6 bits ○ 7 bits ● 8 bits	8
Parity	● None ○ Even ○ Odd ○ Mark ○ Space	None
Stop Bit	⊙ 1 bits ○ 2 bits	1
Checksum	O True ⊙ False	1
operation 10de	2 • 0 (Vxcomm),1 (ModbusRTU),2 (Program),3 (UPLink),4 (Debug), 5(Console)	2
Net ID	1 Modbus Station Number	1
Time Out	200 ms (5~32767)	200
Station per COM Port	10 Stations	10

Run the "7188xw.exe" utility to connect to the ET-6000 to open the console windows.

```
7188XW 1.26 [COM1:115200,N,8,1],FC=0,CTS=0, DIR=C:\Documents and Settings\sean
C:\Documents and Settings\sean>7188xw
7188x for WIN32 version 1.26 (10/19/2004)[By ICPDAS. Tim.]
[Begin Key Thread...]Current set: Use COM1 115200,N,8,1
AutoRun:
Autodownload files: None
Current work directory="C:\Documents and Settings\sean" original baudrate = 115200!
now baudrate = 115200!
ET-6K>help
?,help [command]: Help
reset
default
ip,setip
mask,setmask
gateway,setgateway
mac,seteid
com1 [baudrate][databit][parity][stopbit]
commode
web
ET-6K>
```

The console will initially display the "ET-6K>" prompt in the Serial console mode. Enter the "help" command to view all commands.



2. Ethernet : Telnet (Unavailable)



# **10.** Troubleshooting and Technical Support

This chapter discusses methods of quickly diagnosing and fixing problems or errors without having to contact ICPDAS.

When troubleshooting the following problems, please make sure that the module is switched on, and confirm that the physical connections are correct (power cable, network cable and serial cable)

Note that some unexplained errors might be caused by duplicate IP addresses on the Network. Make sure that the IP address of your module is unique.

**Table 10-1** Troubleshooting

Table 10-1 Troubleshooting					
Symptom/Problem	Possible cause	Solution			
The Power LED and RUN	Internal power has failed	Return the module for			
LED doesn't light		repair.			
The DHCP LED indicator is	The Switch is placed in the	Move the switch to the			
flashing continuously.	Init position.	Normal position.			
The RUN LED indicator					
doesn't light.					
The RUN LED indicator is	The module has possibly	Reboot the module			
ON (light), but not flashing.	crashed.				
Cannot communicate via	The IP/Mask/Gateway	Change the			
the Ethernet port, but the	address isn't within the IP	IP/Mask/Gateway address			
ET-6000 is still operating.	address range of the LAN.	to match the LAN, or ask			
		the MIS administrator for			
		assistance.			
	The IP address has	Check the IP filter setting			
	restricted by the IP filter	using the Web			
	settings	configuration.			
	There are more than 30	Reboot the module.			
	TCP/IP connections. (Check				
	the Group 44444				
	information on the SMMI)				
Cannot communicate	Caused by either a cable	Change the serial port			
through RS232 port	problem, unmatched Baud	settings to match the			
	Rate or data format, etc.	requests and check the			
	(As shown on the Serial	operation mode of the COM			



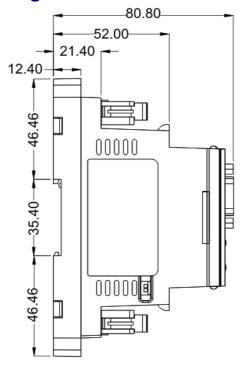
# Chapter 10 Trouble Shooting and Technical

	Port page)	port.
Able to explore the web	Port 502 has been restricted	Consult your MIS
page through port 80 using	by the firewall.	administrator for assistance.
a web browser, but the Web		
HMI and Modbus/TCP		
program cannot access the		
module through port 502.		
The Web HMI and	The Port 502 has restricted	Consult your MIS
Modbus/TCP program can	by the firewall.	administrator for assistance.
access the module through	The Web Configuration	Enable the Web
port 502, but Web browse	function has been disabled.	Configuration function using
cannot explore the web	(Shown on the Basic	either the SMMI or the
page through port 80 using	Settings page)	console.
a web browser.	The Web server TCP port	Change the TCP port to 80
	has been changed from port	or reconnect the ET-6000
	80	using the specific TCP port.
	(Shown on the Basic	
	Settings page)	

