

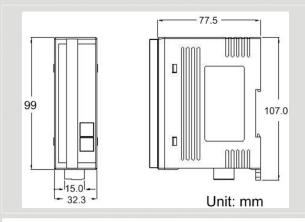
CANopen Series Products

PWM module of CANopen Slave





CAN-2088C



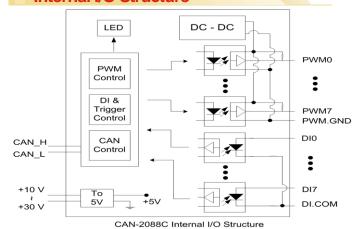
Dimensions

PWM (Pulse width modulation) is a powerful technique for controlling analog circuits. By using digital outputs, it can generate a waveform with variant duty cycle and frequency to control analog circuits. CAN-2088C, a CAN bus remote I/O modules with CANopen protocol, provides 8 PWM output channels and 8 digital inputs channels with high-speed counter function. It can be used to develop practical and economical analog control systems in the CANopen network.

Features

- Hardware-controlled PWM output
- PWM output frequency: 0.2 Hz ~ 500 kHz with 0.1%~99.9% duty cycle
- PWM Output Modes: software trigger / hardware trigger
- Trigger each PWM output individually or all PWM outputs synchronously
- Support Burst output mode and Continue output mode
- Provide 32-bit 500 kHz high-speed counter for each DI channel
- Pass the validation of CANopen conformance test
- Provide EDS file for CANopen master interface

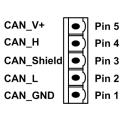
Internal I/O Structure



I/O Pin & Wire Connection

Terminal No. Pin Assignment	Output Type	ON State LED ON Readback as 1	OFF State LED OFF Readback as 0
01 PO.0	Drive Relay	Relay On	Relay Off
02 PO.1			
03 PO.2		—————————————————————————————————————	PO X PO X
04 PO.3		PO.GND	
05 PO.4			
06 PO.5	Resistance Load	†## FECTION	tax rollnox
07 PO.6	Load	PO X PO.GND	PO X PO.GND
08 PO.7			V
09 PO.GND	Input Type	ON State LED ON Readback as 1	OFF State LED OFF Readback as 0
10 PO.GND	Relay Contact	Relay On	Relay Off
[11 DI.0		+ <u>+</u> D) X	+ _± □⊖ DIX
[12 DI.1		Relay Close DI.GND	Relay Open DI.GND
∬ □ 13 DI.2	TTL/CMOS Logic	Voltage > 10 V	Voltage < 4 V
14 DI.3		Logic Power C Logic Level Low DI X DI GND	Logic Power Color
[15 DI.4		[-0]]	Open Collector Off
[o 16 DI.5	NPN Output	Open Collector On	- +
[17 DI.6		□ DI X DI.GND	□ DIX DI.GND
[18 DI.7	PNP Output	Open Collector On	Open Collector Off
19 DI.GND		DIX D⊟ DIX	off the transfer of the trans
20 DI.GND		DI.GND	DI.GND DI.GND

CAN Pin & Baud Rate Rotary





Switch Value	Baud Rate	
0	10 kbps	
1	20 kbps	
2	50 kbps	
3	125 kbps	
4	250 kbps	
5	500 kbps	
6	800 kbps	
7	1000 kbps	

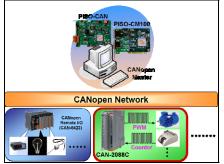


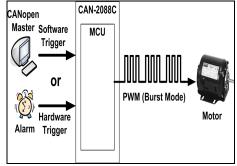


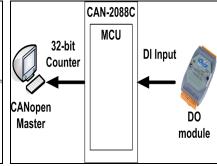
Hardware Specifications

CAN Interface			
Connector	5-pin screwed terminal block (CAN_GND, CAN_L, CAN_SHLD, CAN_H, CAN_V+)		
Baud Rate (bps)	10 k, 20 k, 50 k, 125 k, 250 k, 500 k, 800 k, 1M		
Terminator Resistor	Switch for 120 Ω terminator resistor		
Node ID	1~99 selected by rotary switch		
Protocol	CANopen DS-301 ver4.02, DS-401 ver2.1		
No. of PDOs	10 Rx, 10 Tx (support dynamic PDO)		
PDO Mode	Event Triggered, Remotely requested, Cyclic and acyclic SYNC		
Error Control	Node Guarding protocol and Heartbeat Producer protocol		
Emergency Message	Yes		
PWM Interface			
Channels	8 (Source)		
Output Max. Load Current	1 mA		
Frequency Range	$0.2~Hz \sim 500~kHz$ (non-continuous, the min. unit of the high/low level signal is 1 us)		
PWM Mode	Continue mode, Burst mode, Hardware trigger mode, Software trigger mode		
ESD Protection	4 kV Contact for each channel		
DI Interface			
Channels	8 (Sink)		
Counter Frequency	32-bit, 500 kHz Max.		
ESD Protection	4 kV Contact for each channel		
LED			
Round LED	PWR LED, RUN LED, ERR LED		
I/O LED	8 LEDs as PWM, 8 LEDs as Digital Input, and 1 LED as terminal resister indicator		
Power			
Input range	Unregulated $+10 \sim +30 \text{ V}_{DC}$		
Power Consumption	3.5 W		
Mechanism			
Installation	DIN-Rail		
Dimensions	32.3 mm x 99 mm x 77.5 mm (W x L x H)		
Environment			
Operating Temp.	-25 ~ +75 °C		
Storage Temp.	-30 ~ +80 °C		
Humidity	10 ~ 90% RH, non-condensing		

Applications







Ordering Information

CAN-2088C CANopen Module of 8-channel PWM and 8-channel DI with High-speed Counters