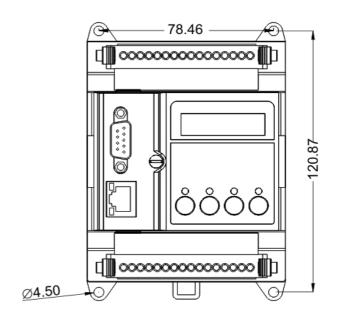


# **Appendix A: Dimensions**

# **Single Unit**

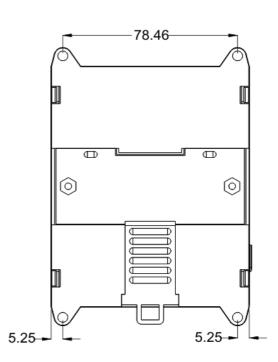


Left Side View



Front View

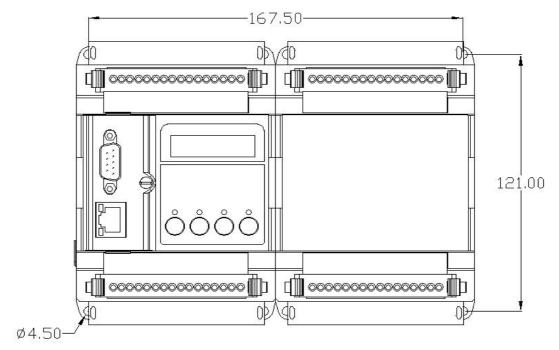
Unit: mm



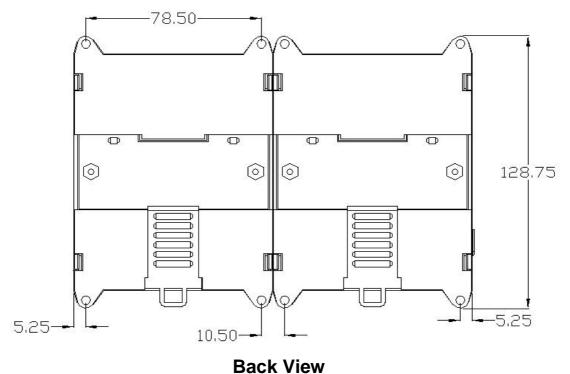
**Back View** 

# Appendix A Dimension

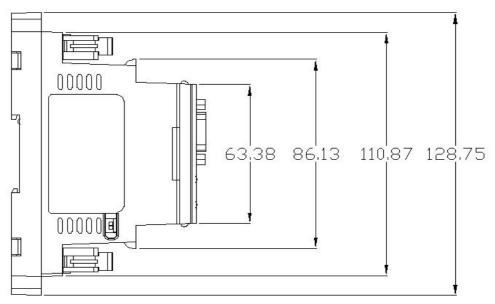
#### **Two Units**



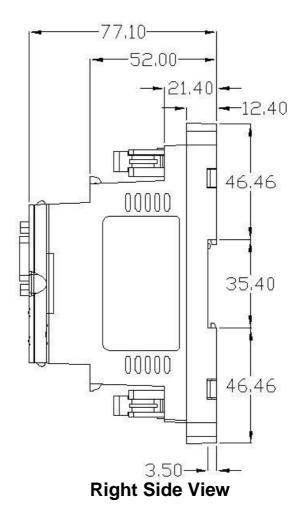
**Front View** 



## Appendix A Dimension

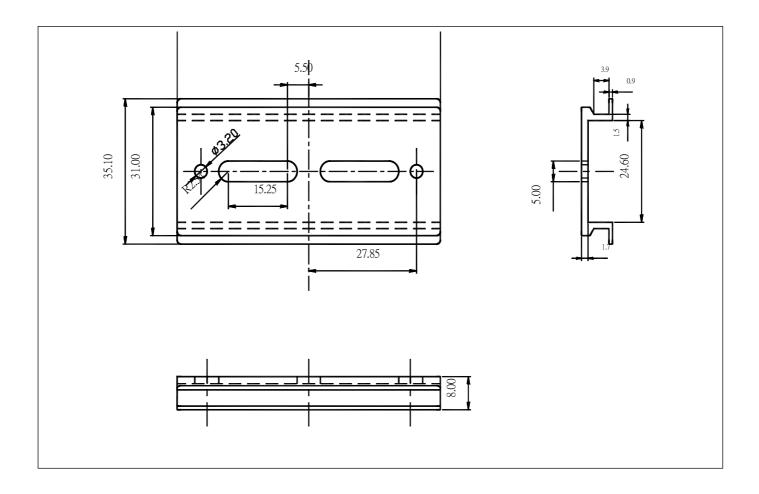


**Left Side View** 



# Appendix A Dimension

# **Wall Mount Bracket**



On occasions, ICPDAS will offer an update to the ET-7000 firmware or MiniOS7. The MiniOS7 utility is used to easily update your software to the latest version. The **MiniOS7 Utility** is used for both essential configuration and for downloading programs into the ET-7000 controller embedded in the ICPDAS MiniOS7 environment.

The **MiniOS7 Utility** program provides 3 main functions:

- Update the MiniOS7 image
- Download firmware to Flash memory
- Configure Ethernet and COM port settings

#### MiniOS7 utility location

The MiniOS7 utility is located in the

- CD:\ NAPDOS\ET6000\Tools\Tools for MiniOS7\MiniOS7\_utility folder on the enclosed CD or from
- ftp://ftp.icpdas.com/pub/cd/6000cd/napdos/et6000/tools/tools for minios7/minios7\_utility/

#### Downloading firmware to the ET-6000 controller

The download procedure is as follows:

#### **Via Serial Port**

**Step 1:** From the Windows START menu, navigate to programs/ICPDAS/MiniOS7 Utility and locate the **MiniOS7 utility'** program.

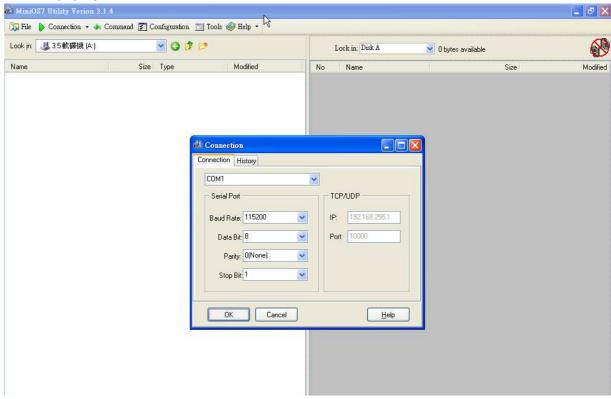


#### Note:

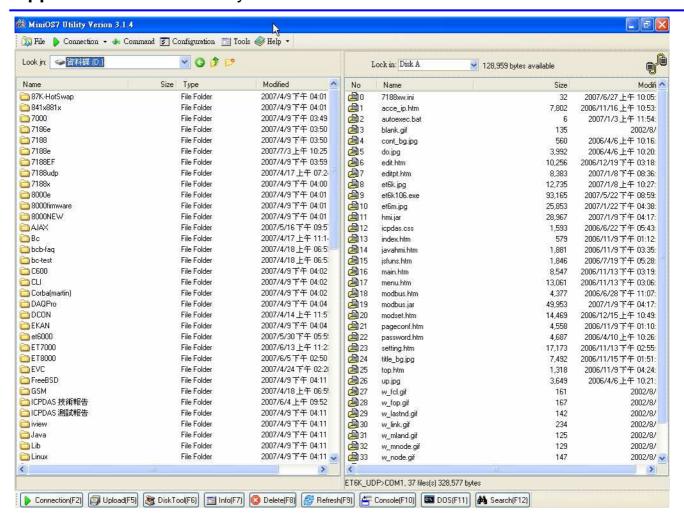
- During configuration, the Init/Normal switch is placed in the Init position.
- Return the Switch to the Normal position after updating the configuration.



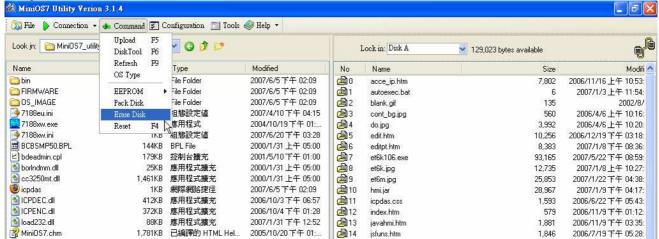
Select a valid COM port with the baud rate, data bit, parity and Stop bit shown as follows



**Step 3:** After a connection between the ET-6000 and PC has been successfully established, the following screen will be displayed. (The total files on the selected ET-6000 shows on the file list of right hand window)



**Step 4:** Click **Erase Disk** item of **Command** item of main menu.



**Step 5:** Locate the required file in the left hand window, then drag and drop this file to the ET-6000. The figure below shows that the ET-6000 firmware has been downloaded to the ET-6000 module.

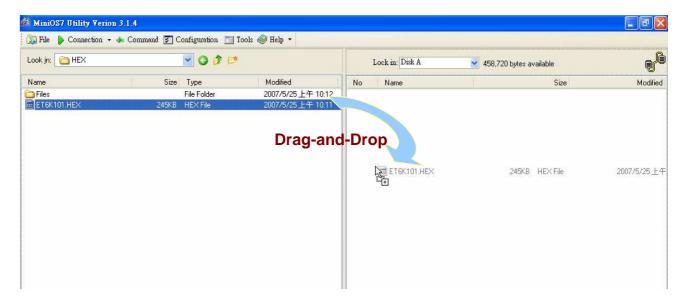


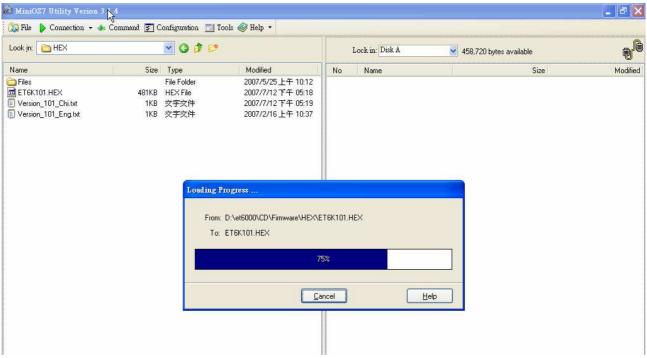
Before updating the firmware, you must delete all files existed on the ET-6000.



#### **Notes:**

- The ET-6000 firmware is a file named ET6Knnn.HEX, where 'nnn' is the version number.
- The MiniOS7 utility is only a tool for the ET-6000 series module to update its firmware, and the version of MiniOS7 utility must be V3.14 or later





The **Init/Normal** switch must be placed in the **Normal** position while using the serial port to download firmware is finished.



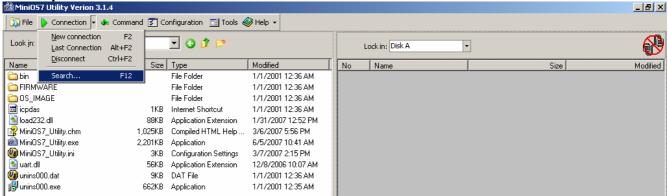
#### **Notes:**

- To select multiple files, press and hold the CTRL or SHIFT keys while making your/a selection and drag them to simultaneously download the files to ET-6000
- After completing the download, turn off the power to the ET-6000 and then turn it back ON. This will cause the program to begin running the autoexec.bat (the content of the autoexec.bat indicates which file in the ET-6000 will run after rebooting). Alternatively, click the button to execute it.
- Please refer to the MiniOS7 utility help file for more details regarding the use of the MiniOS7 utility. This file is located in the ICPDAS MiniOS7\_utility group in the 'Start' menu, or can be accessed by clicking the icon at the top of the MiniOS7 utility toolbar.

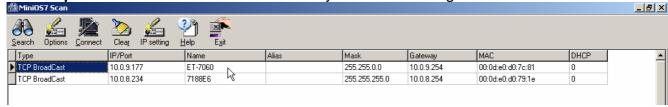
#### Via Ethernet interface

**Step 1:** From the Windows START menu, navigate to programs/ICPDAS/MiniOS7 Utility and locate the **MiniOS7 utility'** program.

**Step 2:** Click Search item on the Connect item of man menu.



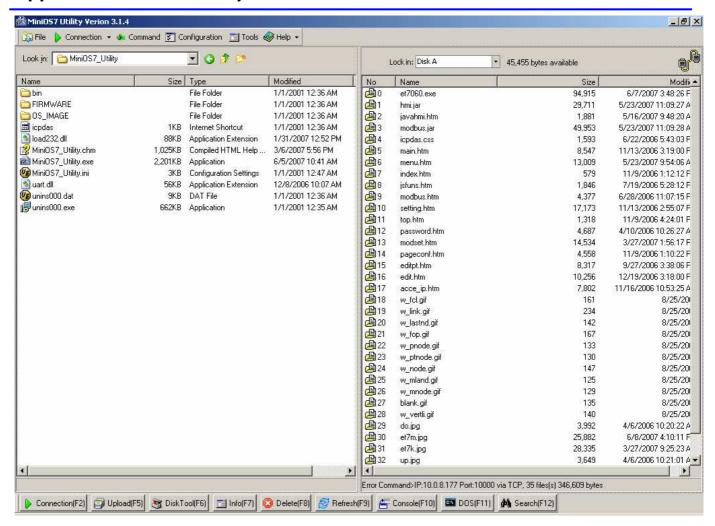
Step 3: Double click the ET-6000 which you want to configure.



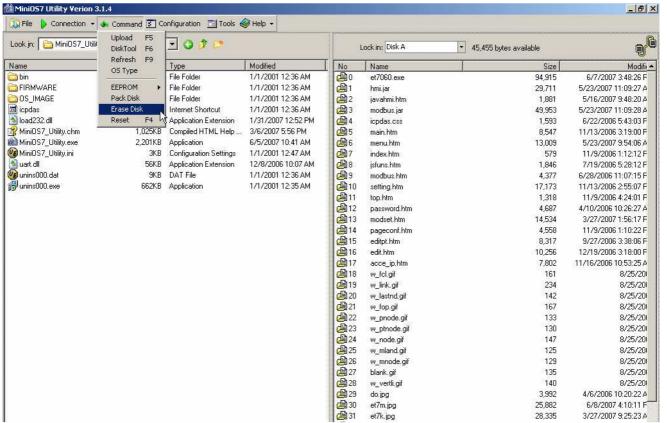
**Step 3:** After a connection between the ET-6000 and PC has been successfully established, the following screen will be displayed. (The total files on the selected ET-6000 shows on the file list of right hand window)



The **Init/Normal** switch is always placed in the **Normal** position while using the Ethernet port to download firmware



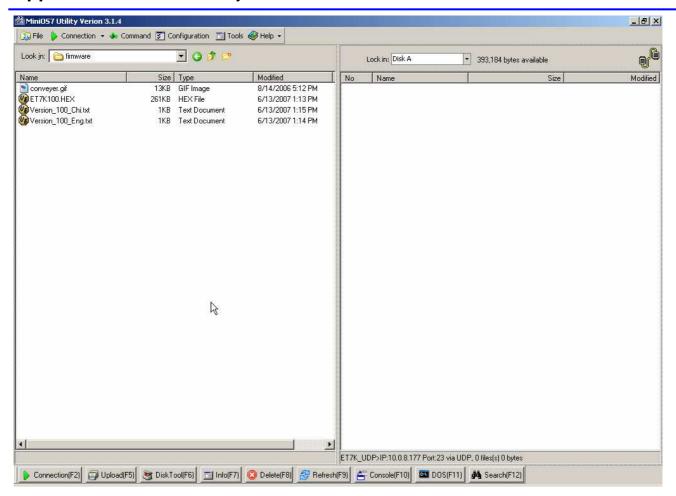
**Step 5:** Click **Erase Disk** item of **Command** item of main menu.



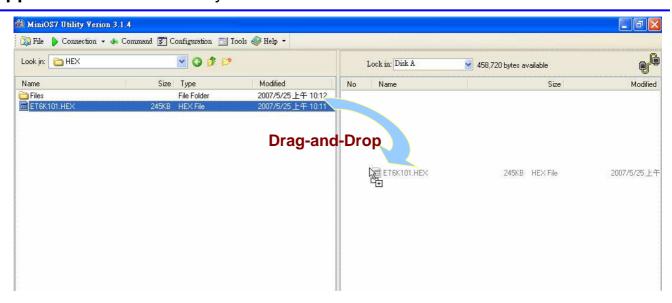
Step 6: A Confirm dialog notices whether all files will be deleted or not.

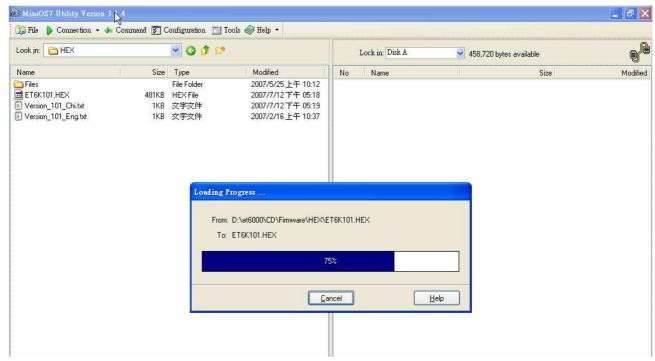


If Press "Yes" button, all files on ET-6000 will be deleted. Please refer to the picture below.



**Step 5:** Locate the required file in the left hand window, then drag and drop this file to the ET-6000. The figure below shows that the ET-6000 firmware has been downloaded to the ET-6000 module.



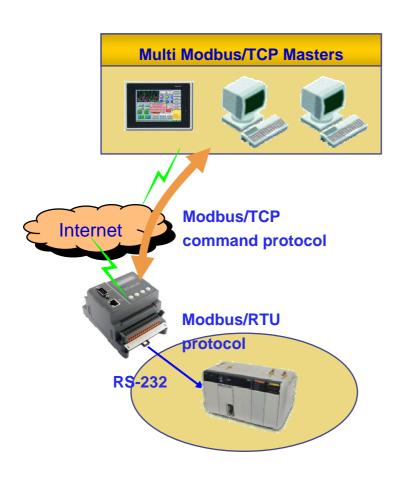




The Modbus Protocol provides client/server communication between devices connected on different types of buses or networks. Modbus is capable to run full-duplex RS232 lines, and Ethernet & TCP/IP solutions. The Internet community is able to access MODBUS at a reserved system port 502 on the TCP/IP stack.

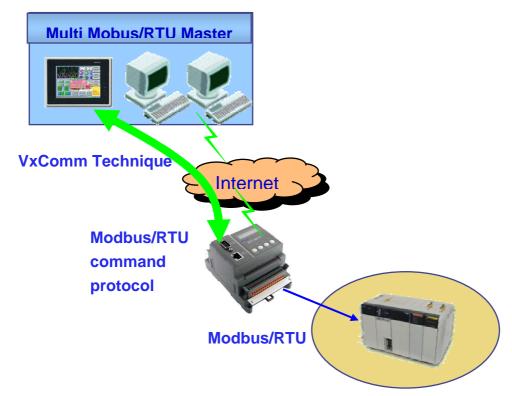
#### **♦** Modbus/TCP to Modbus/RTU protocol converter

The ET-6000 controller can be used as a single Modbus/TCP to multi-Modbus/RTU converter simply by configuring the device and then setting connection between SCADA, HMI software and the ET-6000 module.



#### ♠ Modbus/RTU protocol using the VxComm technique (unavailable)

In combination with the VxComm technique, the ET-6000 controller is also able to link to serial devices supported by the Modbus/RTU without changing the original Modbus/RTU program on the host PC.



#### Adjust system settings

The Modbus station number is a very important parameter for ET-6000. It is used to recognize different Modbus stations. But the ET-6000 does not have any hardware design such as dip-switch or jump allowing you to set the Modbus station number (or called NetID). You must set the parameters regarding to Modbus station number by Web page. System settings include the following:

#### **Net ID** (Default = 1):

If the Modbus station number in a Modbus/TCP request (from PC or HMI) matches the Net ID, the request is passed to the Modbus kernel. Then Modbus kernel program will then respond and send the internal registers to the Modbus/TCP client (PC or HMI). The content of all other registers is zero.

#### **Stations per COM port** (Default = 10):

This value is used to decide how many Modbus/RTU stations can add on one ET-6000 COM port for control. That also means the value can decide which COM the Modbus/TCP request will be passed to. The formula is as follows:

COM = station number in Modbus/TCP request / Stations per COM port

#### Example 1:

Stations per COM port = 10 Modbus/TCP requests for station 35 The requests will be passed to COM 3 (35/10 = 3.5)

#### Example 2:

Stations per COM port = 20 Modbus/TCP requests for station 35 The request will be passed to COM 1 (35/20 = 1.75)

#### Adjust the COM port settings



#### **Operation Mode** (Default = Console mode):

ET-6000 COM ports can be configured as follows:

#### 1. VxComm (Virtual COM) (unavailable):

Enable VxComm. Remote application program can use Virtual COM (need to install the VxComm Driver) or connect to TCP/IP port 10000 + n to access the COM port via Ethernet. At VxComm mode, the COM port has access to any serial device.

#### 2. Modbus/RTU:

Enable the protocol converter function to convert from Modbus/TCP to Modbus/RTU. In Modbus/RTU mode, the COM Port can only has access Modbus/RTU slave devices.

#### 3. System Reserved

#### 4. UpLink

Enable the COM Port to as a Modbus/RTU slave port.

#### 5. Debug port:

The Modbus kernel prints out some messages, while communicating with Modbus clients or masters.

The messages include:

- (0) Receives a Modbus request response from Modbus client or master.
- (1) By passes Modbus request to COM Port
- (2) Send Modbus request to COM Port
- (3) Check Modbus response from COM Port
- (4) Send Modbus response to Modbus client or masters

#### 6. Console:

The function disables the communication capabilities of the COM port. It's a serial console port that allows configuration to be performed via the RS232 Port. The commands related to the **serial** console are the same as the **Telnet** console.

#### Modbus/RTU Data format

There are several kinds of data formats used in the Modbus/RTU protocol that must be changed to suit the specific Modbus/RTU devices that are connected to the COM Port.

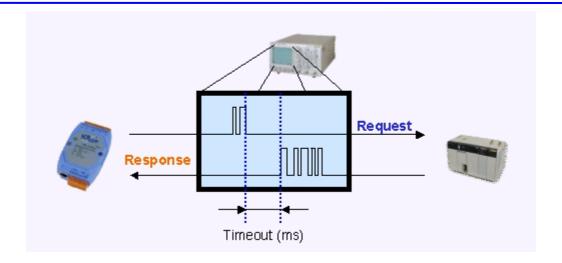
- 8 data bits, none parity, 1 stop bits
- 8 data bits, none parity, 2 stop bits
- 8 data bits, odd parity, 1stop bits
- 8 data bits, even parity, 1stop bits (Default)

Note: When an ET-6000 module receives a Modbus/TCP request that not addressed to its internal registers, it first decides which COM Port to send the request. Modbus/RTU must be enabled for this COM Port, otherwise the request will be discarded.

Timeout (Default = 200 milliseconds)

After completing transmission of any data, the system begins to count time. If the timeout expires, the system will stop receiving responses.







# **Appendix D: MODBUS Register Tables**

Modules Supported (ET-6000 series)						
Name	Date	Firmware	Note			
ET-6052 (D)	1-Dec-2006	V1.00	8 DO, 14 DI			
ET6060 (D)	1- Dec -2006	V1.00	8 DO, 10 DI 8 Relay Output (Form A), 10 DI			
ET2-6064 (D)	1- Dec -2006	V1.00	24 DO 18 Relay Output (Form A), 6 Relay Output (Form C)			

Note: for DO and DI, a register is one byte; while AO and AI, a register is two byte.

# Appendix D: Modbus Register

#### **Common Functions for all ET-6000 series modules**

(0xxxx) D0	(0xxxx) DO address						
Begin address	Points	Description	Registers per Point	Range	Access Type		
226	1	Recover all I/O default settings	1	1=recover	W (Pulse)		
227	1	Recover all web default settings (*)	1	1=recover	W (Pulse)		
228	1	ID default settings (*)	1	1=recover	W (Pulse)		
229	1	Web Enable/Disable	1	1=recover	W (Pulse)		
233	1	Reboot ET-6000	1	1=reboot	W (Pulse)		

<sup>(\*)</sup> Not yet implemented for security reason.

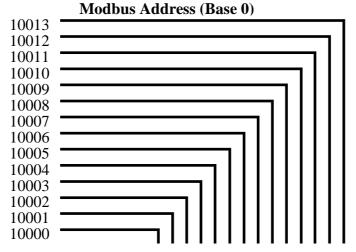
(3xxxx) Al address							
Begin address	Points	Description	Registers per Point	Range	Access Type		
350	1	OS image version	1	123 means version=1.2.3	R		
351	1	Total Firmware version	1	123 means version=1.2.3	R		
358	1	Modbus communication status	1	0= No Error -1= CRC error -2= Timeout	R		
360	1	Pair Connection	1	0=Normal 1=Timeout 2=Disconnected	R		



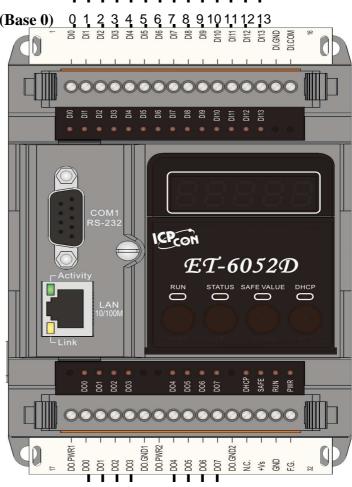
(4xxxx) A	(4xxxx) AO address						
Begin address	Points	Description	Registers per Point	Range	Access Type		
555	1	CPU reset status	1	1= by power on 2= by 0.8 second WDT 3= by Reset command	R/W		
556	1	CPU reset events	1	How many CPU reset events has happened? When CPU is reset by one of the situations described in register 555, the event increases one count.	R/W/E		
557	1	Set host watch dog timer	1	<5: Disabled 5~65535: Enabled (unit: second) (default=0) When ET-6000 loses communication with PC more than the WDT setting, DO and AO go to their safe values and host WDT events plus 1 count.	R/W/E		
558	1	Host WDT events	1	How many host WDT events has happened after CPU reset?	R/W		
559	1	Module name	4	8 ASCII characters	R		
563	1	Module nick name	8	16 ASCII characters	R/W/E		

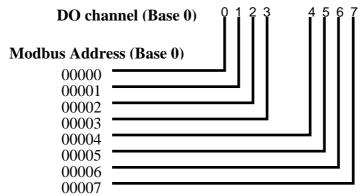
#### ET-6052 (D)

**I/O Address Mapping** 



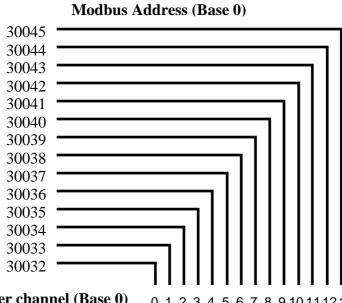
DI channel(Base 0)

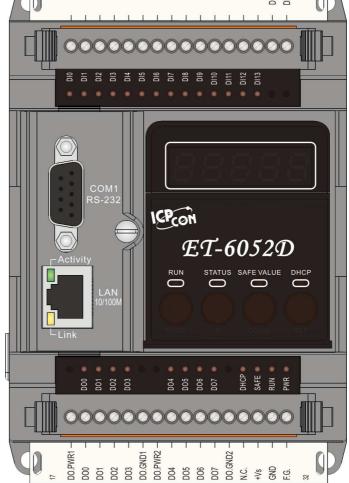




ET-6000 User's Manual, 2007, Sep., V1.1, 6PH-002-11-----163<sup>1</sup>

#### ET-6052 (D) Counter Address Mapping







# Appendix D: Modbus Register

## **Detailed Modbus Address Table for ET-6052 (D)**

(0xxxx) Do	0xxxx) DO address						
Begin address	Points	Description	Registers per Point	Range	Access Type		
0	0~7	Digital Output	1	0=off 1=on	R/W		
80	1	Clear all DI latched status (high)	1	1=clear	W (Pulse)		
81	1	Clear all DI latched status (low)	1	1=clear	W (Pulse)		
82	0~13	Clear low speed (100Hz) digital counter	1	1=clear	W (Pulse)		
350	1	Enable all DI latched status (high/low)	1	0=disable 1=enable (default=0)	R/W/E		
351	0~13	Enable low speed (100Hz) digital counter	1	0=disable 1=enable (default=0)	R/W/E		
431	1	Write DO Power on value to EEPROM	1	1=write	W (Pulse)		
432	1	Write DO Safe value to EEPROM	1	1=write	W (Pulse)		
435	0~7	Power on value for DO	1	0=off 1=on (default=0)	R/W/E		
515	0~7	Safe value for DO	1	0=off 1=on (default=0)	R/W/E		

(1xxxx) DI address							
Begin address	Points	Description	Registers per Point	Range	Access Type		
0	0~13	Digital Input	1	0=off 1=on	R		
80	0~13	Digital latched status (high)	1	0=no 1=latched	R		
160	0~13	Digital latched status (low)	1	0=no 1=latched	R		



# Appendix D: Modbus Register

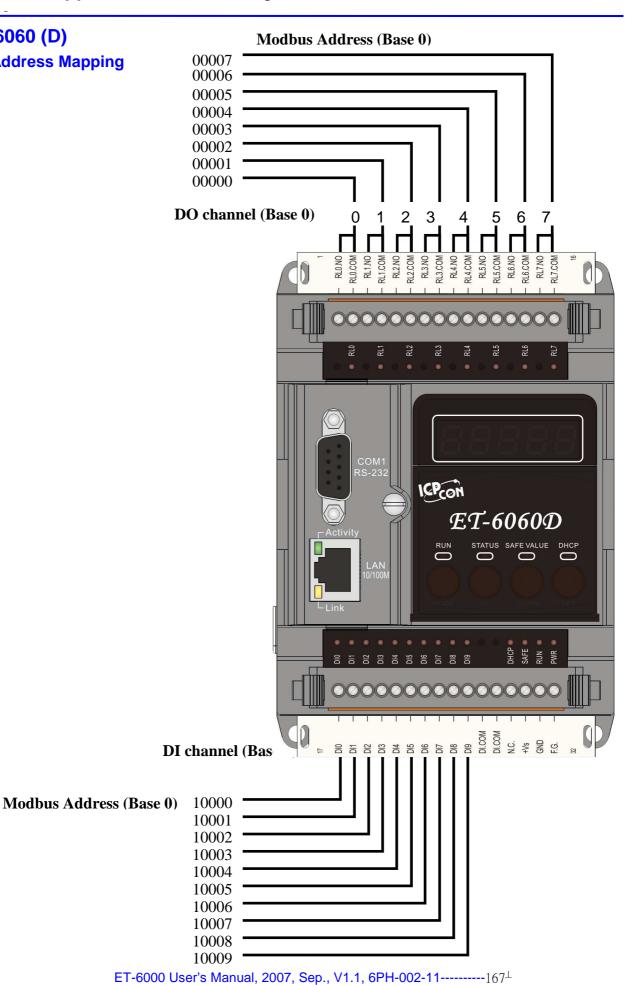
(3xxxx) A	(3xxxx) Al address							
Begin address	Points	Description	Registers per Point	Range	Access Type			
32		Low speed (100Hz) digital counter	1	0~65535	R			

(3xxxx) AI	(3xxxx) Al address (Static Channel Number Value)							
Begin address	Points	Description	Registers per Point	Value	Access Type			
300	1	DI (channel number)	1	14	R			
301	1	DI high/low latch (channel number)	1	14	R			
310	1	DO (channel number)	1	8	R			
311	1	Power on value for DO (channel number)	1	8	R			
312	1	Safe value for DO (channel number)	1	8	R			
321	1	Low speed counter (100Hz) (channel number)	1	14	R			

(4xxxx) AC	(4xxxx) AO address							
Begin address	Points	Description	Registers per Point	Range	Access Type			
200		Preset value for low speed (100Hz) digital counter	1	0~65535(default=0)	R/W/E			

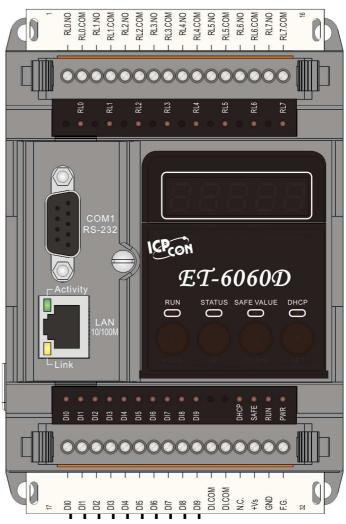
ET-6060 (D)

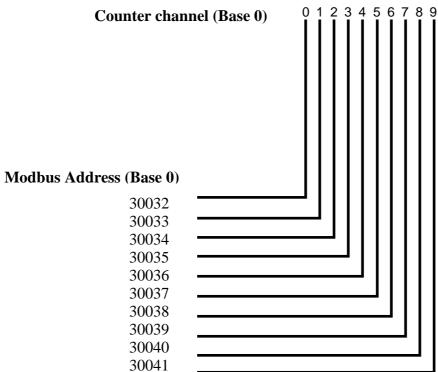
I/O Address Mapping





#### ET-6060 (D) Counter Address Mapping







# Appendix D: Modbus Register

## **Detailed Modbus Address Table for ET-6060 (D)**

(0xxxx) Do	(0xxxx) DO address						
Begin address	Points	Description	Registers per Point	Range	Access Type		
0	0~7	Digital Output	1	0=off 1=on	R/W		
80	1	Clear all DI latched status (high)	1	1=clear	W (Pulse)		
81	1	Clear all DI latched status (low)	1	1=clear	W (Pulse)		
82	0~9	Clear low speed (100Hz) digital counter	1	1=clear	W (Pulse)		
350	1	Enable all DI latched status (high/low)	1	0=disable 1=enable (default=0)	R/W/E		
351	0~9	Enable low speed (100Hz) digital counter	1	0=disable 1=enable (default=0)	R/W/E		
431	1	Write DO Power on value to EEPROM	1	1=write	W (Pulse)		
432	1	Write DO Safe value to EEPROM	1	1=write	W (Pulse)		
435	0~7	Power on value for DO	1	0=off 1=on (default=0)	R/W/E		
515	0~7	Safe value for DO	1	0=off 1=on (default=0)	R/W/E		

(1xxxx) DI address							
Begin address	Points	Description	Registers per Point	Range	Access Type		
0	0~9	Digital Input	1	0=off 1=on	R		
80	0~9	Digital latched status (high)	1	0=no 1=latched	R		
160	0~9	Digital latched status (low)	1	0=no 1=latched	R		



# Appendix D: Modbus Register

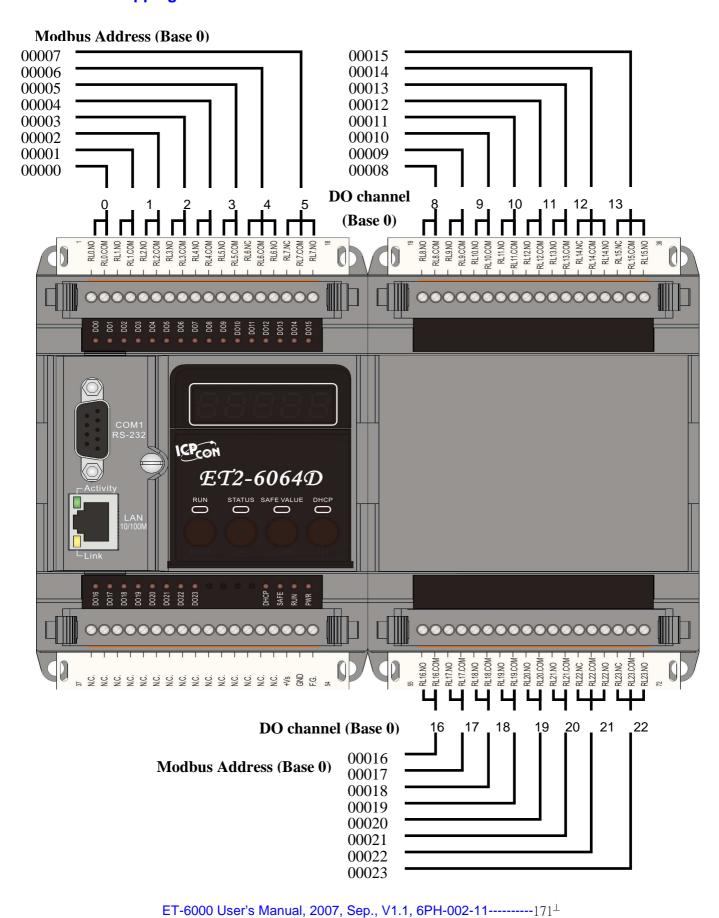
(3xxxx) Al	(3xxxx) Al address							
Begin address	Points	Description	Registers per Point	Range	Access Type			
32		Low speed (100Hz) digital counter	1	0~65535	R			

(3xxxx) AI	(3xxxx) Al address (Static Channel Number Value)						
Begin address	Points	Description	Registers per Point	Value	Access Type		
300	1	DI (channel number)	1	10	R		
301	1	DI high/low latch (channel number)	1	10	R		
310	1	DO (channel number)	1	8	R		
311	1	Power on value for DO (channel number)	1	8	R		
312	1	Safe value for DO (channel number)	1	8	R		
321	1	Low speed counter (100Hz) (channel number)	1	10	R		

(4xxxx) AO address						
Begin address	Points	Description	Registers per Point	Range	Access Type	
200		Preset value for low speed (100Hz) digital counter	1	0~65535(default=0)	R/W/E	

#### ET2-6064 (D)

#### I/O Address Mapping





# Appendix D: Modbus Register

**Detailed Modbus Address Table for ET2-6064 (D)** 

(0xxxx) Do	(0xxxx) DO address						
Begin address	Points	Description	Registers per Point	Range	Access Type		
0	0~23	Digital Output	1	0=off 1=on	R/W		
431	1	Write DO Power on value to EEPROM	1	1=write	W (Pulse)		
432	1	Write DO Safe value to EEPROM	1	1=write	W (Pulse)		
435	0~23	Power on value for DO	1	0=off 1=on (default=0)	R/W/E		
515	0~23	Safe value for DO	1	0=off 1=on (default=0)	R/W/E		

(3xxxx) Al address (Static Channel Number Value)						
Begin address	Points	Description	Registers per Point	Value	Access Type	
310	1	DO (channel number)	1	24	R	
311		Power on value for DO (channel number)	1	24	R	
312		Safe value for DO (channel number)	1	24	R	



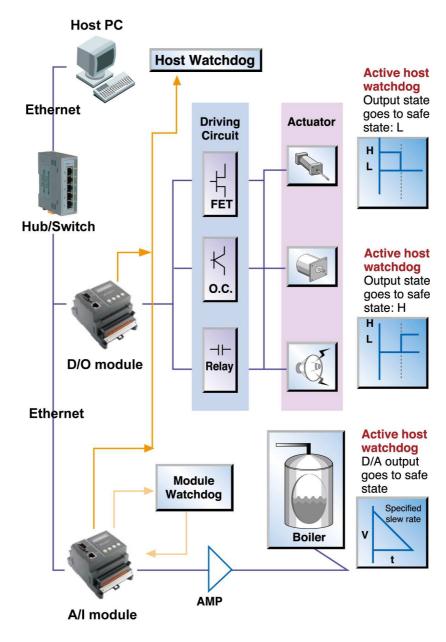
# **Appendix E: Modbus Application Notes**

#### **Dual Watchdog**

Dual Watchdog consists of **Module Watchdog** and **Host Watchdog**.

The **Module Watchdog** is a built-in hardware circuit that will reset the CPU module if a failure occurs in either the hardware or the software. If the application does not refresh the watchdog timer within 0.8 seconds, the watchdog circuit will initiate a reset of the CPU.

The **Host Watchdog** is a software function that can be used to monitor the operating status of the host. Its purpose is to prevent network communication problems or a host failure. If the Watchdog timeout interval expires, the module will return all outputs to a predefined Safe value (Refer to the **Safe Value** application note), which can prevent the controlled target from unexpected situation.





AO address **40557** of the ET-6000 series Modbus register is the address of the **Host Watchdog** timer, and will be stored into EEPROM. The WDT function will be disabled if the value is set to less then **5** seconds.

#### **Power ON Value**

If the ET-6000 series module is reset, the output of the module is set to the predefined Power ON Value for the DO and AO channels.

DO address **00435** of the ET-6000 series Modbus register is the first address of the Power ON value, and the total number of channels depend on the type of module.

For example:

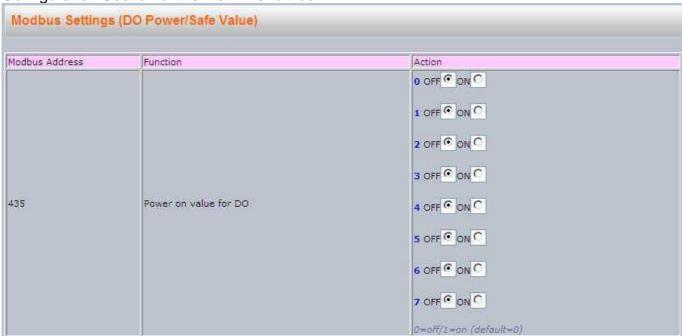
Addresses **00435** to **00442** records the Power ON value for the 8-Channel ET-6060.

Be careful to set the ON value to DO address **00431** to write the DO Power ON value to the EEPROM of the ET-6000 DO module after using Modbus commands (05 or 15) to change the Power ON value.

Set the ON value to DO address, **00433** to write the AO Power ON value to the EEPROM of the ET-6000 AO module after using the Modbus commands (06 or 16) to change the Power ON value.

#### Configuration via Web page

Browse to the homepage of the ET-6000, and click the "Modbus I/O Settings" link in the Configuration Section of the Main Menu tree.



Click the ON/OFF radio box to set the power ON/OFF value and then click the button to enable the settings to take effect.



#### Safe Value

If the time of the Host PC losing Modbus/TCP communication with the module is greater than the host WatchDog timer setting (called WDT timeout), the output of the Digital and Analog channels is set to the Safe Value, and the count of the host WDT events is increased by one.

AO address **40558** is the address of the Host WDT events. The value of the WDT events will be not stored into EEPROM, and will return to 0 after the module is rebooted.

DO address **00515** is the first address of the Safe value and the total number of channels depends on the type of module.

For example:

Address **00515** to **00522** records the Safe value for the 8-Channel ET-6060.

Be careful to set the ON value to DO address **00432** to write the DO Safe value to the EEPROM of the ET-6000 DO module after using Modbus commands (05 or 15) to change the Power ON value.

Set the ON value to DO address **00434** to write the AO Safe value to the EEPROM of the ET-6000 AO module after using Modbus commands (06 or 16) to change the Power ON value.

While the WDT timeout is set, the module can also receive the Modbus/TCP commands (05, 06, 15 and 16) to change the DO or AO value without needing to clear the host watchdog timeout value.

#### Configuration via the Web page

Browse to the homepage of the ET-6000, and click the "Modbus I/O Settings" link in the Configuration Section of the Main Menu tree.





Click the ON/OFF radio box to set the Safe value and then click the Submit button to enable the settings to take effect.

#### View the Power ON/Safe Value via the Web page

Click the "Web HMI" link in the Web HMI Section of the Main Menu tree.



## **Digital Input High/Low Latch**

DI Latch Function	Enable Latch	Clear ALL Latch (High)	Clear ALL Latch (Low)	Latch Status (High)	Latch Status (Low)	
Address	00350	00080	00081	10080~1XXXX	10160~1XXXX	
WWW B I II ( CET 0000 ' III						

**XXXX:** Depends on the type of ET-6000 series module

For example: The user connects a key switch to the digital input channel of a digital input module and wants to read the keystrokes. The key input is a pulse digital input signal, and the user will miss the stroke. When reading the DI status for DI address **10000** by Modbus

command 02 in A and B position, the response will be that no keystroke has been made and the keystroke information will be lost. In contrast, reading the latched low digital input at DI address **10160** using Modbus command 02 will solve this problem. When issuing 02 command in A and B position, the response denotes that there has been a low pulse between the A and B position indicating a keystroke.

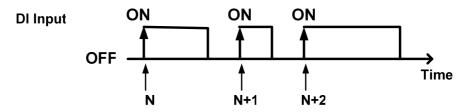
#### Configuration via the Web page



## **Digital Input Counter**

Low Speed Counter: 100Hz Valid Range: 0~65535 counters

DI status is changed from OFF to ON (rising edge).



Address	00351~0XXXX	00082~0XXXX	30032~3XXXX	40200~4XXXX
DI Counter Functions	Enable Counter	Clear Counter	Counter Value	Preset value for Counter

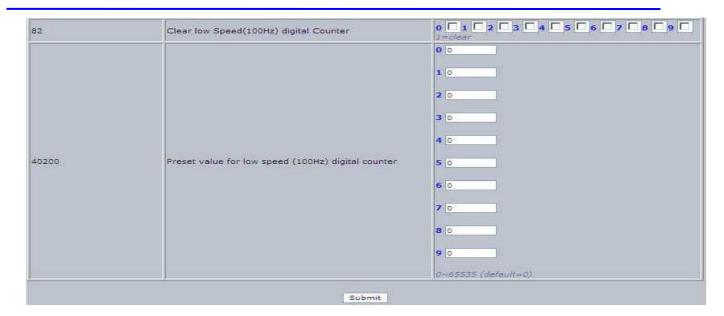
XXXX: Depends on the type of ET-6000 series module

Be careful to set the ON value to DO address **00630** to save the Preset value for the DI counter to the EEPROM of the ET-6000 DI module after using Modbus commands (06 or 16) to change the Preset value.

#### Configuration via the Web page







#### View the DI Counter and Latch status via the Web page

Click the "Web HMI" link in the Web HMI Section of the Main Menu tree.

5	Stop					
No	Register	Action	Counter&Clear	High Latch	Low Latch	1
	0	OFF	0	OFF	OFF	-
DI0 DI1	1	OFF	0	OFF	OFF	
DI2 DI3 DI4	2	OFF	0	OFF	OFF	
DI3	3	OFF	0	OFF	OFF	
DI4	4	OFF	0	OFF	OFF	- L
The State of the S		Total State Control of the Control o	4 - 10 - 10	The state of the s	TOTAL CO.	-

The DI Counter value is shown in each field of the "Counter & Clear" column, and the can be cleared by clicking the button on the page.

On clicking the button, the counter value will return to 0, such as (As long as a preset value for the DI Counter in't set).

If the preset value for the DI Counter is set to 2, when the button is clicked and the counter value will return to the preset value, such as  $\longrightarrow$  2.

The DI latch status is shown in each field of the "High Latch/Low Latch" column.

The entire of DI/DI Counter/Latch status data on this page will be updated automatically for a period time.



#### Is Your Web Browser Java Enabled?

Link to the URLs below to check whether the Java is available on the Web Browser.

- 1. http://www.javatester.org/enabled
- 2. http://www.java.com/en/download/help/testvm.xml

If Java is installed, but not enabled, Sun has instructions to enable the JRE through your Web browser

(http://www.java.com/en/download/help/enable\_browser.xml) and to Enable the JRE through the "Java?Plug-in Control Panel".

(http://www.java.com/en/download/help/enable\_panel.xml)

# Online Download and Installation for the JRE (Java Runtime Environment)- An Example for Windows XP platform

#### Download and Install

- 1. Go to Java.com
- 2. Click on the Java Software Download button.
- 3. Start the installation process:
  - a. Installing JRE on Windows XP with Service Pack 2 (SP2) using Internet Explorer

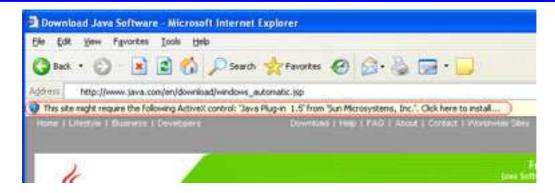
If you are using Internet Explorer on Windows XP with Service Pack 2 (SP2), you need to complete these steps:

1. An Information Bar dialog box pops up displaying this message:



2. Click **OK**. A toolbar displays this message:





3. Click on the toolbar and choose: Install ActiveX Control....



A Security Warning dialog box appears.



- 4. Click Install to start the installation process.
- 4. The download process starts. During the download, a progress window lets you know the estimated time remaining for the download to finish. The download can take anywhere from a few seconds on a fast Internet connection to half an hour or more on a very slow connection. Once the download is over the installation process will start automatically.



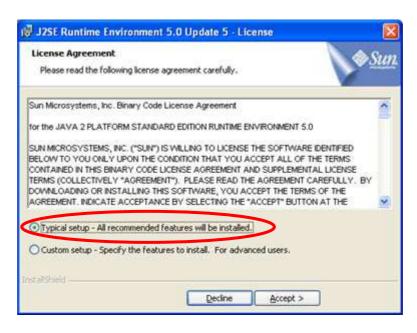


#### 5. The JRE installation starts:

The installer "unpacks" the files needed to continue. A dialog box tracks this process, which takes less than a minute. After briefly displaying a Java logo splash screen, the installer presents the license agreement.

The installer displays a **Setup Type** screen that allows you to choose either a typical or custom setup. We recommend that you choose the **Typical** option (the default selection) unless you are an advanced user who wants more precise control over the components that will be installed.

After ensuring that the **Typical** setup is selected, click the **Next** button to continue with the installation.

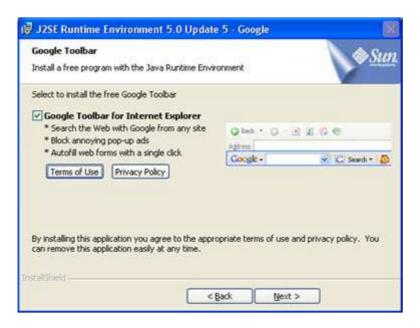


The **Java Runtime Environment 5.0 Update 5 – Google Programs** dialog box will appear. By default **Google Toolbar for Internet Explorer** is checked. Click **Next** button. This will start installing selected programs features including the JRE on your system.

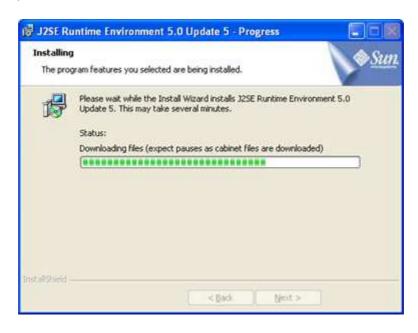
Note: You can choose to install or ignore this useful additional program by checking or



unchecking the check box.



Now that you have given the installer all of the information it needs to proceed, progress boxes track the installation process.



A few brief dialogs confirm the last steps of the installation process, and a concluding message appears with the confirmation "Installation Completed OK."

#### **Enable and Configure**

Once the installation is complete, ensure that the JRE is enabled and configured properly for applets and applications. For instructions to enable the JRE for the browser, such as Internet Explorer, Mozilla, or Netscape, go to:

Enable Java Runtime Environment 5.0 through the Control Panel (http://java.com/en/download/help/5000020200.xml)



Enable Java Runtime Environment 5.0 through your Web browser (http://java.com/en/download/help/5000020500.xml)

Configuring proxy settings for Java Runtime Environment 5.0 (http://java.com/en/download/help/5000020600.xml)

#### **Test Installation**

To test that the JRE is installed, enabled and working properly on your computer, run this test applet from our web site:

Test your Java Runtime Environment (http://java.com/en/download/installed.jsp)



# **Appendix G: Frame Ground**

Electronic circuits are constantly vulnerable to Electro-Static Discharge (ESD), which become worse in a continental climate area. ET-6000 series modules feature a new design for the frame ground, which provides a path for bypassing ESD, allowing enhanced static protection (ESD) capability and ensures that the module is more reliable.

The following options will provide a better protection for the module:

The ET-6000 controller has a metallic board attached to the back of the plastic basket as shown in the Figure F-1 below. When mounted to the DIN rail, connect the DIN rail to the earth ground because the DIN rail is in contact with the upper frame ground as shown in the Figure F-2 below.

# Frame Ground

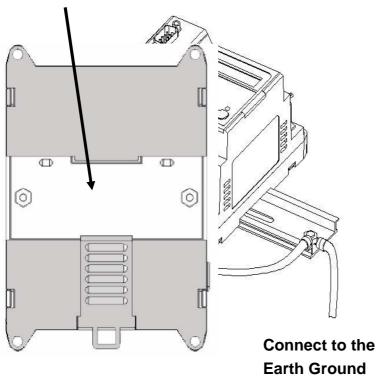


Figure F-1 Figure F-2



# **Appendix H: Technical Support**

Should you encounter problems while using your ET-6000 series module, and are unable to find the help you need in this manual or on our website, please contact ICP DAS Product Support.

Email: service@icpdas.com

Website: http://www.icpdas.com/service/support.htm

When requesting technical support, be prepared to provide the following information about your system:

- 1 1. Module name and serial number: The serial number can be found printed on the barcode label attached to the cover of the module.
- 2 2. Firmware and OS version: See **Section 3.1 Overview** for information regarding the command used to identify the firmware/OS version.
- 3 3. Host configuration: Host type and operating system (if needed).
- 4. If the problem is reproducible, please give full details describing the procedure used to reproduce the problem.
- 5. Specific error messages displayed. If a dialog box with an error message is displayed, please include the full text of the dialog box, including the text in the title bar.
- 6 6. If the problem involves other programs or hardware devices, please describe the details of the problem in full.
- 7. Any comments and suggestions related to the problem are welcome.

ICP DAS will reply to your request by email within three business days.